

# DEPARTAMENTO DE MATEMÁTICA APLICADA

## Relatório Técnico

RT-MAP-9002  
RETARDED FUNCTIONAL DIFFERENTIAL  
EQUATIONS WITH WHITE NOISE  
PERTURBATIONS

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# RETARDED FUNCTIONAL DIFFERENTIAL EQUATIONS

## WITH WHITE NOISE PERTURBATIONS

by

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### ABSTRACT

Given a retarded functional differential equation, a stable equilibrium point and a bounded neighbourhood contained in its basin of attraction, one perturbs the differential equation with small white noise and proves a large deviation result, namely, solutions starting in the neighbourhood very likely escape from it. The end of the escaping path is described.

June 1989

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The authors thank CAPES and COFECUB for supporting this work.

## I. Preliminaries and statement of the main result

Let  $C$  be the Banach space of all continuous paths  $\varphi: [-1, 0] \rightarrow \mathbb{R}^n$  with respect to the norm  $\|\varphi\| = \max\{|\varphi(\theta)|, -1 \leq \theta \leq 0\}$ , where  $|\cdot|$  is the Euclidean norm in  $\mathbb{R}^n$ . For a continuous function  $x: [t_0 - 1, t_0 + A) \rightarrow \mathbb{R}^n$ ,  $A > 0$ , and a real number  $t$  in  $[t_0, t_0 + A)$ , we write  $x_t$  to denote the element in  $C$  given by  $x_t(\theta) = x(t + \theta)$ ,  $-1 \leq \theta \leq 0$ ; then, the function  $t \in [t_0, A) \mapsto x_t \in C$  is continuous.

We call a retarded functional differential equation a relation of the form

$$(1,0) \quad \dot{x}(t) = f(x_t)$$

where  $f: C \rightarrow \mathbb{R}^n$  is a continuous function (see [Ha]).

An important example is given by the integrodifferential equation

$$\dot{x}(t) = F(x(t), x(t-1)) - \int_{-1}^0 a(-\theta)g(x(t+\theta))d\theta$$

where  $F: \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}^n$ ,  $g: \mathbb{R}^n \rightarrow \mathbb{R}^n$  and  $a: [0, 1] \rightarrow \mathbb{R}$  are continuous functions.

For technical reasons, we will suppose that  $f$  is continuously differentiable and that  $\|f\|_1 = \max\{\sup_{\varphi \in C} |f(\varphi)|, \sup_{\varphi \in C} \|Df(\varphi)\|\}$  is finite, where  $\|Df(\varphi)\| = \sup\{|Df(\varphi)\psi| : \|\psi\| = 1\}$ .

Equation (1,0) defines the semigroup solution  $(S(t))_{t \geq 0}$  - the flow - on  $C$  by

$$S(t)\varphi = x_t, \quad t \geq 0, \quad \varphi \in C$$

where  $x$  is the solution of (1,0) in  $[0, +\infty)$  which starts in  $\varphi$ , i. e.,  $x_0 = \varphi$  or  $x(\theta) = \varphi(\theta)$ , for all  $\theta$  in  $[-1, 0]$ . We know that  $S(t): C \rightarrow C$  is continuously differentiable,  $S(t+s) = S(t)S(s)$  for all  $t, s \geq 0$ ,  $S(0) =$  identity of  $C$  and also that for any fixed  $\varphi$  in  $C$ , and any  $\psi$  in  $C$ ,  $\lim_{t \rightarrow 0} \left[ \frac{\partial}{\partial \varphi}(S(t)\varphi) \right] \psi = \psi$  in  $C$ .

Let  $W^{1,2}$  be the subset of all functions  $\varphi: [-1, 0] \rightarrow \mathbb{R}^n$  absolutely continuous on  $[-1, 0]$  such that  $\dot{\varphi} \in L_2$  i.e.  $\|\dot{\varphi}\|_{L_2} = \left( \int_{-1}^0 |\dot{\varphi}(\theta)|^2 d\theta \right)^{1/2} < \infty$ . With respect to the norm  $\|\varphi\|_{1,2} = \left( |\varphi(0)|^2 + \int_{-1}^0 |\dot{\varphi}(\theta)|^2 d\theta \right)^{1/2}$ ,  $W^{1,2}$  is a Hilbert space and the inclusion  $W^{1,2} \rightarrow C$  is continuous. We know that  $W^{1,2}$  is invariant under the flow  $(S(t))_{t \geq 0}$  and that  $S(t): W^{1,2} \rightarrow W^{1,2}$  remains continuously differentiable.

Later, we will suppose that the function  $\varphi = 0$  in  $C$  is an equilibrium point of Equation (1,0), that is,  $f(0) = 0$ , which attracts its small neighborhoods. We know that there exist positive constant  $K$  and  $a$  such that  $\|x_t(\varphi)\| \leq K e^{-at} \|\varphi\|$  for all  $t \geq 0$  and all  $\varphi$  in a sufficiently small neighborhood of 0. The above estimate is obtained (see [Ha]) by considering the linearized variational equation about  $\psi = 0$ :  $\dot{y}(t) = f'(0)y_t$ .

Let  $(\Omega, F, P)$  be a probability space and let  $w(t): \Omega \rightarrow \mathbb{R}^n$ ,  $t \geq 0$ , be the Brownian motion in  $\mathbb{R}^n$ . We remember [F-W] that: 1<sup>o</sup>)  $w(0) = 0$ ; 2<sup>o</sup>)  $w$  is continuous in  $t \in [0, \infty)$  with probability 1; 3<sup>o</sup>)  $w$  has stationary independent increments; 4<sup>o</sup>) for each  $t > 0$  and each borelian  $A \subset \mathbb{R}^n$  we have  $P\{w(t) \in A\} = \int_A \frac{1}{\sqrt{2\pi t}} e^{-|x|^2/2t} dx$ .

Let us consider the perturbed stochastic differential equation

$$(1, \epsilon) \quad X^\epsilon(t) = f(X_t^\epsilon) + \epsilon \dot{w}(t), \quad t > 0$$

for which a solution through  $\varphi \in C$  at time  $t = 0$  is meant a continuous random variable  $X^\epsilon(t, \omega)$ ,  $t \geq -1$ ,  $\omega \in \Omega$  such that  $X^\epsilon(\theta, \omega) = \varphi(\theta)$  (with probability one) for all  $\theta \in [-1, 0]$  and such that for all  $t \geq 0$ , we have

$$X^\epsilon(t) = \varphi(0) + \int_0^t f(X_s^\epsilon) ds + \epsilon w(t)$$

also with probability one.

We know that, for each  $\varphi \in C$ , there exists one and only one solution of Equation (1,  $\epsilon$ ) through  $\varphi$  defined for all  $t \geq 0$ . We will prove that:

I.1. Proposition - Given an interval  $[0, T]$  and a function  $\varphi \in C$ , then, during the time interval  $[0, T]$ , the solution  $X^\epsilon(t)$  of equation (1,  $\epsilon$ ) through  $\varphi$  at time  $t = 0$  very likely follows the solution of Equation (1, 0) through  $\varphi$  at time  $t = 0$ ; more precisely, for any  $\delta > 0$ ,

$$\lim_{\epsilon \rightarrow 0} P \left\{ \sup_{t \in [-1, T]} |X^\epsilon(t) - x(t)| > \delta \right\} = 0$$

or, equivalently,

$$\lim_{\epsilon \rightarrow 0} P \left\{ \sup_{t \in [0, T]} \|X_t^\epsilon - x_t\| > \delta \right\} = 0.$$

Proof: It is easy to see that

$$\|x_t^\varepsilon - x_t\| \leq \|f\|_1 \int_0^1 \|x_s^\varepsilon - x_s\| ds + \varepsilon |w(t)|,$$

so, Gronwall's inequality implies that

$$\|x_t^\varepsilon - x_t\| \leq \varepsilon e^{T\|f\|_1} \sup_{t \in [0, T]} |w(t)|.$$

Using the classical inequality (see [F.W])

$$P \left\{ \sup_{0 \leq t \leq T} \varepsilon |w(t)| > \eta \right\} \leq C_1 e^{-C_2/\varepsilon^2}$$

we find that

$$P \left\{ \sup_{0 \leq t \leq T} \|x_t^\varepsilon - x_t\| > \delta \right\} \leq C_1 e^{-C_2'/\varepsilon^2}$$

for appropriate constants  $C_1$  e  $C_2$  ; this last inequality clearly implies the conclusion of our proposition.

In order to estimate the probability that a solution  $x_t^\varepsilon$  of the Equation (1,  $\varepsilon$ ) belongs to a neighborhood of a fixed path  $\{x(t), T_1 \leq t \leq T_2\}$ , we introduce the action functional associated to the random process  $X_t^\varepsilon$  and a quasipotential extending Freidlin and Wentzell's construction for perturbed vector fields [see F-W].

Associated to the Brownian motion there is an action functional

$$S: C[T_1, T_2] \rightarrow [0, \infty]$$

defined by

$$S(\gamma) = \frac{1}{2} \int_{T_1}^{T_2} |\dot{\gamma}(t)|^2 dt$$

if  $\gamma \in W^{1,2}[T_1, T_2]$  and  $S(\gamma) = +\infty$  otherwise.

In a similar way as Freidlin and Wentzell do for vector fields, let us define the normalized action functional associated to the process  $X_t^\epsilon$  by

$$S_{T_1 T_2}(\gamma) = \frac{1}{2} \int_{T_1}^{T_2} |\dot{\gamma}(t) - f(\gamma_t)|^2 dt$$

Without loss of generality, we can assume that either  $T_1 = 0$  and  $T_2 > 0$  or  $T_2 = 1$  and  $T_1 < 0$ .

Let us denote by  $\rho_T$  the distance between two continuous functions  $x$  and  $y$  in  $C[-1, T]$ :

$$\rho_T(x, y) = \max_{t \in [-1, T]} |x(t) - y(t)|$$

and, for  $\phi \in C[-1, T]$ , let us define:

$$\rho_T(x, \phi) = \inf\{\rho_T(x, y) : y \in \phi\}.$$

The following is an extension of a theorem of Freidlin and Wentzell, which we will use many times:

**1.2. Theorem** - Let  $X^\epsilon(\phi)$  be a solution of the perturbed equation (1,  $\epsilon$ ). Then, given  $T > 1$ ,  $\delta > 0$ ,  $\beta > 0$  and  $\epsilon_0 > 0$  we have:

(a) There exists  $\epsilon_0 > 0$  such that for all  $\epsilon \in (0, \epsilon_0)$  the inequality

$$P\{\rho_T(x^\epsilon(\varphi) - \gamma) < \delta\} \geq \exp\{-\epsilon^{-2}(S(\gamma) + \beta)\}$$

holds for all  $\varphi \in W^{1,2}$  and  $\gamma \in W^{1,2}[-1, T]$  such that  $\gamma_0 = \varphi$  and  $S(\gamma) \leq s_0$ .

(b) There exists  $\epsilon_0 > 0$  such that for all  $\epsilon \in (0, \epsilon_0)$ , all  $s \in [0, s_0]$  and all  $\varphi \in W^{1,2}$ , we have

$$P\{\rho_T(x^\epsilon(\varphi), \phi(s, \varphi)) \geq \delta\} \leq \exp\{-\epsilon^{-2}(s - \beta)\}$$

where  $\phi(s, \varphi) = \{\gamma \in W^{1,2}[-1, T] : \gamma_0 = \varphi \text{ and } S(\gamma) \leq s\}$ .

The quasipotential of Equation (1,0) with respect to the origin 0 in  $W^{1,2}$  is, by definition, the functional

$$V(0, \varphi) = \inf\{S_{T_1, T_2}(\gamma) : t_1 < T_2, \gamma \in W^{1,2}[T_1 - 1, T_2], \gamma_{T_1} = 0, \gamma_{T_2} = \varphi\}.$$

It is clear that  $V(0, \varphi) \geq 0$  for all  $\varphi \in W^{1,2}$  and that  $V(0, \varphi)$  is continuous in  $\varphi$ ; moreover, if 0 is an equilibrium of equation (1,0), then  $V(0, 0) = 0$ .

The name quasipotential comes from the fact that for gradient systems in  $R^n$ ,  $\dot{x}(t) = -\text{grad } U(x(t))$ , with 0 as an attractor, the quasipotential is twice the potential  $U$ , if we stay in the basin of the attractor.

The following theorem, as in the non retarded case, studies the exit from a domain contained in the basin of an attracting equilibrium.

**I.3. Theorem** - Let  $O$  be an asymptotically stable equilibrium of Equation (1,0) and let  $D \subset W^{1,2}$  be a bounded connected open neighborhood of  $O$ , the closure of which admits a  $\delta_0$ -neighborhood  $D_{\delta_0}$  contained in the basin of  $O$ . Let us suppose also that  $\bar{D}$  and  $\bar{D}_{\delta}$  are strictly contracted by the flow of the nonperturbed system. Let us suppose, moreover, that there exists a unique point  $\varphi_0 \in \partial D$  minimizing the quasipotential  $V(O, \varphi)$  on  $\partial D$ .

Then, for any  $\delta > 0$  and all  $\varphi \in D$  we have:

$$\lim_{\varepsilon \rightarrow 0} P_{\varphi} \{ \|X_{\tau_{\varepsilon}}^{\varepsilon} - \varphi_0\|_{1,2} < \delta \} = 1$$

where  $\tau_{\varepsilon} = \inf\{t > 0: X_t^{\varepsilon} \in \partial D\}$ .

Before proving the above theorem, we will study the extremals of the action functional.

## II. The action functional

We will restrict ourselves to random perturbations of equations of the following type:

$$(2.1) \quad \dot{x}(t) = f(x_t)$$

where  $f: C \rightarrow \mathbb{R}^n$  is given by

$$f(\varphi) = F(\varphi(0), \varphi(-1)) - \int_{-1}^0 a(-\theta)g(\varphi(\theta))d\theta.$$

We suppose that  $F: \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}^n$  and  $g: \mathbb{R}^n \rightarrow \mathbb{R}^n$  are bounded  $C^1$  functions with bounded derivatives and that  $a: [0,1] \rightarrow \mathbb{R}$  is of class  $C^2$ .

The perturbed equation is

$$(2.3) \quad \dot{x}^\epsilon(t) = f(x_t^\epsilon) + \epsilon \dot{w}(t)$$

The corresponding action functional is

$$S_{0T}(\gamma) = S(\gamma) = \frac{1}{2} \int_0^T \left| \dot{\gamma}(t) - F(\gamma(t), \gamma(t-1)) \right|^2 dt + \int_{-1}^0 a(-\theta) g(\gamma(t(\theta))) d\theta \Big|^2 dt.$$

We want to minimize  $S$  on the following class:

$$M = \{ \gamma \in C[-1, T] \cap W^{1,2}[0, T] : \gamma_0 = \varphi, \gamma_T = \bar{\varphi} \}$$

where  $\varphi$  and  $\bar{\varphi}$  are given functions.

It is clear that we have to assume  $T \geq 1$ .

**II.1. Proposition** - A necessary condition for  $\gamma \in M$  to minimize  $S$  on  $M$  is that  $\gamma$  satisfies the following Euler-Lagrange equation (2.4):

$$\begin{aligned} \frac{d}{dt} H(\gamma)(t) + \left[ D_1 F(\gamma(t), \gamma(t-1)) \right]^* H(\gamma)(t) + \left[ D_2 F(\gamma(t+1), \gamma(t)) \right]^* H(\gamma)(t+1) \\ - \left[ g'(\gamma(t)) \right]^* \int_{-1}^0 a(-\theta) H(\gamma)(t-\theta) d\theta = 0 \end{aligned}$$

where

$$H(\gamma)(t) = \dot{\gamma}(t) - F(\gamma(t), \gamma(t-1)) + \int_{-1}^0 a(-\theta) g(\gamma(t+\theta)) d\theta$$

(the star indicates the matrix transposition).

Recall that  $\gamma_0 = \varphi$  and  $\gamma_T = \bar{\varphi}$  and observe that the equation above which is retarded and advanced in time, is, as matter of fact, a second order integro-differential equation. In spite of the fact that we do not know "a priori" that  $\gamma$  has first and second derivatives in  $[0, T-1]$ , we remark that the function  $H(\gamma)(t)$  is absolutely continuous in  $[0, T-1]$  and  $\frac{d}{dt} H(\gamma(\cdot)) \in L_2[0, T-1]$ . Later on we will show that  $\gamma$  is  $C^2$  in  $[0, T-1]$ .

Proof. Let  $h \in C^1[0, T-1]$  such that  $h(0) = h(T-1) = 0$  and put  $h(\theta) = 0$ ,  $\theta \in [-1, 0]$  and  $h(t) = 0$ ,  $t \in [T-1, T]$ . We know that if  $\gamma \in M$  is a local minimum for  $V$  then  $\left. \frac{d}{d\lambda} S(\gamma + \lambda h) \right|_{\lambda=0} = 0$  for all  $h$  as above.

Let us make explicit this condition:

$$\begin{aligned} \left. \frac{d}{d\lambda} S(\gamma + \lambda h) \right|_{\lambda=0} = & \int_0^T H^*(\gamma)(t) \left[ \dot{h}(t) - D_1 F(\gamma(t), \gamma(t-1)) h(t) - \right. \\ & \left. - D_2 F(\gamma(t), \gamma(t-1)) h(t-1) + \int_{-1}^0 a(-\theta) g'(\gamma(t+\theta)) h(t-\varepsilon) d\theta \right] dt. \end{aligned}$$

Since  $h_0 = h_T = 0$  and after using integration by parts and inversion of the two integrals we obtain the following expression:

$$\begin{aligned} \left. \frac{dS}{d\lambda}(\gamma + \lambda h) \right|_{\lambda=0} = & \int_0^{T-1} \left\{ H^*(\gamma)(t) + \int_0^t \left[ H^*(\gamma)(s) D_1 F(\gamma(s), \gamma(s-1)) + \right. \right. \\ & \left. \left. + H^*(\gamma)(s+1) D_2 F(\gamma(s+1), \gamma(s)) - \int_{-1}^0 a(-\theta) H^*(\gamma)(s-\theta) d\theta \cdot g'(\gamma(s)) \right] ds \right\} \dot{h}(t) dt \end{aligned}$$

Since  $h$  is arbitrary, the result follows from Du-Bois-Reymond's lemma (see [A]) which says that if  $\phi: [a, b] \rightarrow \mathbb{R}^n$  is continuous

and if  $\int_a^b \phi^*(t) \dot{h}(t) dt = 0$  for all  $C^1$  functions  $h: [a, b] \rightarrow \mathbb{R}^n$  such that  $h(a) = h(b) = 0$ , then  $\phi$  is constant on  $[a, b]$ .

We have then, for all  $t \in [0, T-1]$ :

$$H^*(\gamma)(t) + \int_0^t \left[ H^*(\gamma)(s) D_1 F(\gamma(s), \gamma(s-1)) + H^*(\gamma)(s+1) D_2 F(\gamma(s+1), \gamma(s)) - \int_{-1}^0 a(-\theta) H^*(\gamma)(s-\theta) d\theta \cdot g'(\gamma(s)) \right] ds = \text{constant.}$$

Since the integrand belongs to  $L_2[0, T-1]$  it follows that  $H^*(\gamma)(t)$  is absolutely continuous on  $[0, T-1]$ . If we transpose the expression obtained after computing the derivate of the last equality we get the following Euler-Lagrange equation which holds for  $\gamma$ , almost everywhere in  $[0, T-1]$ :

$$\frac{d}{dt} H(\gamma)(t) + \left[ D_1 F(\gamma(t), \gamma(t-1)) \right]^* H(\gamma)(t) + \left[ D_2 F(\gamma(t+1), \gamma(t)) \right]^* H(\gamma)(t+1) - \left[ g'(\gamma(t)) \right]^* \int_{-1}^0 a(-\theta) H(\gamma)(t-\theta) d\theta = 0 \text{ as claimed.}$$

Let us now consider the existence of an absolute minimum for  $S$  in the class  $M$ , which will imply the existence of solution for the equation (2.4) with boundary condition  $\gamma_0 = \varphi$  and  $\gamma_T = \bar{\varphi}$ .

Let  $\nu = \inf\{S(\gamma) : \gamma \in M\} \geq 0$  and  $(\gamma_m)_{m \in \mathbb{N}}$  a minimizing sequence of elements in  $M$ , that is,  $S(\gamma_m) \rightarrow \nu$  as  $m \rightarrow \infty$ . Without loss of generality we may assume  $S(\gamma_m) \leq S(\gamma_1)$ .

**II.2. Proposition** - There exists a subsequence, also denoted by  $(\gamma_m)_{m \in \mathbb{N}}$ , which converges uniformly in  $[0, T-1]$  to a function  $\bar{\gamma} \in M$  such that  $S(\bar{\gamma}) = \nu$ .

**Proof.** The idea is to show that  $M$  is compact in  $C[0, T]$  and that  $S$  is lower semi-continuous on  $M$ .

We start observing that there exist constants  $\alpha$  and  $\beta$  such that  $\alpha > 0$  and

$$\frac{1}{2} \left| \dot{\gamma}_m(t) - F(\gamma_m(t), \gamma_m(t-1)) + \int_{-1}^0 a(-\theta) g(\gamma_m(t+\theta)) d\theta \right|^2 \geq \alpha \left| \dot{\gamma}_m(t) \right|^2 - \beta.$$

This implies that

$$-\beta T + \alpha \int_0^T \left| \dot{\gamma}_m(t) \right|^2 dt \leq S(\gamma_m) \leq A$$

and then

$$\|\dot{\gamma}_m\|_{L_2} \leq B = \left( \frac{A + \beta T}{\alpha} \right)^{1/2} \text{ for all } m.$$

By Cauchy-Schwarz inequality we have:

$$\left| \gamma_m(t) - \gamma_m(s) \right| \leq \left| \int_s^t \dot{\gamma}_m(s) \cdot 1 ds \right| \leq \left| \int_s^t \dot{\gamma}_m(s) \right|^2 ds \Big|^{1/2} |t-s|^{1/2}$$

and we are able to conclude that  $(\gamma_m)_{m \in \mathbb{N}}$  is an equicontinuous sequence in  $C[0, T-1]$ . Again, by the same inequality we obtain:

$$|\gamma_m(t)| \leq |\varphi(0)| + \int_0^t |\dot{\gamma}_m(s)| \cdot 1 \, ds \leq |\varphi(0)| + B \cdot T^{1/2}$$

and  $(\gamma_m)$  is a bounded sequence in  $C[0, T]$ . By the Theorem of Ascoli and Arzela, there exists a subsequence of  $(\gamma_m)$  which converges uniformly to a function  $\bar{\gamma} \in C[0, T-1]$ ; extend  $\bar{\gamma}$  to  $[-1, T]$  by  $\bar{\gamma}_0 = \varphi$  and  $\bar{\gamma}_T = \bar{\varphi}$ . To show that  $\bar{\gamma}$  is absolutely continuous in  $[0, T-1]$  we consider a chain of inequalities obtained by using the Cauchy-Schwarz inequality for integrals and sums. For any numbers  $s_i, t_i \in [0, T-1]$ ,  $i=1, \dots, k$ , such that  $s_1 < t_1 < s_2 < t_2 < \dots < s_k < t_k$  we have

$$\begin{aligned} \sum_{i=1}^k |\gamma_m(t_i) - \gamma_m(s_i)| &\leq \sum_{i=1}^k |t_i - s_i|^{1/2} \left( \int_{s_i}^{t_i} |\dot{\gamma}_m(s)|^2 \, ds \right)^{1/2} \leq \\ &\leq \left( \sum_{i=1}^k |t_i - s_i| \right)^{1/2} \left( \sum_{i=1}^k \int_{s_i}^{t_i} |\dot{\gamma}_m(s)|^2 \, ds \right)^{1/2} \leq \\ &\leq B \left( \sum_{i=1}^k |t_i - s_i| \right)^{1/2}. \end{aligned}$$

Passing to the limit as  $m \rightarrow \infty$  we obtain

$$\sum_{i=1}^k |\bar{\gamma}(t_i) - \bar{\gamma}(s_i)| \leq B \left( \sum_{i=1}^k |t_i - s_i| \right)^{1/2}.$$

so  $\bar{\gamma}$  is absolutely continuous on  $[0, T-1]$ .

To prove  $\bar{\gamma} \in L_2[0, T-1]$  take  $t \in (0, T-1)$  and choose  $h > 0$  small enough such that  $[t, t+h] \subset [0, T-1]$ .

Using again Cauchy-Schwarz inequality we have

$$\left| \frac{\gamma_m(t+h) - \gamma_m(t)}{h} \right|^2 \leq \frac{1}{h} \int_0^h |\dot{\gamma}_m(t+u)|^2 du$$

If we integrate between 0 and  $(T-1-h)$  and by inversion in the order of integration one obtains

$$\int_0^{T-1-h} \left| \frac{\gamma_m(t+h) - \gamma_m(t)}{h} \right|^2 dt \leq \int_0^h \left[ \int_0^{T-1-h} |\dot{\gamma}_m(t+u)|^2 dt \right] du$$

and since the last term is bounded by  $B^2$ , we pass to the limit as  $m \rightarrow \infty$  and see that, for all  $\tau < T-1$  and  $h > 0$  sufficiently small, we have

$$\int_0^\tau \left| \frac{\bar{\gamma}(t+h) - \bar{\gamma}(t)}{h} \right|^2 dt \leq B^2.$$

Since  $\bar{\gamma}$  is absolutely continuous in  $[0, T-1]$ , we use Fatou's theorem and obtain

$$\int_0^\tau |\dot{\bar{\gamma}}(t)|^2 dt \leq B^2.$$

But  $\tau < T-1$  arbitrary implies  $\dot{\bar{\gamma}} \in L_2[0, T-1]$  and  $\|\dot{\bar{\gamma}}\|_{L_2} \leq B$ .

Let us show now that  $\dot{\gamma}_m$  converges weakly to  $\dot{\bar{\gamma}}$  on  $[0, T-1]$ , in the sense that, for each  $\psi \in L_2[0, T-1]$ , we have  $\lim_{m \rightarrow \infty} I_m = 0$ , where

$$I_m = \left| \int_0^{T-1} (\gamma_m(t) - \bar{\gamma}(t)) * \psi(t) dt \right|.$$

Given  $\epsilon > 0$  and  $\psi \in L_2 [0, T-1]$ , we can find a polynomial  $p(t)$  such that

$$\int_0^{T-1} |p(t) - \psi(t)|^2 dt < \epsilon^2.$$

Choose  $m_0$  such that, for  $m \geq m_0$ , we have

$$\sup_{0 \leq t \leq T-1} |\gamma_m(t) - \bar{\gamma}(t)| \leq \frac{\epsilon}{\|\dot{p}\|_1}$$

$$\text{where } \|\dot{p}\|_1 = \int_0^{T-1} |\dot{p}(t)| dt.$$

Then

$$I_m \leq \left| \int_0^{T-1} (\gamma_m(t) - \bar{\gamma}(t)) * p(t) dt \right| + \left| \int_0^{T-1} (\gamma_m(t) - \bar{\gamma}(t)) * (\psi(t) - p(t)) dt \right|.$$

Using integration by parts and Cauchy-Schwarz inequality we get:

$$I_m \leq \left| \int_0^{T-1} (\gamma_m(t) - \bar{\gamma}(t)) * \dot{p}(t) dt \right| + \|\dot{\gamma}_m - \bar{\dot{\gamma}}\|_{L_2} \|\psi - p\|_{L_2}$$

so

$$I_m \leq \left( \sup_{0 \leq t \leq T-1} |\gamma_m(t) - \bar{\gamma}(t)| \right) \int_0^{T-1} |\dot{p}(t)| dt + 2B\epsilon$$

and finally,  $I_m \leq (1+2B)\epsilon$  which shows that  $\lim_{m \rightarrow \infty} I_m = 0$ .

To conclude, let us prove that the absolute minimum  $\mu$  of  $S$  is achieved in  $\bar{\gamma}$ .

Let us introduce the following abbreviations:

$$f_m = F(\gamma_m(t), \gamma_m(t-1)) - \int_{-1}^0 a(-\theta)g(\gamma_m(t+\theta))d\theta$$

$$\bar{f} = F(\bar{\gamma}(t), \bar{\gamma}(t-1)) - \int_{-1}^0 a(-\theta)g(\bar{\gamma}(t+\theta))d\theta.$$

We already know that  $f_m$  converges to  $\bar{f}$  uniformly on  $[0, T]$ .

We have:

$$\begin{aligned} S(\gamma_m) &= S(\bar{\gamma}) + \frac{1}{2} \int_0^T (|\dot{\gamma}_m - f_m|^2 - |\dot{\bar{\gamma}} - \bar{f}|^2) dt \\ &\quad + \frac{1}{2} \int_0^T (|\dot{\bar{\gamma}} - \bar{f}|^2 - |\dot{\bar{\gamma}} - \bar{f}|^2) dt \\ &= S(\bar{\gamma}) + \frac{1}{2} \int_0^T |\dot{\gamma}_m - \dot{\bar{\gamma}}|^2 dt + \int_0^T (\dot{\bar{\gamma}} - f_m)^* (\dot{\gamma}_m - \dot{\bar{\gamma}}) dt \\ &\quad + \frac{1}{2} \int_0^T (f_m - \bar{f} - 2\dot{\bar{\gamma}})^* (f_m - \bar{f}) dt \end{aligned}$$

Therefore

$$\begin{aligned} S(\gamma_m) &\geq S(\bar{\gamma}) - \left| \int_0^T (\dot{\bar{\gamma}} - f_m)^* (\dot{\gamma}_m - \dot{\bar{\gamma}}) dt \right| \\ &\quad - \frac{1}{2} \left| \int_0^T (f_m - \bar{f} - 2\dot{\bar{\gamma}})^* (f_m - \bar{f}) dt \right| \end{aligned}$$

Since these last integrals tend to zero as  $m$  goes to  $+\infty$ , we get  $S(\bar{\gamma}) = \mu$ .

### III. Proof of Theorem I.2

In this section, following Freidlin and Wentzell's approach [F-W], we will decompose the proof of Theorem I.2 into a series of lemmas.

III.1. Lemma - Let  $F$  be a compact subset of  $C$  and  $T, \delta$  positive numbers. Then, there exist  $\varepsilon_0 > 0$  and  $\beta > 0$  such that

$$P \left\{ \sup_{0 \leq t \leq T} \|X_t^\varepsilon(\varphi) - x_t(\varphi)\| \geq \delta \right\} \leq \exp \{-\varepsilon^{-2}\beta\}$$

for any  $\varphi \in F$  and any  $\varepsilon > 0$ ,  $\varepsilon < \varepsilon_0$ .

Proof: Let  $\varphi \in F$  fixed and define:

$$G(\varphi) = \{\gamma \in C[-1, T] : \gamma_0 = \varphi, \rho_T(\gamma, x(\varphi)) \geq \delta\}.$$

Recall that  $\rho_T(\gamma, x(\varphi)) = \sup_{-1 \leq t \leq T} |\gamma(t) - x(t, \varphi)|$ .

Since  $G(\varphi)$  is closed and  $F$  is compact we see that

$$\bigcup_{\varphi \in F} G(\varphi)$$

is closed in  $C$ .

We know that the infimum  $d$  of  $S(\gamma)$  for  $\gamma \in \bigcup_{\varphi \in F} G(\varphi)$  is achieved.

Since  $S(\gamma)$  vanishes only on the solution of Equation (1,0), it is clear that  $d > 0$ .

For each  $d' < d$ , let us consider the set

$$\Phi_{\varphi}(d') = \{\gamma \in C[-1, T] : \gamma_0 = \varphi \text{ and } S(\gamma) \leq d'\}.$$

It is compact and disjoint of  $\bigcup_{\varphi \in F} G(\varphi)$ ; therefore, the distance between  $\Phi_{\varphi}(d')$  and  $\bigcup_{\varphi \in F} G(\varphi)$  is a positive number  $\delta'$ .

Now, for any  $\gamma_1 > 0$ , we have for any  $\epsilon$  and  $\varphi \in F$ :

$$\begin{aligned} \mathbb{P}\{\rho_T(X^\epsilon(\varphi), x(\varphi)) \geq \delta\} &= \mathbb{P}\{X^\epsilon(\varphi) \in G(\varphi)\} \\ &\leq \mathbb{P}\{\rho_T(X^\epsilon(\varphi), \Phi_{\varphi}(d')) \geq \delta'\} \\ &\leq \exp\{-\epsilon^{-2}(d' - \gamma_1)\}. \end{aligned}$$

Taking  $\beta = d' - \gamma_1$ , this proves the lemma.

**III.2. Lemma** - Let us suppose that 0 is an asymptotically stable equilibrium of Equation (1,0). Let  $D$  be a bounded connected open set, whose closure  $\bar{D}$  is contained in the basin of attraction of 0. Moreover, let us suppose that the flow  $\phi_t$  of Equation (1,0) satisfies:

$$\phi_t(\bar{D}) \subset D$$

for all  $t > 0$ .

Then for any fixed  $\alpha > 0$  such that the ball  $B_{\alpha}(0)$  is contained in  $D$ , we have:

(a) There exist positive constants  $a$  and  $T_0$  such that

$$S(\gamma) > a(T - T_0)$$

for any  $T > T_0$  and any  $\gamma \in C[-1, T]$  satisfying  $\gamma_t \in \bar{D} \setminus B(0, \alpha)$  for  $t \in [0, T]$ .

(b) There exist positive constants  $c$  and  $T_0$  such that, for any  $\varepsilon > 0$  small enough and any  $\varphi \in \bar{D} \setminus B_\alpha(0)$  we have

$$P_\varphi\{\zeta_\alpha > T\} \leq \exp\{-\varepsilon^{-2}(T - T_0) \cdot c\}$$

for any  $T > T_0$ , where  $\zeta_\alpha = \inf\{t: x_t^\varepsilon \notin D \setminus B_\alpha(0)\}$ .

Proof: (a) We take  $\alpha' < \alpha$  such that any solution of Equation (1.0) which starts in  $B_{\alpha'}(0)$  never leaves  $B_\alpha(0)$ .

For a given  $\varphi \in \bar{D}$  let  $T(\alpha, \varphi)$  be the first instant  $t$  at which we have  $x_t(\varphi) \in \bar{B}_{\alpha'}(0)$ . It is clear that  $T(\alpha, \varphi) < \infty$ . Let us see that  $T(\alpha, \varphi)$  is upper semicontinuous with respect to  $\varphi$ : given  $\varepsilon > 0$  we have  $x_{T(\alpha, \varphi) + \varepsilon}(\varphi) \in B_{\alpha'}(0)$ ; therefore we can take  $r > 0$  small enough in order to guarantee that  $B_r(x_{T(\alpha, \varphi) + \varepsilon}(\varphi)) \subset B_{\alpha'}(0)$ ; using the continuity of the solution with respect to the initial conditions, we can find a positive number  $\delta$  such that  $|x_t(\bar{\varphi}) - x_t(\varphi)| < r$  for all  $\bar{\varphi} \in B_\delta(0)$  and all  $t \in [0, T(\alpha, \varphi) + \varepsilon]$ ; therefore,  $x_{T(\alpha, \varphi) + \varepsilon}(\bar{\varphi}) \in B(x_{T(\alpha, \varphi) + \varepsilon}(\varphi), r)$  so that  $T(\alpha, \bar{\varphi}) \leq T(\alpha, \varphi) + \varepsilon$ , which proves the upper semicontinuity of  $T(\alpha, \varphi)$  with respect to  $\varphi$ .

Let  $D_1$  be the closure of the image of  $\bar{D}$  by the flow of Equation (1.0) after the time 1; since  $D_1$  is compact, there exists

$$T_0 = \max\{T(\alpha, \varphi) : \varphi \in D_1\} < \infty.$$

It is clear that any solution of Equation (1.1) which starts at  $\varphi \in \bar{D}$  is in  $B_\alpha(0)$  after the time  $T_0$ .

We consider the closed subset  $C_{T_0}$  of  $C[-1, T_0]$  given by  $C_{T_0} = \{\gamma: [-1, T_0] \rightarrow \mathbb{R}^n : \gamma_t \in \bar{D} \setminus B_\alpha(0) \text{ for all } t \in [0, T_0]\}$ . The action functional  $S_{OT_0}$  assumes on  $C_{T_0}$  its infimum which is a positive number: in fact, if not, we would have a solution of Eq. (1.0) in  $C_{T_0}$ , which contradicts the definition of  $T_0$ . Therefore, there exists a constant  $A > 0$  such that  $S_{OT_0}(\gamma) \geq A$  for all  $\gamma \in C_{T_0}$ .

Let  $T > T_0$ , let  $[T/T_0]$  be the integer part of  $T/T_0$ , and let  $\gamma: [-1, T] \rightarrow \mathbb{R}^n$  such that  $\gamma_t \in \bar{D} \setminus B_\alpha(0)$  for all  $t \in [0, T]$ . Then,

$$\begin{aligned} S_{OT}(\gamma) &= \frac{1}{2} \left\{ \int_0^{T_0} + \dots + \int_{\left[\frac{T}{T_0}-1\right]T_0}^{\left[\frac{T}{T_0}\right]T_0} + \int_{\left[\frac{T}{T_0}\right]T_0}^T \right\} |\dot{\gamma}(t) - f(\gamma_t)|^2 dt \\ &\geq A + \dots + A = A \cdot \left[\frac{T}{T_0}\right] \geq \frac{A}{T_0} (T - T_0) \\ &= a(T - T_0) \end{aligned}$$

where  $a = \frac{A}{T_0}$ , which proves Lemma III.2.(a).

(b) We can assume that  $\delta < \frac{\alpha}{2}$ . Let  $A = A(\delta)$  and  $T_0 = T_0(\delta)$  the constants obtained in the proof of part (a) above for the set

$D = \bar{D}_\delta$  and the neighborhood  $B_{\alpha/2}(0)$ . Therefore, if  $\gamma: [-1, T_0(\delta)] \rightarrow \mathbb{R}^n$  satisfies  $\gamma_t \in \bar{D}_\delta \setminus B_{\alpha/2}(0)$  then  $S_{0T_0}(\delta) > \lambda_\delta$ .

For  $\varphi \in D$ , the functions of the set

$$\Phi_\varphi(\lambda_\delta) = \{\gamma: [-1, T_0(\delta)] \rightarrow \mathbb{R}^n: \gamma_0 = \varphi, S_{0T_0}(\delta)(\gamma) \leq \lambda_\delta\}$$

reach  $B_{\alpha/2}(0)$  or leave  $D_\delta$  during the interval of time  $[0, T_0(\delta)]$ .

Suppose  $\tau_\alpha > T_0(\delta)$ .

From the above assertion, we have

$$P_{0T_0}(\delta) (X^\varepsilon, \Phi_\varphi(\lambda_\delta)) \geq \delta$$

because  $X_t^\varepsilon \in D \setminus B_{\alpha/2}(0)$  for all  $t$  in  $[0, T_0(\delta)]$ .

Hence, for any sufficiently small  $\varepsilon > 0$  and any  $\varphi \in D$  we have the set inclusion

$$\{\omega \in \Omega: \tau_\alpha > T_0(\varepsilon)\} \subset \{\omega \in \Omega: P_{0T_0}(\delta) (X^\varepsilon, \Phi_\varphi(\lambda_\delta)) \geq \delta\}$$

so that, for any  $\beta > 0$ ,

$$\begin{aligned} P_\varphi\{\tau_\alpha > T_0(\delta)\} &\leq P_\varphi\{P_{0T_0}(\delta) (X^\varepsilon, \Phi_\varphi(\lambda_\delta)) \geq \delta\} \\ &\leq \exp\{-\varepsilon^{-2}(\lambda_\delta - \beta)\}. \end{aligned}$$

Now,

$$\begin{aligned}
P_{\varphi}\{\zeta_{\alpha} > (n+1)T_0\} &= \int_{\{\zeta_{\alpha} > nT_0\}} P_{X_{nT_0}^{\varepsilon}}\{\zeta_{\alpha} > T_0\} \\
&\leq \int_{\{\zeta_{\alpha} > nT_0\}} \sup_{\psi \in D} P_{\psi}\{\zeta_{\alpha} > T_0\} \\
&\leq \int_{\{\zeta_{\alpha} > nT_0\}} \exp\{-\varepsilon^{-2}(A_{\delta} - \beta)\} \\
&= P_{\varphi}\{\zeta_{\alpha} > nT_0\} \cdot \exp\{-\varepsilon^{-2}(A_{\delta} - \beta)\}
\end{aligned}$$

and by induction

$$\begin{aligned}
P_{\varphi}\{\zeta_{\alpha} > T\} &\leq P_{\varphi}\{\zeta_{\alpha} > [T/T_0]T_0\} \\
&\leq (P_{\varphi}\{\zeta_{\alpha} > T_0\})^{[T/T_0]} \\
&\leq \left( \sup_{\psi \in D} P_{\psi}\{\zeta_{\alpha} > T_0\} \right)^{[T/T_0]} \\
&\leq \left( \exp\{-\varepsilon^{-2}(A_{\delta} - \beta)\} \right)^{[T/T_0]} \\
&\leq \exp\{-\varepsilon^{-2}(T - T_0) \cdot c\}
\end{aligned}$$

where  $c = \frac{A_{\delta} - \beta}{T_0}$ , which concludes the proof of Lemma III.2.(b).

**III.3. Lemma** - (a) *There exists a positive constant L such that, for any  $\bar{\varphi} \in W^{1,2}$  in a sufficiently small neighbourhood of 0 in  $W^{1,2}$ , we can find a  $T > 0$  and a path  $\gamma \in W^{1,2}[-1, T]$*

satisfying  $\gamma_0 = 0$ ,  $\gamma_T = \bar{\varphi}$  and  $S_{0T}(\gamma) \leq L \|\bar{\varphi}\|_{W^{1,2}}$ .

(b) Given  $\gamma \in W^{1,2}[-1, T]$  satisfying  $\gamma_0 = 0$  and  $\gamma_T = \bar{\varphi}$  given in  $W^{1,2}$ , there exists a constant  $K > 0$  such that for any  $\bar{\varphi}_1 \in W^{1,2}$  sufficiently near of  $\bar{\varphi}$  in the space  $W^{1,2}$ , we can find a path  $\tilde{\gamma} \in W^{1,2}[-1, T]$  verifying the conditions:  $\tilde{\gamma}_0 = 0$ ,  $\tilde{\gamma}_T = \bar{\varphi}_1$  and

$$S_{0T}(\tilde{\gamma}) \leq S_{0T}(\gamma) + K \|\bar{\varphi}_1 - \bar{\varphi}\|_{W^{1,2}}.$$

Proof: (a) We take  $T > 1$  arbitrary. Let  $\gamma: [-1, T] \rightarrow \mathbb{R}^n$  be defined by  $\gamma(t) = 0$  for  $t \in [-1, 0]$ ,  $\gamma(t) = t\bar{\varphi}(-1)$  for  $t \in [0, T-1]$  and  $\gamma(t) = \bar{\varphi}(t-T)$  for  $t \in [T-1, T]$ . Then,  $\|\gamma_t\|_\infty \leq \|\bar{\varphi}\|_\infty$  for any  $t \in [0, T]$ .

Now,

$$\begin{aligned} S_{0T}(\gamma) &= \frac{1}{2} \int_0^{T-1} \left| \frac{\bar{\varphi}(-1)}{T-1} - f(\gamma_t) \right|^2 dt \\ &\quad + \frac{1}{2} \int_{T-1}^T |\bar{\varphi}(t-T) - f(\gamma_t)|^2 dt \\ &\leq \frac{1}{T-1} |\bar{\varphi}(-1)|^2 + \int_0^T |f(\gamma_t)|^2 dt + \|\dot{\bar{\varphi}}\|_{L_2}^2. \end{aligned}$$

Since,  $f(0) = 0$  and  $|f(\gamma_t)| \leq |f|_1 \|\gamma_t\|_\infty \leq |f|_1 \|\bar{\varphi}\|_\infty$  and  $\|\bar{\varphi}\|_\infty \leq |\bar{\varphi}(-1)| + \|\dot{\bar{\varphi}}\|_{L_2}$ , we can write:

$$S_{0T}(\gamma) \leq \left( \frac{1}{T-1} + 2T|f|_1^2 \right) |\bar{\varphi}(-1)|^2 + (1+2T|f|_1^2) \|\dot{\bar{\varphi}}\|_{L_2}^2$$

and, since we can suppose  $\|\dot{\bar{\varphi}}\|_{L_2} < 1$ ,

$$S_{OT}(\gamma) \leq L \|\varphi\|_{W^{1,2}}$$

where  $L = \max \left\{ \frac{1}{T-1} + 2T\|f\|_1^2, 1 + 2T\|f\|_1^2 \right\}$ ; this finishes the proof.

(b) Let  $\tilde{\gamma}$  be defined by:  $\tilde{\gamma}(t) = 0$  for  $t \in [-1, 0]$ ,

$$\tilde{\gamma}(t) = \gamma(t) + \frac{\bar{\varphi}_1(-1) - \bar{\varphi}(-1)}{T-1} \cdot t \quad \text{for } t \in [0, T-1], \quad \text{and}$$

$$\tilde{\gamma}(t) = \bar{\varphi}_1(t-T) \quad \text{for } t \in [T-1, T].$$

Then,  $\|\tilde{\gamma}_t - \gamma_t\|_\infty \leq \|\bar{\varphi}_1 - \bar{\varphi}\|_\infty \leq |\varphi_1(-1) - \bar{\varphi}(-1)| + \|\dot{\bar{\varphi}}_1 - \dot{\bar{\varphi}}\|_{L_2}$

and

$$\begin{aligned} S_{OT}(\tilde{\gamma}) - S_{OT}(\gamma) &= \\ &= \frac{1}{2} \int_0^T \langle \dot{\tilde{\gamma}}(t) - \dot{\gamma}(t) + f(\gamma_t) - f(\tilde{\gamma}_t), \dot{\tilde{\gamma}}(t) + \dot{\gamma}(t) - \\ & f(\tilde{\gamma}_t) - f(\gamma_t) \rangle dt \\ &\leq \frac{1}{2} \left( \|\dot{\tilde{\gamma}} - \dot{\gamma}\|_{L_2} + \|f(\tilde{\gamma}_t) - f(\gamma_t)\|_{L_2} \right) \left( \|\dot{\tilde{\gamma}}\|_{L_2} + \|\dot{\gamma}\|_{L_2} + \|f(\tilde{\gamma}_t)\|_2 + \|f(\gamma_t)\|_2 \right) \end{aligned}$$

We have the estimates:

$$(i) \quad \|\dot{\tilde{\gamma}} - \dot{\gamma}\|_{L_2} \leq K_1 \|\bar{\varphi}_1 - \bar{\varphi}\|_{W^{1,2}} \quad \text{where } K_1 = \max \left\{ 1, \frac{1}{T-1} \right\};$$

$$(ii) \quad \|f(\tilde{\gamma}_t) - f(\gamma_t)\|_{L_2} = \left( \int_0^T |f(\tilde{\gamma}_t) - f(\gamma_t)|^2 dt \right)^{1/2} \leq$$

$$\left( \int_0^T |f|_1^2 \|\tilde{\gamma}_t - \gamma_t\|_\infty^2 dt \right)^{1/2} \leq K_2 \|\bar{\varphi}_1 - \bar{\varphi}\|_{W^{1,2}};$$

where  $\kappa_2 = \|f\|_1 \cdot \left(2 + \frac{1}{T-1}\right)$ .

$$(iii) \quad \|\dot{\tilde{\gamma}}\|_{L_2} \leq \|\dot{\gamma}\|_{L_2} + \|\dot{\tilde{\gamma}} - \dot{\gamma}\|_{L_2} \leq \|\dot{\gamma}\|_{L_2} + \kappa_1 \|\bar{\varphi}_1 - \bar{\varphi}\|_{W^{1,2}}.$$

$$(iv) \quad \|f(\tilde{\gamma}_t)\|_{L_2} \leq \|f(\gamma_t)\|_{L_2} + \kappa_2 \|\bar{\varphi}_1 - \bar{\varphi}\|_{L_2}.$$

From these estimates and supposing  $\|\bar{\varphi}_1 - \bar{\varphi}\|_{W^{1,2}} < 1$ , we get the final estimate

$$S_{OT}(\tilde{\gamma}) - S_{OT}(\gamma) \leq \kappa \|\bar{\varphi}_1 - \bar{\varphi}\|_{W^{1,2}}$$

where  $\kappa = \frac{1}{2}(\kappa_1 + \kappa_2) \cdot (\kappa_1 + \kappa_2 + 2\|\dot{\gamma}\|_{L_2} + 2\|f(\gamma_t)\|_{L_2})$ .

Suppose we have the conditions of Lemma III.2 and suppose also that the quasipotential  $V(\varphi)$  verifies the condition:

there exists a unique  $\bar{\varphi}_0 \in \partial D$  such that  $V(\bar{\varphi}_0) = \min\{V(\bar{\varphi}) : \bar{\varphi} \in \partial D\}$ .

For any given  $\delta > 0$ , define  $d$  as the positive number

$$d = \min\{V(\bar{\varphi}) : \bar{\varphi} \in \partial D, \|\bar{\varphi} - \bar{\varphi}_0\|_{W^{1,2}} \geq \delta\} - V(\bar{\varphi}_0).$$

We choose  $\mu > 0$ ,  $\mu < \frac{d}{5 \max\{K, L\}}$ , where  $K$  and  $L$  are the

constants given by Lemma II.3, such that  $B_\mu(0) \subset D$ . Let us denote by  $S^r$  the sphere with center  $O$  and radius  $r$ .

Following F-W, we consider the following sequence of Markov times:  $\tau_0 = 0$ ,  $\sigma_0 = \inf\{t > \tau_0 : x_t^E \in S^\mu\}$ ,  $\tau_1 = \inf\{t > \sigma_0 : x_t^E \in \partial D \cup S^{\mu/2}\}$ , ...,  $\sigma_n = \inf\{t > \tau_n : x_t^E \in S^\mu\}$ ,  $\tau_{n+1} = \inf\{t > \sigma_n : x_t^E \in \partial D \cup S^{\mu/2}\}$ .

III.4. Lemma - For any given  $\epsilon > 0$  sufficiently small, we have, for all  $\varphi \in S^{\mu/2}$ :

$$(a) \quad P_{\varphi}\{X_{T_1}^{\epsilon} \in \partial D\} \geq \exp\{-\epsilon^{-2}(V(\bar{\varphi}_0) + 0,45d)\}.$$

$$(b) \quad P_{\varphi}\{X_{T_1}^{\epsilon} \in \partial D \setminus B_{\delta}(\bar{\varphi}_0)\} \leq \exp\{-\epsilon^{-2}(V(\bar{\varphi}_0) + 0,55d)\}.$$

Proof: (a) We take  $\bar{\varphi}_1$  out of  $\bar{D}$  such that  $\|\bar{\varphi}_1 - \bar{\varphi}\|_{W^{1,2}} \leq \frac{\mu}{4}$  and choose initially, using the fact that  $\bar{\varphi}_0$  is a minimum point of  $V$  on  $\partial D$ , a path  $\gamma^{(1)} \in W^{1,2}[-1, T_1] \rightarrow \mathbb{R}^n$  such that  $\gamma^{(1)}(t) = 0$  for  $t \in [-1, 0]$ ,  $\gamma_{T_1}^{(1)} = \bar{\varphi}_0$  and  $S_{0T_1}(\gamma^{(1)}) \leq V(\bar{\varphi}_0) + 0,05d$ .

Using Lemma III.3 (b), we can find a path  $\tilde{\gamma}^{(1)} \in W^{1,2}[-1, T_1] \rightarrow \mathbb{R}^n$  such that  $\tilde{\gamma}^{(1)}(t) = 0$  for  $t \in [-1, 0]$ ,  $\tilde{\gamma}_{T_1}^{(1)} = \bar{\varphi}_1$  and

$$S_{0T_1}(\tilde{\gamma}^{(1)}) \leq V(\bar{\varphi}_0) + 0,1 d.$$

Let  $t_1 = \max\{t > 0: \tilde{\gamma}^{(1)}(t) \in S^{\mu}\}$  and let  $\psi_1 = \tilde{\gamma}_{t_1}^{(1)}$ . Denote by  $\tilde{\gamma}^{(2)} \in W^{1,2}[-1, T_1 - t_1]$  the path given by  $\tilde{\gamma}^{(2)}(t) = \psi_1(t)$  for  $t \in [-1, 0]$  and  $\tilde{\gamma}^{(2)}(t) = \tilde{\gamma}^{(1)}(t - t_1)$  for  $t \in [0, T_2]$ , where  $T_2 = T_1 - t_1$ .

$$\text{Then, } S_{0T_2}(\tilde{\gamma}^{(2)}) \leq V(\bar{\varphi}_0) + 0,1 d.$$

By Lemma III.3.(a), we can find a path  $\tilde{\gamma}^{(3)} \in W^{1,2}[-1, T_3]$  such that  $\tilde{\gamma}_0^{(3)} = 0$ ,  $\tilde{\gamma}_{T_3}^{(3)} = \psi_1$  and  $S_{0T_3}(\tilde{\gamma}^{(3)}) \leq 0,2 d$ ; by the same argument, for each  $\varphi \in S^{\mu/2}$ , we can find a path  $\tilde{\gamma}^{(4)} \in W^{1,2}[-1, T_4]$  such that  $\tilde{\gamma}_0^{(4)} = 0$ ,  $\tilde{\gamma}_{T_4}^{(4)} = \tilde{\varphi}$  and  $S_{0T_4}(\tilde{\gamma}^{(4)}) \leq 0,1 d$ , where  $\tilde{\varphi}$  is defined by  $\tilde{\varphi}(\theta) = \varphi(-1 - \theta)$ ,  $\theta \in [-1, 0]$ .

We construct now the path  $\gamma^{\varphi} \in W^{1,2}[-1, T]$  where  $T = T_1 + T_2 + T_3$  by  $\gamma^{\varphi}(t) = \tilde{\gamma}^{(4)}(T_4 - 1 - t)$  for  $t \in [-1, 0]$ ,  $\gamma^{\varphi}(t) = \tilde{\gamma}^{(3)}(t)$  for

$t \in [0, T_3]$ ,  $\gamma^\varphi(t) = \gamma^{(2)}(t - T_3)$  for  $t \in [T_3, T_3 + T_2]$  and finally,  $\gamma^\varphi(t) = \gamma^{(1)}(t - T_3 - T_2)$  for  $t \in [T_3 + T_2, T]$ . Then,  $\gamma_0^\varphi = \varphi$ ,  $\gamma_T^\varphi = \bar{\varphi}_1$  and

$$S_{0T}(\gamma^\varphi) \leq V(\bar{\varphi}_0) + 0,4 d.$$

We choose now  $\delta' < \min\{\frac{\mu}{4}, \text{dist}(\bar{\varphi}_1, \partial D)\}$ . We know that [F-V] there exists an  $\epsilon > 0$  such that for any  $\varphi \in S^{\mu/2}$  we have

$$P_\varphi \left\{ \sup_{t \in [-1, T]} |x^\epsilon(t) - \gamma^\varphi(t)| < \delta' \right\} \geq \exp \left\{ -\epsilon^{-2}(V(\bar{\varphi}_0) + 0,45d) \right\}$$

Since

$$\left\{ \omega \in \Omega : x_{\tau_1}^\epsilon \in \partial D \right\} \supset \left\{ \omega \in \Omega : \sup_{t \in [-1, T]} |x^\epsilon(t) - \gamma^\varphi(t)| < \delta' \right\}$$

it results

$$P_\varphi \left\{ x_{\tau_1}^\epsilon \in \partial D \right\} \geq \exp \left\{ -\epsilon^{-2}(V(\bar{\varphi}_0) + 0,45d) \right\}$$

which concludes the proof.

(b) As in [F-V] define  $\tau(S^{\mu/2} \cup \partial D) = \inf \{t > 0 : x_t^\epsilon \in S^{\mu/2} \cup \partial D\}$ .

Then,  $\tau(S^{\mu/2} \cup \partial D) \leq \tau_1$  and

$$x^\epsilon(\tau_1, 0, \varphi) = x^\epsilon(\tau(S^{\mu/2} \cup \partial D), 0, x^\epsilon(\sigma_0, 0, \varphi)).$$

Now, for any  $\varphi \in S^{\mu/2}$  there exists  $\hat{\varphi} \in S^\mu$  such that

$$\left\{ \omega \in \Omega : X^\varepsilon(\tau_1, 0, \varphi) \in \partial D \setminus B_\delta(\bar{\varphi}_0) \right\} =$$

$$= \left\{ \omega \in \Omega : X^\varepsilon(\tau(S^{\mu/2} \cup \partial D), 0, \hat{\varphi}) \in \partial D \setminus B_\delta(\bar{\varphi}_0) \right\} ;$$

then, 
$$P_\varphi \left\{ X^\varepsilon_{\tau_1} \in \partial D \setminus B_\delta(\bar{\varphi}_0) \right\} \leq \sup_{\hat{\varphi} \in S^\mu} P_{\hat{\varphi}} \left\{ X^\varepsilon_{\tau(S^{\mu/2} \cup \partial D)} \in \partial D \setminus B_\delta(\bar{\varphi}_0) \right\} .$$

We majorize this last quantity. First, note that for any  $T$  we have: the set

$$\left\{ \omega \in \Omega : X^\varepsilon_{\tau(S^{\mu/2} \cup \partial D)} \in \partial D \setminus B_\delta(\bar{\varphi}_0) \right\}$$

is contained in the union  $\left\{ \omega \in \Omega : \tau(S^{\mu/2} \cup \partial D) > T \text{ and}$

$$X^\varepsilon_{\tau(S^{\mu/2} \cup \partial D)} \in \partial D \setminus B_\delta(\bar{\varphi}_0) \right\} \cup \left\{ \omega \in \Omega : \tau(S^{\mu/2} \cup \partial D) \leq T \text{ and}$$

$$X^\varepsilon_{\tau(S^{\mu/2} \cup \partial D)} \in \partial D \setminus B_\delta(\bar{\varphi}_0) \right\} ;$$

therefore

$$P_{\hat{\varphi}} \left\{ X^\varepsilon_{\tau(S^{\mu/2} \cup \partial D)} \in \partial D \setminus B_\delta(\bar{\varphi}_0) \right\} \leq P_{\hat{\varphi}} \left\{ \tau(S^{\mu/2} \cup \partial D) > T \right\} +$$

$$P_{\hat{\varphi}} \left\{ \tau(S^{\mu/2} \cup \partial D) \leq T \text{ and } X^\varepsilon_{\tau(S^{\mu/2} \cup \partial D)} \in \partial D \setminus B_\delta(\bar{\varphi}_0) \right\} .$$

By Lemma III.3.(b), there exist constants  $c > 0$  and  $T_0$  such that for any  $\varepsilon > 0$  small enough and any  $\hat{\varphi} \in S^\mu$  we have

$$P_{\hat{\varphi}} \left\{ \zeta_{\delta} > T \right\} \leq \exp \left\{ -\varepsilon^{-2} \cdot c \right\}$$

where  $\zeta_{\delta} = \inf \left\{ t: X_t^{\varepsilon} \notin D \setminus B_{\delta}(0) \right\}$ ; since  $\tau(S^{\mu/2} \cup \partial D) \leq \zeta_{\delta}$  we have also

$$\left\{ \omega \in \Omega: \tau(S^{\mu/2} \cup \partial D) > T \right\} \subset \left\{ \omega \in \Omega: \zeta_{\delta} > T \right\}$$

and

$$P_{\hat{\varphi}} \left\{ \tau(S^{\mu/2} \cup \partial D) > T \right\} \leq \exp \left\{ -\varepsilon^{-2} c \right\}.$$

Making  $c = V(\bar{\varphi}_0) + d$  we can write

$$P_{\hat{\varphi}} \left\{ \tau(S^{\mu/2} \cup \partial D) > T \right\} \leq \exp \left\{ -\varepsilon^{-2} (V(\bar{\varphi}_0) + d) \right\}.$$

Let now  $K$  be the closure of the  $\mu/2$  - neighbourhood of  $\partial D \setminus B_{\delta}(\bar{\varphi}_0)$ . We prove that no path  $\gamma \in W^{1,2}[-1, T]$  such that  $\gamma_0 = \hat{\varphi} \in S^{\mu}$  and action  $S_{0T}(\gamma) \leq V(\bar{\varphi}_0) + 0,65d$  reaches  $K$ . In fact, suppose by contradiction that there exists  $t_1 \in [0, T]$ , such that  $\gamma_{t_1} \in K$ . Then,  $S_{0t_1}(\gamma) \leq V(\bar{\varphi}_0) + 0,65d$ . By Lemma III.3.(a), we can construct a path  $\gamma^{(1)} \in W^{1,2}[0, T_1]$  such that  $\gamma_0^{(1)} = 0$ ,  $\gamma_{T_1}^{(1)} = \hat{\varphi}$  and  $S_{0T_1}(\gamma^{(1)}) \leq L \|\hat{\varphi}\|_{W^{1,2}} \leq 0,2d$ .

Let  $\bar{\gamma}$  be the path given by  $\bar{\gamma}(t) = 0$  for  $t \in [-1, 0]$ ,  $\bar{\gamma}(t) = \gamma^{(1)}(t)$  for  $t \in [0, T_1]$  and  $\bar{\gamma}(t) = \gamma(t - T_1)$  for  $t \in [T_1, T_1 + t_1]$ . Then,  $\bar{\gamma}_0 = 0$ ,  $\bar{\gamma}_{T_1 + t_1} = \gamma_{t_1} \in K$  and

$$S_{0(T_1 + t_1)}(\bar{\gamma}) \leq V(\bar{\varphi}_0) + 0,85d.$$

By Lemma III.3.(b), we can find a path  $\tilde{\gamma} \in W^{1,2}[0, T_1+t_1]$  such that  $\tilde{\gamma}_0 = 0$ ,  $\tilde{\gamma}_{t_1+T_1} = \hat{\psi} \in \partial D \setminus B_\delta(\bar{\varphi}_0)$  (for  $\hat{\psi}$  in the open ball  $B_{\mu/2}(\gamma_{t_1})$ ) and such that  $S_0(T_1+t_1)(\tilde{\gamma}) \leq S_0(T_1+t_1)(\bar{\gamma}) + K\|\psi-\gamma_{t_1}\|_{W^{1,2}} = V(\bar{\varphi}_0) + 0,85d + K\|\psi-\gamma_{t_1}\| \leq V(\bar{\varphi}_0) + 0,95d$ .

Now, this implies that  $V(\hat{\psi}) \leq V(\bar{\varphi}_0) + 0,95d$  which is not possible by the definition of the number  $d$  since  $\hat{\psi} \in \partial D \setminus B_\delta(\bar{\varphi}_0)$ .

Therefore, all the paths  $\gamma$  in the set  $\bigcup_{\hat{\varphi} \in S^\mu} \hat{\varphi}(V(\bar{\varphi}_0) + 0,65d)$  satisfy

$$\text{dist}(\gamma_t, \partial D \setminus B_\delta(\bar{\varphi}_0)) \geq \frac{\mu}{2}$$

and then

$$P_{\hat{\varphi}} \left\{ \tau(S^{\mu/2} \cup \partial D) \leq T, X^\varepsilon_{\tau(S^{\mu/2} \cup \partial D)} \in \partial D \setminus B_\delta(\bar{\varphi}_0) \right\} \leq P_{\hat{\varphi}} \left\{ \text{dist}(X^\varepsilon, \hat{\varphi}(V(\bar{\varphi}_0) + 0,65d)) \geq \frac{\mu}{2} \right\}.$$

This last quantity is, by Theorem 1.1, less or equal to  $\exp\{-\varepsilon^{-2}(V(\bar{\varphi}_0) + 0,65d - 0,05d)\}$  if  $\varepsilon$  is small enough.

Collecting the estimates above we can assert that, for any  $\hat{\varphi} \in S^\mu$ , we have:

$$P_{\hat{\varphi}} \left\{ X^\varepsilon_{\tau(S^{\mu/2} \cup \partial D)} \in \partial D \setminus B_\delta(\bar{\varphi}_0) \right\} \leq \exp\left\{-\varepsilon^{-2}(V(\bar{\varphi}_0)+d)\right\} + \exp\left\{-\varepsilon^{-2}(V(\bar{\varphi}_0) + 0,6d)\right\} \leq \exp\left\{-\varepsilon^{-2}(V(\bar{\varphi}_0) + 0,55d)\right\},$$

which finishes the proof.

Let us proof now Theorem I.2.

It follows from Lemma III.4 that for any  $\varphi \in S^{\mu/2}$  and  $\epsilon > 0$  small enough:

$$(*) \quad \frac{P_{\varphi} \left\{ X_{\tau_1} \in \partial D \setminus B_{\delta}(\bar{\varphi}_0) \right\}}{P_{\varphi} \left\{ X_{\tau_1} \in \partial D \right\}} \leq \frac{\exp \{-\epsilon^{-2}(v(\bar{\varphi}_0) + 0,55d)\}}{\exp \{-\epsilon^{-2}(v(\bar{\varphi}_0) + 0,45d)\}}.$$

Let  $v$  be the minimum integer  $n$  for which  $Z_n \in \partial D$ , where  $Z_n = X_{\tau_n}^{\epsilon}$ . Then, for any  $\epsilon \in S^{\mu/2}$ :

$$P_{\varphi} \left\{ \left\| X_{\tau_n}^{\epsilon} - \bar{\varphi}_0 \right\| \geq \delta \right\} = P_{\varphi} \left\{ Z_v \in \partial D \setminus B_{\delta}(\bar{\varphi}_0) \right\},$$

and, since the set  $\{\omega \in \Omega: Z_{v(\omega)}(\omega) \in \partial D \setminus B_{\delta}(\bar{\varphi}_0)\}$  is equal to the union  $\bigcup_{n=1}^{\infty} \{\omega \in \Omega: v(\omega)=n, Z_n \in \partial D \setminus B_{\delta}(\bar{\varphi}_0)\}$ , we can write

$$\begin{aligned} P_{\varphi} \{Z_v \in \partial D \setminus B_{\delta}(\bar{\varphi}_0)\} &= \sum_{n=1}^{\infty} P_{\varphi} \{v=n, Z_n \in \partial D \setminus B_{\delta}(\bar{\varphi}_0)\} \\ &= \sum_{n=1}^{\infty} \int_{A_n} P_{Z_{n-1}} \{Z_1 \in \partial D \setminus B_{\delta}(\bar{\varphi}_0)\}, \end{aligned}$$

where  $A_n = \{\omega \in \Omega: Z_1 \in S^{\mu/2}, \dots, Z_{n-1} \in S^{\mu/2}\}$ .

From the inequality (\*), we have

$$P_{\varphi} \{Z_v \in \partial D \setminus B_{\delta}(\bar{\varphi}_0)\} \leq \sum_{n=1}^{\infty} \int_{A_n} P_{Z_{n-1}} \{Z_1 \in \partial D\} \cdot \exp\{-\epsilon^{-2} \cdot 0,1d\}$$

$$\begin{aligned}
&= \sum_{n=1}^{\infty} P_{\varphi}\{v=n\} \cdot \exp\{-\epsilon^{-2}0,1d\} \\
&= \exp\{-\epsilon^{-2}0,1d\}.
\end{aligned}$$

It follows that, for  $\epsilon \rightarrow 0$ , we have

$$P_{\varphi} \left\{ \left\| X_{\tau^{\epsilon}}^{\epsilon} - \bar{\varphi}_0 \right\| \geq \delta \right\} \rightarrow 0$$

for any  $\varphi \in S^{\mu/2}$ . Now, for any  $\varphi \in D$ :

$$\begin{aligned}
P_{\varphi} \left\{ \left\| X_{\tau^{\epsilon}}^{\epsilon} - \bar{\varphi}_0 \right\| \geq \delta \right\} &= P_{\varphi} \left\{ \left\| X_{\tau^{\epsilon}}^{\epsilon} - \bar{\varphi}_0 \right\| \geq \delta, \tau(S^{\mu/2} \cup \partial D) = \tau^{\epsilon} \right\} + \\
&P_{\varphi} \left\{ \left\| X_{\tau^{\epsilon}}^{\epsilon} - \bar{\varphi}_0 \right\| \geq \delta, \tau(S^{\mu/2} \cup \partial D) < \tau^{\epsilon} \right\}
\end{aligned}$$

Therefore, the probability  $P_{\varphi} \left\{ \left\| X_{\tau^{\epsilon}}^{\epsilon} - \bar{\varphi}_0 \right\| \geq \delta \right\}$  is less than

$$P_{\varphi} \left\{ X_{\tau(S^{\mu/2} \cup \partial D)}^{\epsilon} \in \partial D \right\} + P_{\tau} \left\{ \left\| X_{\tau^{\epsilon}}^{\epsilon} - \bar{\varphi}_0 \right\| \geq \delta, X_{\tau(S^{\mu/2} \cup \partial D)}^{\epsilon} \in S^{\mu/2} \right\}.$$

The first probability of this sum, by Lemma III.1, tends to zero as  $\epsilon \rightarrow 0$ , for any  $\varphi \in S^{\mu/2}$ . Also,

$$\begin{aligned}
&P_{\varphi} \left\{ \left\| X_{\tau^{\epsilon}}^{\epsilon} - \bar{\varphi}_0 \right\| \geq \delta, X_{\tau(S^{\mu/2} \cup \partial D)}^{\epsilon} \in S^{\mu/2} \right\} = \\
&= \int_A P_{X_{\tau(S^{\mu/2} \cup \partial D)}^{\epsilon}} \left\{ \left\| X_{\tau^{\epsilon}}^{\epsilon} - \bar{\varphi}_0 \right\| \geq \delta \right\}
\end{aligned}$$

where

$$\lambda = \left\{ x^\epsilon \int_{\tau(S^{\mu/2} \cup \partial D)} \epsilon S^{\mu/2} \right\}$$

and this last integral is  $\leq \exp(-\epsilon^{-2} \cdot 0,1d)$ , which also goes to zero as  $\epsilon \rightarrow 0$ .

This finishes the proof of the Theorem.

#### IV. Example

Let us apply the foregoing results to the problem of exit from a domain attracted to 0, in the case of the dynamical system defined by the scalar linear retarded differential difference equation:

$$(4.0) \quad \dot{x}(t) = -x(t-b).$$

We know [Ha] that the condition  $0 < b < \frac{\pi}{2}$  is a necessary and sufficient condition to ensure that 0 is an asymptotically stable equilibrium of Eq. (4.0); in fact, this condition is equivalent to assume that all roots of the characteristic equation

$$\lambda + e^{-\lambda b} = 0$$

verify  $\text{Re} \lambda < 0$ .

The action functional corresponding to equation (4.0) is given by

$$(4.1) \quad S_T(\gamma) = \frac{1}{2} \int_{-T}^b \left( \dot{\gamma}(t) + \gamma(t-b) \right)^2 dt$$

and the Euler-Lagrange equations for the extremals of  $S$  are given by

$$(4.2.1) \quad \dot{\gamma}(t) + \gamma(t-b) = H(t), \quad t \in (-T, b)$$

$$(4.2.2) \quad \dot{H}(t) - H(t+b) = 0, \quad t \in (-T, 0]$$

We will compute the quasipotential of equation (4.1) with respect to the origin.

As noted before we may suppose that  $T = \infty$ .

Equation (4.2.2) is an advanced difference-differential equation, which becomes a retarded equation by performing the change of independent variable  $t \mapsto -t$ . Therefore, by [B-T], given  $\psi \in L_2[-b, 0]$ , and  $\xi \in \mathbb{R}$ , we can solve (4.2.2) to find a unique function  $H: (-\infty, b] \rightarrow \mathbb{R}$  which satisfies: 1°)  $H(b+\theta) = \psi(\theta)$  for almost all  $\theta \in [-b, 0]$ ; 2°)  $H(0) = \xi$ ; 3°)  $H$  is absolutely continuous on  $(-\infty, 0]$ , and, 4°) for almost all  $t$  in  $(-\infty, 0]$ ,  $\dot{H}(t) = H(t+b)$ .

With  $H = H(t, \xi, \psi)$  so determined, we solve Eq. (4.2.1) in  $(-\infty, 0]$  with initial condition  $\gamma_{-} = 0$ . We get a function  $\gamma: (-\infty, +b] \rightarrow \mathbb{R}$  which is absolutely continuous on  $(-\infty, 0]$ .

Of course,  $\gamma$  depends upon  $\psi$  and  $\xi$ ; the relations

$$(4.3) \quad \gamma_b = \varphi, \quad \varphi \in W^{1,2}$$

allow us determine  $\psi$  and  $\xi$  uniquely in function of  $\varphi$ . In fact, from the variation of constants formula [Ha], we have

$$(4.4) \quad \gamma(t) = \int_{-\infty}^t x(t-s)H(s, \psi, \xi) ds, \quad t \in (-\infty, b],$$

where  $X$  is the fundamental solution:

$$\dot{X}(t) = -X(t-b), \quad t > 0$$

$$X(0) = 1$$

$$X(t) = 0, \quad t < 0.$$

Given  $\psi \in L_2$ , let  $J(t)$  be the solution of  $\dot{J}(t) = -J(t-b)$ ,  $t > 0$ ,  $J(0) = 0$ ,  $J_0 = \tilde{\psi}$ , where  $\tilde{\psi}$  is defined by  $\tilde{\psi}(\theta) = \psi(-b-\theta)$  for all  $\theta \in [-b, 0]$ .

It is easy to see that

$$J(t) = \int_{-b}^0 x(t+u)\psi(u)du, \quad t > 0$$

and that

$$H(t, \psi, \xi) = x(-t)\xi + J(-t), \quad t \in (-\infty, 0).$$

By equation (4.2.1) we have for  $t \in [-b, 0]$ :

$$\psi(t-b) = \dot{\varphi}(t-b) + \int_{-\infty}^{t-b} x(t-b-s) \left[ x(-s)\xi + \int_{-b}^0 x(-s+u)\psi(u)du \right] dt$$

or

$$(4.5) \quad \psi(\theta) = \dot{\varphi}(\theta) + \int_{-\theta}^{\infty} x(t+\theta)x(t)dt\xi + \int_{-b}^0 \left[ \int_{-\theta}^{\infty} x(t+\theta)x(t+u)dt \right] \psi(u)du$$

Define the function  $a(\theta)$ ,  $\theta \in [-b, 0]$ , by

$$a(\theta) = \int_0^{\infty} x(t-\theta)x(t)dt.$$

Then, we can write equation (4.4) as

$$(4.6) \quad \psi(\theta) = \dot{\varphi}(\theta) + a(\theta)\xi + \int_{-b}^0 a(-|\theta-u|)\psi(u)du$$

Letting  $t = 0$  in equation (4.4), we get

$$(4.7) \quad \varphi(-b) = a(0)\xi + \int_b^0 a(u)\psi(u)du.$$

Since  $a(0) > 0$ , we can solve Eq. (4.7) for  $\xi$  so that equation (4.6) can be written as

$$(4.8) \quad \psi(\theta) = \dot{\varphi}(\theta) + \frac{a(\theta)}{a(0)} \varphi(-b) + \int_{-b}^0 K(\theta,u)\psi(u)du$$

$$\text{where } K(\theta,u) = a(-|\theta-u|) - \frac{a(\theta)a(u)}{a(0)}.$$

We now compute the function  $a(\theta)$ .

It follows from the definition that

$$\dot{a}(\theta) = - \int_0^{\infty} \dot{x}(t-\theta)x(t)dt = \int_0^{\infty} x(t-\theta-b)x(t)dt = a(-b-\theta).$$

Therefore,  $\ddot{a}(\theta) = -a(\theta)$  and there exist constants  $c_1$  and  $c_2$  such that

$$a(\theta) = c_1 \cos \theta + c_2 \sin \theta.$$

From the equation  $\dot{a}(\theta) = a(-b-\theta)$  it follows that

$$a(\theta) = \frac{a(0)}{\cos \beta} \cos(\theta - \beta)$$

where  $\beta = \frac{\pi}{4} - \frac{b}{2}$ .

Now,  $a(-b) = \int_0^{\infty} X(t+b)X(t)dt = \frac{1}{2}$  so that

$$a(0) = \frac{1 + \operatorname{sen} b}{2 \cos b} \text{ and finally}$$

$$a(\theta) = \frac{1 + \operatorname{sen} b}{2 \cos b \cos \beta} \cos(\theta - \beta).$$

Also, the kernel  $K(\theta, u)$  has the expression

$$K(\theta, u) = - \frac{\cos(\theta+b) \operatorname{sen} u}{\cos b} \text{ for } -b \leq \theta \leq u \leq 0$$

$$K(\theta, u) = - \frac{\cos(u+b) \operatorname{sen} \theta}{\cos b} \text{ for } -b \leq u \leq \theta \leq 0.$$

Equation (4.8) now becomes

$$(4.9) \quad \psi(\theta) = \ddot{\varphi}(\theta) - \frac{\cos(\theta-b)}{\cos b} \psi(-b) - \int_{-b}^{\theta} \frac{\operatorname{sen} u}{\cos b} \cos(u+b) \psi(u) du - \int_{\theta}^0 \frac{\cos(\theta+b) \operatorname{sen} u}{\cos b} \psi(u) du.$$

We prove now that 1 is not an eigenvalue of the operator  $k$  defined by

$$(k \psi)(\theta) = \int_{-b}^0 K(\theta, u) \psi(u) du.$$

Suppose that  $k\psi = \psi$ . Then,

$$\psi(0) = 0 \quad \text{and} \quad \dot{\psi}(-b) = 0 \quad \text{and} \quad \ddot{\psi} + 2\psi = 0.$$

$$\text{Hence, } \psi(\theta) = c_1 \cos \sqrt{2} \theta + c_2 \sin \sqrt{2} \theta.$$

The condition  $\psi(0) = 0$  implies  $c_1 = 0$  and the condition  $\dot{\psi}(-b) = 0$  implies that  $c_2 = 0$ . Hence,  $\psi \equiv 0$ .

Since the operator  $k$  is compact, and  $1 \notin \sigma(k)$  equation (4.9) has a unique solution  $\psi$  for each  $\varphi \in W^{1,2}$ .

We now compute the quasipotential relative to the origin.

From what has been proved above, the quasipotential  $V(\varphi)$  is given by

$$V(\varphi) = \frac{1}{2} \int_{-\infty}^b |\dot{\gamma}(t) + \gamma(t-b)|^2 dt$$

where  $\gamma(t) = x(-t)$ , where  $x(t)$  is the solution of  $\dot{x}(t) = -x(t-b)$ ,  $t > 0$ ,  $x_0 = \bar{\varphi}$ . In fact,  $\gamma_b = \varphi$  and  $\gamma_{-\infty} = 0$  and  $\gamma$  satisfies the variational equations (4.2.1) and (4.2.2).

$$\text{We have } V(\varphi) = \frac{1}{2} \int_{-b}^{\infty} |\dot{x}(t) - x(t+b)|^2 dt,$$

$$V(\varphi) = \frac{1}{2} \int_{-b}^{\infty} |\dot{x}(t)|^2 dt - \int_{-b}^{\infty} \dot{x}(t)x(t+b) dt + \frac{1}{2} \int_{-b}^{\infty} |x(t+b)|^2 dt$$

$$= \frac{1}{2} \int_{-b}^0 |\dot{\varphi}(\theta)|^2 dt + \frac{1}{2} \int_0^{\infty} |x(t-b)|^2 dt$$

$$- [x(t)x(t+b)]_{-b}^{\infty} - \int_{-b}^{\infty} x(t)\dot{x}(t+b) dt + \frac{1}{2} \int_{-b}^{\infty} |x(t+b)|^2 dt$$

$$= \frac{1}{2} \int_{-b}^0 |\varphi(\theta)|^2 d\theta - \frac{1}{2} \int_{-b}^0 |\varphi(\theta)|^2 d\theta + \varphi(0)\varphi(-b).$$

From the Cauchy-Schwarz inequality one can prove that, if  $b \in (0, 1/2)$ , then

$$V(\varphi) \geq \left(\frac{1}{2} - b\right) \|\varphi\|_{1,2}^2$$

which shows that  $\sqrt{V}$  is a norm on  $W^{1,2}$ , equivalent to the natural norm.

If we take  $D$  as the open ball with respect to the norm  $\sqrt{V}$ , with center  $c$  and radius  $R$ , where  $c$  and  $R$  are positive constants,  $c < R$ , then, theorem I.2 can be applied to the perturbed system

$$\dot{x}(t) = -x(t-b) + c \dot{w}(t).$$

In fact, the minimum of  $V(\varphi)$  on  $\partial D = \{\varphi \in W^{1,2} : V(\varphi-c) = R^2\}$  is achieved only at the point  $\varphi = R + c$ .

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