



Characterizing the hydrodynamic response to the initial conditions

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Abstract

In hydrodynamics, the momentum distribution of particles at the end of the evolution is completely determined by initial conditions. We study quantitatively to what extent anisotropic flow v_n is determined by predictors such as the initial eccentricity ε_n in a set of realistic simulations, and we also show the importance of nonlinear terms in order to correctly predict v_4 . This knowledge will be important for making a more direct link between experimental observables and hydrodynamic initial conditions, the latter being poorly constrained at present.

1. Introduction

One of the most important probes of ultrarelativistic heavy-ion collisions is the anisotropic flow. Event-by-event hydrodynamics [1] provides a natural way of studying anisotropic flow and its fluctuations. In such calculations, one supplies a set of initial conditions (IC), evolves them through ideal or viscous hydrodynamics, and finally computes particle emission at the end. One can then write the azimuthal distribution of outgoing particles in a hydrodynamic event as a Fourier series

$$\frac{2\pi}{N} \frac{dN}{d\phi} = 1 + 2 \sum_n^\infty v_n \cos[n(\phi - \Psi_n)], \quad (1)$$

or equivalently $\{e^{in\phi}\} = v_n e^{-in\Psi_n}$, where $\{\dots\}$ is the average in one event. Since the largest source of uncertainty in these calculations is the initial conditions, it is useful to identify which properties of the initial state determine each observable. This knowledge can then allow to constrain the initial state directly from data.

It is well known that the initial average profile of non-central collisions is almond-shaped. One can obtain the eccentricity and the direction of the initial profile computing $\varepsilon_2 e^{i2\Phi_2} = -\{r^2 e^{i2\phi}\} / \{r^2\}$ in the CM frame, where ε_2 is the participant eccentricity, Φ_2 is the participant plane, whose direction is the minor axis of the ellipse, and $\{\dots\}$ denotes an average over the initial density profile. The hydrodynamic expansion produces an elliptic distribution of particles, i.e. $\varepsilon_2 \propto v_2$, and the maximum of the distribution of particles is aligned with the direction of the steepest energy gradient in the IC, i.e $\Phi_2 = \Psi_2$. Nevertheless, due to the finite number of nucleons colliding in each nucleus-nucleus collisions, there are fluctuations in the initial profile, thus the relations $v_2 \propto \varepsilon_2$ and $\Psi_2 = \Phi_2$ may no longer be valid in event-by-event hydrodynamics. However, the study of these relations for several models of IC in event-by-event hydrodynamics, showed that they are reasonably satisfied [2, 3, 4, 5].

Symmetry considerations have been used to argue that higher-order flows (v_n with $n \geq 3$) should also be created by an anisotropy, ε_n . It has been shown that this is also true for $n = 3$, but it is not valid for $n = 4, 5$ [4, 5]. Nevertheless, Teaney and Yan [6] have introduced a cumulant expansion in the initial density profile, in which ε_n is only the first term in an infinite series, and they have suggested that the hydrodynamic response may be improved by adding higher-order or nonlinear terms.

In order to understand which properties of the initial state determine v_n and Ψ_n , we propose a simple quantitative measure of the correlation between (v_n, Ψ_n) and any proposed predictor, such as (ε_n, Φ_n) . We then use this to find better estimators for the anisotropic flows. Details can be found in [7].

2. Characterizing the hydrodynamic response

In previous works [3, 4, 5], the correlation of the anisotropic flow with the initial geometry has been studied by visually inspecting two types of plots representing separately magnitude and direction: the $\Psi_n - \Phi_n$ distribution, and a scatter plot of v_n versus ε_n . Instead, we carry out a global analysis, studying the correlation between the entire vector both simultaneously and quantitatively. For a given event in a centrality class, we write

$$v_n e^{in\Psi_n} = k \varepsilon_n e^{in\Phi_n} + \mathcal{E}, \quad (2)$$

where k is a proportionality constant, and \mathcal{E} is the difference between the calculated flow and the proposed estimator, or the error in the estimate. The generalized eccentricity ε_n , used throughout this work, is: $\varepsilon_n e^{in\Phi_n} = -\{r^n e^{in\phi}\} / \{r^n\}$, which was proposed in Ref. [3], and later showed to be the lowest term in a cumulant expansion of the initial energy density [6]. The best estimator is defined as the one that minimizes the mean square error $\langle|\mathcal{E}^2|\rangle$, where $\langle \cdots \rangle$ is the average over events in a centrality class. Thus, the best linear fit is achieved when

$$k = \frac{\langle \varepsilon_n v_n \cos[n(\Psi_n - \Phi_n)] \rangle}{\langle \varepsilon_n^2 \rangle}. \quad (3)$$

We define the quality of the estimator by

$$Quality = k \frac{\sqrt{\langle \varepsilon_n^2 \rangle}}{\sqrt{\langle v_n^2 \rangle}}. \quad (4)$$

The closer *Quality* to 1, the better the response and the smaller the rms error $\langle|\mathcal{E}^2|\rangle$. Note that a negative *Quality* means that Ψ_n and Φ_n are anticorrelated.

We now present results for Au-Au collisions at the top RHIC energy using the hydrodynamic code NeXSPheRIO [1]. NeXSPheRIO evolves initial conditions generated by the event generator NeXus, solves the equations of relativistic ideal hydrodynamics, then emits particles at the end of hydrodynamical evolution using a Monte-Carlo generator. For this work, we generated 150 events in each of the 10% centrality classes, and we added 115 events in an extra class for events with zero impact parameter - particles from the pseudorapidity interval $|\eta| < 1$ were used. Eccentricities are obtained by averaging over the initial transverse energy density profile at $z=0$. Our hydrodynamical calculations contain fluctuating initial flow, as well as longitudinal fluctuations, thus the final flow measured is not entirely determined by the initial transverse geometry. In this sense, these results represent something of a worst-case scenario.

Fig. 1 displays the *Quality* of the hydrodynamic response for elliptic and triangular flow as a function of centrality. As expected, the elliptic flow is driven to the almond-shaped overlap area for non-central collisions, where Ψ_2 is approximately coincident with Φ_2 . Even for central collisions, where v_2 comes from fluctuations, the best estimator given by Eq. (2) is able to capture the physics of the elliptic flow fluctuations. The *Quality* for $n = 3$ is not as close to 1 as for the elliptic case, but one can see that the triangularity ε_3 is still a good estimator of the triangular flow. We have also tested the triangularity definition proposed by Roland and Alver [8] (not shown, see Ref. [7]), where r^3 is replaced by r^2 in Eq. (2). The triangularity with r^3 weight is a better predictor than with r^2 for most centralities. Since the r^3 weight gives more weight to outer shells of the initial energy profile, this means that the source of anisotropic flow moves inward as the collision becomes more peripheral.

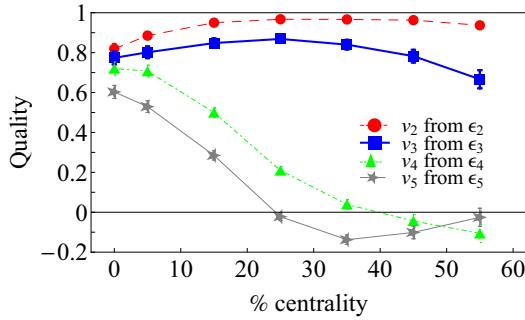


Figure 1: *Quality* of the hydrodynamic response for elliptic (circle), triangular (square), quadrangular (triangle) and pentagonal flow (star) for different centrality bins. The leftmost points correspond to events with zero impact parameter.

The estimators for $n = 4, 5$ differ qualitatively from our results for v_2 and v_3 , where ε_4 and ε_5 only give reasonable predictions for central collisions. Moving to peripheral collisions the *Quality* decreases and even become negative. This shows that ε_n alone cannot be used to map the hydrodynamics response to the initial geometry for $n = 4, 5$.

3. Finding better estimators

One can hope to improve the estimator adding more terms in Eq. (2), e.g.

$$v_n e^{in\Psi_n} = k \varepsilon_n e^{in\Phi_n} + k' \varepsilon'_n e^{in\Phi'_n} + \mathcal{E}, \quad (5)$$

where ε'_n and Φ'_n are other quantities determined from the initial density profile (for instance, the next higher cumulant). The procedure to obtain the better estimator is similar: minimize the mean-square error $\langle |\mathcal{E}^2| \rangle$ with respect to k and k' , take the average over events in each centrality class, then insert the values of k and k' in Eq. (5) and compute

$$\text{Quality} = \frac{\langle |k \varepsilon_n e^{in\Phi_n} + k' \varepsilon'_n e^{in\Phi'_n}|^2 \rangle}{\langle v_n^2 \rangle}. \quad (6)$$

One can show that the quality is higher than with just one term, Eq. (4).

We want to apply the improved estimator to the quadrangular flow (for other flows see Ref. [7]), but we need to know which are ε'_n and Φ'_n . Taking an elliptic initial condition, i.e an elliptic profile with only $\varepsilon_2 \neq 0$, then evolving it through ideal hydrodynamics, and computing the

particle emission, one will obtain, using Eq. (1), the anisotropic flows and the event-plane angles. Since there is only $\varepsilon_2 \neq 0$ one should expect only $v_2 \neq 0$. The results for this initial condition are: $v_2 \neq 0$ as a response to ε_2 and $\Psi_2 = \Phi_2$, $v_n = 0$ when n odd (by symmetry), but there is a quadrangular flow, $v_4 \neq 0$, and Ψ_4 is aligned with Φ_2 . Since there is no ε_4 , so where does v_4 come from? The answer is, v_4 is induced by the almond shape.

As quadrangular flow can also come from ε_2 , we want to investigate, first, v_4 solely as a response to the almond shape. Thus, the natural estimator is $v_4 e^{i4\Psi_4} = k(\varepsilon_2 e^{i2\Phi_2})^2 + \mathcal{E}$ – the square in the first term of rhs is used to preserve the rotational symmetry. The result can be seen in the Fig. 2. For mid-central collisions, where ε_2 is large, the nonlinear term is important, yet this estimator is not as good as previous estimators of v_2 and v_3 . Therefore, to obtain a better estimator for v_4 is necessary to combine both contributions, thus using Eqs. (5) and (6), Fig. 2 show that the resulting estimator is good for all centralities. For v_5 , the best estimator has linear and nonlinear terms: ε_5 and $\varepsilon_2 \varepsilon_3$ [7].

We have defined a quantitative measure of the quality of estimators of v_n from initial condi-

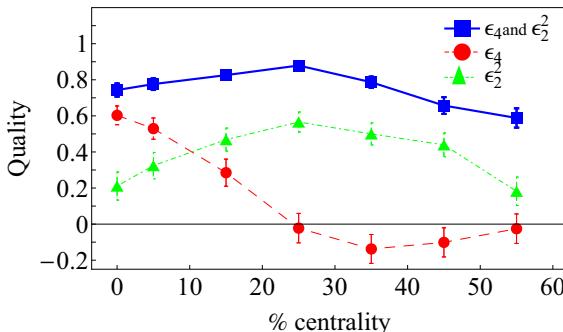


Figure 2: *Quality* for 3 different estimators of v_4 . The combined estimator (square) is the best estimator.

tions in event-by-event hydrodynamics. v_2 and v_3 are well predicted by ε_2 and ε_3 , but for v_4 and v_5 it is necessary nonlinear terms. These results provide an improved understanding of the hydrodynamic response to the initial state in realist heavy-ion collisions.

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