

ON LINEAR KURZWEIL-HENSTOCK-INTEGRAL EQUATIONS

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Abstract

We give a Riemann-Stieltjes integral representation theorem for the elements of $L(\mathcal{C}([a,b],X),Y)$; this theorem completes a result of J. Batt and H. König [2]. We apply our result to obtain an integral representation for the elements of $L(K([a,b],X),\mathcal{C}([c,d],Y))$ where $K([a,b],X)$ denotes the space of all functions $f:[a,b] \rightarrow X$ that are integrable in the sense of Kurzweil-Henstock. This normed space is not complete but it is ultrabornological. This representation theorem is applied to study the corresponding linear Fredholm-Kurzweil and Volterra-Kurzweil integral equations

$$(F) \quad x(t) - K \int_a^b \alpha(t,s) \cdot x(s) ds = f(t), \quad a \leq t \leq b, \quad \text{and}$$

$$(V) \quad x(t) - K \int_a^t \alpha(t,s) \cdot x(s) ds = f(t), \quad a \leq t \leq b.$$

We prove that if for every $f \in K([a,b],X)$ the equation (F) has one and only one solution $x_f \in K([a,b],X)$ then the application $f \mapsto x_f$ is bicontinuous and (F) has a resolvent that has a similar integral representation. For equation (V) we prove that for every $f \in K([a,b],X)$ it has one and only one solution $x_f \in K([a,b],X)$ and that the resolvent of (V) is given by the Neumann series.

1. The Riemann-Stieltjes integral and representation theorems

X, Y, Z always denote real normed spaces that are supposed to be complete unless otherwise stated. All results are still true for complex vector spaces. We denote by $L(X,Y)$ the Banach space of all

linear continuous applications $P: X \rightarrow Y$. We write $X' = L(X, R)$ and I_X or I denotes the identical application of X . $\mathcal{C}([a, b], X)$ or simply $\mathcal{C}$ denotes the Banach space of all functions $f: [a, b] \rightarrow X$ that are continuous and $\|f\| = \sup_{a \leq t \leq b} \|f(t)\|$. For a function $\alpha: [a, b] \rightarrow L(X, Y)$ we denote by $SV_{[a, b]}[\alpha]$ or $SV[\alpha]$ the smallest element $c \in [0, \infty]$ such that for every division

$$t_0 = a < t_1 < t_2 < \dots < t_n = b$$

of $[a, b]$ and for all $x_i \in X$ we have

$$\left\| \sum_{i=1}^n [\alpha(t_i) - \alpha(t_{i-1})] \cdot x_i \right\| \leq c \sup_{1 \leq i \leq n} \|x_i\|$$

If $SV[\alpha] < \infty$ we say that α is a function of bounded semivariation (on $[a, b]$) and we write $\alpha \in SV([a, b], L(X, Y))$ or simply $\alpha \in SV$. If we have furthermore $\alpha(c) = 0$, where $c \in [a, b]$, we write

$$\alpha \in SV_c([a, b], L(X, Y))$$

For the following results and for further informations see [2] and [10], Chapter I; see also [12].

1.1 a - $SV_c([a, b], L(X, Y))$ is a Banach space when endowed with the norm $\alpha \mapsto SV[\alpha]$.

b - For every $f \in \mathcal{C}([a, b], X)$ and $\alpha \in SV([a, b], L(X, Y))$ there exists the Riemann-Stieltjes integral.

$$\int_a^b d\alpha(t) \cdot f(t) = \lim \sum_{i=1}^n [\alpha(t_i) - \alpha(t_{i-1})] \cdot f(\xi_i), \quad \xi_i \in [t_{i-1}, t_i],$$

where $\lim$ denotes that we take $\sup_{1 \leq i \leq n} |t_i - t_{i-1}| \rightarrow 0$. We write

$$F_\alpha(f) = \int_a^b d\alpha(t) \cdot f(t)$$

and we have $F_\alpha \in L[\mathcal{C}([a, b], X), Y]$ and $\|F_\alpha\| \leq SV[\alpha]$.

c - If $\alpha \in SV([a, b], L(X, Z'))$ [$\alpha \in SV([a, b], L(X, Y))$] then for every $t \in [a, b[$ there exists one and only one element $\alpha(t+) \in L(X, Z')$

$[\alpha(t^+) \in L(X, Y^n)]$ such that for every $x \in X$ and $z \in Z$ [$z \in Y'$] we have

$$\lim_{\varepsilon \downarrow 0} \langle \alpha(t+\varepsilon)x, z \rangle = \langle \alpha(t^+)x, z \rangle.$$

We define $\alpha^+(t) = \alpha(t^+)$ if $a < t < b$ and $\alpha^+(a) = \alpha(a)$. α^+ is of bounded semivariation and we write

$$\alpha^+ \in SV^+([a, b], L(X, Z'))$$

For every $f \in \mathcal{C}([a, b], X)$ we have $\int_a^b d\alpha^+(t) \cdot f(t) = \int_a^b d\alpha(t) \cdot f(t)$ and $\|F_\alpha\| = SV[\alpha^+]$.

1.2 (see [2], Satz 10 and [10], Theorem I.3.8) - The mapping

$$\alpha \in SV_c^+([a, b], L(X, Z')) \mapsto F_\alpha \in L[\mathcal{C}([a, b], X), Z']$$

is an isometry (i.e. $\|F_\alpha\| = SV[\alpha]$) of the first Banach space onto the second.

1.3 (see [10], corol. I.3.9) - For every $F \in L[\mathcal{C}([a, b], X), Y]$ there exists one and only one $\alpha \in SV_c^+([a, b], L(X, Y^n))$ such that $F = F_\alpha$. (The mapping $F \mapsto \alpha_F$ is not onto if $Y^n \neq Y$).

The next theorem completes 1.3 and characterizes the image of the mapping $F \mapsto \alpha_F$.

If $\alpha \in SV_b^+([a, b], L(X, Y^n))$ we write $\alpha \in SV_b^{+f}([a, b], L(X, \dot{Y}))$ if we have $\alpha(a) \in L(X, \dot{Y})$ and $\int_a^t \alpha(s)x ds \in Y$ for all $t \in [a, b]$ and $x \in X$.

Theorem 1.4 - The mapping

$$\alpha \in SV_b^{+f}([a, b], L(X, \dot{Y})) \mapsto F_\alpha \in L[\mathcal{C}([a, b], X), Y]$$

where $F_\alpha f = \int_a^b d\alpha(t) \cdot f(t)$, is an isometry (i.e. $\|F_\alpha\| = SV[\alpha]$) of the first Banach space onto the second. We have $\int_a^t \alpha(s)x ds = -F_\alpha(g_{t,x})$ and $\alpha(a)x = -F_\alpha(\chi_{[a,b]}x)$ where for $t \in [a, b]$ and $x \in X$ we define

$$g_{t,x}(s) = \begin{cases} (s-a)x & \text{if } a \leq s < t \\ (t-a)x & \text{if } t \leq s \leq b \end{cases}$$

Proof - 1) For $F \in L[\mathcal{C}([a,b], X), Y]$ let α be the corresponding element by 1.3. We have $\alpha \in SV_b^{+}([a,b], L(X, \dot{Y}))$: indeed, since $g_{t,x} \in \mathcal{C}([a,b], X)$ we have $F(g_{t,x}) \in Y$; but

$$F(g_{t,x}) = \int_a^b d\alpha(s) \cdot g_{t,x}(s) = - \int_a^b \alpha(s) \cdot dg_{t,x}(s) = - \int_a^t \alpha(s)x \, ds$$

where in the second equality we used the integration by parts formula for the Riemann-Stieltjes integral (with $\alpha(b) = 0$ and $g_{t,x}(a) = 0$). Analogously we have $F(\chi_{[a,b]}x) = -\alpha(a)x \in Y$.

2) On the other hand the functions $g_{t,x}$ and $\chi_{[a,b]}x$ ($t \in [a,b]$, $x \in X$) form a total subset of $\mathcal{C}([a,b], X)$; since SV_b^{+} is a closed subspace of SV_b^{+} it follows that the isometry is onto.

Remark: if $X = \mathbb{R}$ we have $\alpha(t+) = -\frac{d^+}{dt} F_\alpha(g_t) = -\lim_{\varepsilon \downarrow 0} \frac{1}{\varepsilon} F_\alpha(g_{t+\varepsilon} - g_t) = \frac{d^+}{dt} \int_a^t \alpha(s) \, ds$, $a \leq t < b$. If $\dim X = \infty$ the function α may not be differentiable (to the right or to the left) at any point. Example: take $X = Y = L_\infty([a,b])$ and $\alpha(t)x = \chi_{[t,b]}x$; see [11], p.14, Example 2. However for every $x \in X$ and $y \in Y$ we have $\langle \alpha(t), y \rangle = -\frac{d^+}{dt} \langle F_\alpha(g_{t,x}), y \rangle$ since the function $t \in [a,b] \mapsto \langle F_\alpha(g_{t,x}), y \rangle = -\int_a^t \langle \alpha(s)x, y \rangle \, ds$ is differentiable to the right (the numerical function $t \in [a,b] \mapsto \langle \alpha(t)x, y \rangle$ is of bounded variation and continuous to the right).

We define $\mathcal{C}_a([a,b], X) = \{f \in \mathcal{C}([a,b], X) \mid f(a) = 0\}$ and $SV_b^{+}([a,b], L(X, \dot{Y})) = \left\{ \alpha \in SV_b^{+}([a,b], L(X, \dot{Y})) \mid \begin{array}{l} \alpha(a+) = \alpha(a) \text{ instead} \\ \text{of } \alpha(a) \in L(X, Y) \end{array} \right\}$.

Theorem 1.5 - The mapping

$$\alpha \in SV_b^{+}([a,b], L(X, \dot{Y})) \mapsto F_\alpha \in L[\mathcal{C}_a([a,b], X), Y]$$

is an isometry of the first Banach space onto the second.

Proof - 1) The mapping is one-to-one: indeed, if α is such that $F_\alpha f = 0$ for every $f \in \mathcal{C}_a$, then for all $t \in [a, b]$, $x \in X$ and $y \in Y$ we have $0 = \langle F_\alpha(g_{t,x}), y \rangle = - \int_a^t \langle \alpha(s)x, y \rangle ds$ hence $\alpha = 0$ since we have, by hypothesis, $\alpha(s^+) = \alpha(s)$ for every $s \in [a, b[$.

2) The mapping is onto: indeed, for $\alpha \in SV_b^{+f}([a, b], L(X, \dot{Y}))$ we define $\alpha_a(a) = \alpha(a^+)$ and $\alpha_a(t) = \alpha(t)$ if $a < t \leq b$; we have $\alpha_a \in SV_b^{+f}([a, b], L(X, \dot{Y}))$ (since $\alpha_a(a^+) = \alpha_a(a)$) and for every $f \in \mathcal{C}_a$ we have $F_{\alpha_a}(f) = F_\alpha(f)$.

3) The isometry follows from Theorem 1.4.

For a function $\alpha: (t, s) \in T \times S \mapsto \alpha(t, s) \in Z$ we write

$$\alpha^t(s) = \alpha_s(t) = \alpha(t, s)$$

For a function $\alpha: [c, d] \times [a, b] \rightarrow L(X, Y'')$ we consider the following properties:

For $a \leq s \leq b$ ($s=a$) and $x \in X$ the function

$$(\tilde{\mathcal{C}}^\sigma)[(\tilde{G}^\sigma); (\tilde{L}_a^\sigma)]: t \in [c, d] \mapsto \int_a^b \alpha(t, \sigma)x d\sigma \in Y \quad (t \in [c, d] \mapsto \alpha(t, a)x \in Y)$$

is continuous [regulated; bounded and measurable]

We write $\alpha \in \tilde{\mathcal{C}}^\sigma \cdot SV_b^{+f}([c, d] \times [a, b], L(X, \dot{Y}))$ [$\tilde{G}^\sigma \cdot SV_b^{+f}u \dots; \tilde{L}_a^\sigma \cdot SV_b^{+f}u \dots$] if besides $(\tilde{\mathcal{C}}^\sigma)[(\tilde{G}^\sigma); (\tilde{L}_a^\sigma)]$ α satisfies

$$(SV_b^{+f}u): \quad \text{for every } t \in [c, d] \text{ we have } \alpha^t \in SV_b^{+f}([a, b], L(X, \dot{Y})) \\ \text{with } SV_b^u[\alpha] = \sup_{c \leq t \leq d} SV[\alpha^t] < \infty.$$

In an analogous way we define $\tilde{\mathcal{C}}^\sigma \cdot SV_b^{+f}u([c, d] \times [a, b], L(X, \dot{Y}))$ (we take $\alpha^t \in SV_b^{+f}([a, b], L(X, \dot{Y}))$) etc.

Theorem 1.6 - a) The mapping

$$\alpha \in \tilde{\mathcal{C}}^\sigma \cdot SV_b^{+f}u([c, d] \times [a, b], L(X, \dot{Y})) \mapsto F_\alpha \in L[\mathcal{C}([a, b], X), \mathcal{C}([c, d], Y)]$$

where $(F_\alpha f)(t) = \int_a^b d_g \alpha(t, s) \cdot f(s)$, $c \leq t \leq d$, is an isometry (i.e. $\|F_\alpha\| = SV^u[\alpha]$) of the first Banach space onto the second. We have $\int_a^b \alpha(t, s) x ds = -F_\alpha[g_{s,x}](t)$, $a \leq s \leq b$, and $\alpha(t, a)x = -F_\alpha[\chi_{[a,b]}x](t)$.

We have analogous results for the mappings

- b) $\alpha \in \tilde{G}^\sigma \cdot SV_b^{+f}([c,d] \times [a,b], L(X, \dot{Y})) \mapsto F_\alpha \in L(\mathcal{C}([a,b], X), G([c,d], Y))$
- c) $\alpha \in \tilde{L}_\infty^\sigma \cdot SV_b^{+f}([c,d] \times [a,b], L(X, \dot{Y})) \mapsto F_\alpha \in L(\mathcal{C}([a,b], X), L_\infty([c,d], Y))$
- d) $\alpha \in \tilde{C}^\sigma \cdot SV_b^{+f}([c,d] \times [a,b], L(X, \dot{Y})) \mapsto F_\alpha \in L(\mathcal{C}_a([a,b], X), \mathcal{C}([c,d], Y))$
- e) $\alpha \in \tilde{G}^\sigma \cdot SV_b^{+f}([c,d] \times [a,b], L(X, \dot{Y})) \mapsto F_\alpha \in L(\mathcal{C}_a([a,b], X), G([c,d], Y))$
- f) $\alpha \in \tilde{L}_\infty^\sigma \cdot SV_b^{+f}([c,d] \times [a,b], L(X, \dot{Y})) \mapsto F_\alpha \in L(\mathcal{C}_a([a,b], X), L_\infty([c,d], Y))$

The proof follows the steps of the proof of Theorem 1.5.10 of [11] (and the remark that follows it) p.49 to 52: the properties of F_α follow from the Theorem of Helly (see loc. cit.). Reciprocally given F for every $t \in [c,d]$ the continuous mapping $f \in \mathcal{C}([a,b], X) \mapsto (Ff)(t) \in Y$ [$f \in \mathcal{C}_a \mapsto (Ff)(t) \in Y$] is, by Theorem 1.4 [Theorem 1.5], represented by an $\alpha^t \in SV_b^{+f}([a,b], L(X, \dot{Y}))$ [$\alpha^t \in SV_b^{+f}([a,b], L(X, \dot{Y}))$] etc.

2. The Kurzweil-Henstock integral and representation theorems.

We say that a function $f: [a,b] \rightarrow X$ is integrable in the sense of Kurzweil-Henstock (we write $f \in \mathcal{K}([a,b], X)$ or $f \in \mathcal{K}$) and that $J \in X$ is its Kurzweil-Henstock integral (we write $\int_a^b f(t) dt = J$) if for every $\varepsilon > 0$ there exists a function $\delta: [a,b] \rightarrow]0, \infty[$ (called gauge function) such that for every tagged division (ξ_i, t_i) of $[a,b]$ (i.e. a division $t_0 = a < t_1 < t_2 < \dots < t_n = b$ of $[a,b]$ with points, tags, $\xi_i \in [t_{i-1}, t_i]$) that is δ -fine, i.e.

$$\xi_i \in [t_{i-1}, t_i] \subset]\xi_i - \delta(\xi_i), \xi_i + \delta(\xi_i)[,$$

we have $\|J - \sum_{i=1}^n f(\xi_i)(t_i - t_{i-1})\| < \varepsilon$.

It can be proved that for every gauge δ there exist always δ -fine tagged divisions of $[a, b]$ and that J is unique, see [15]. The integral is linear, additive with respect to subintervals. However the existence of $\int_a^b f(t)dt$ does not imply the existence of $\int_a^b \|f(t)\|dt$ even in the numerical case ($X = \mathbb{R}$), see [13], 1.7 and 1.8. $K([a, b], X)$ encompasses the functions $f: [a, b] \rightarrow X$ that are integrable in the sense of Bochner-Lebesgue or in the sense of Riemann (proper or improper), see [13], 1.8 and 1.6. We recall that in the numerical case $K([a, b])$ coincides with the spaces of Denjoy or Perron integrable functions.

In $K([a, b], X)$ we define the Alexiewicz seminorm (see [1] or [4])

$$\|f\|_A = \sup_{a \leq t \leq b} \left\| \int_a^t f(s) ds \right\|.$$

2.1 (see [15] or [20]) - For $f \in K([a, b], X)$ we have

$$\tilde{f} \in \mathcal{C}_a([a, b], X) \quad \text{where} \quad \tilde{f}(t) = \int_a^t f(s) ds, \quad a \leq t \leq b.$$

We say that $f, g \in K$ are equivalent if $\tilde{f} = \tilde{g}$. If $\dim X = \infty$ this does not necessarily imply that $f = g$ a.e. Example: for $X = \mathcal{C}_2([a, b])$ and $f(t) = e_t$, where $e_t(s) = \begin{cases} 1 & \text{if } s = t \\ 0 & \text{if } s \neq t \end{cases}$, we have $\tilde{f} = 0$; see [10], p.26 or [11] p.12. We denote by $K([a, b], X)$ the space of the equivalence classes of $K([a, b], X)$. Endowed with the norm $\|\cdot\|_A$, $K([a, b], X)$ is not complete and $K([a, b], X)$ allows no natural Banach space or Frechet space topology: see [13], Theorem 2.7. However Sargent [19] and Thomson [21] proved that $K([a, b], X)$ is barreled and Gilioli extended this result:

Theorem 2.2 ([8]) - $K([a, b], X)$ is ultrabornological.

It is easy to define the Kurzweil integral for "intervals" $[a, b] \subset \mathbb{R}^n$ and in this case too $K([a, b], X)$ is barreled, see [16], and ultrabornological, see [9].

2.3 - The mapping $f \in K([a, b], X) \mapsto \tilde{f} \in \mathcal{C}_a([a, b], X)$ is an isometry (i.e. $\|\tilde{f}\| = \|f\|_A$) of the first space onto a dense subspace of the second.

Theorem 2.4 - For every $\alpha \in SV([a, b], L(X, Y))$ and $f \in K([a, b], X)$ we have $\alpha \cdot f \in K([a, b], Y)$ and

$$\int_a^b \alpha(t) \cdot f(t) dt = \int_a^b \alpha(t) \cdot d\tilde{f}(t) = \alpha(b) \cdot \tilde{f}(b) - \alpha(a) \cdot \tilde{f}(a) - \int_a^b d\alpha(t) \cdot \tilde{f}(t)$$

$$\text{and } \left\| \int_a^b \alpha(t) \cdot f(t) dt \right\| \leq [\|\alpha(a)\| + SV[\alpha]] \|f\|_A.$$

Our proof of this integration by parts formula for the Kurzweil-Henstock integral (see [13], 1.15 and 1.16) is algebraic and much simpler than the analytic proofs given in [5], [3], [7] and [17].

Theorem 2.5 - The mapping

$$\alpha \in SV_b^{+j}([a, b], L(X, \dot{Y})) \mapsto H_\alpha \in L[K([a, b], X), Y]$$

where $H_\alpha f = \int_a^b \alpha(s) \cdot f(s) ds$, is an isometry (i.e. $\|H_\alpha\| = SV[\alpha]$) of the first Banach space onto the second. We have

$$H_\alpha(\chi_{[a, t]} x) = \int_a^t \alpha(s) x ds, \quad x \in X, t \in [a, b].$$

Proof: by Theorem 2.4 we have $\|H_\alpha\| \leq SV[\alpha]$. On the other hand given $H \in L[K([a, b], X), Y]$ and $f \in K([a, b], X)$ we define $\hat{H}(\tilde{f}) = -H(f)$ and by 2.3 $\hat{H}$ has a unique continuous extension to $\mathcal{C}_a([a, b], X)$. If $\alpha \in SV_b^{+j}([a, b], L(X, \dot{Y}))$ represents $\hat{H}$ (see Theorem 1.5) we have

$$H(f) = -\hat{H}(\tilde{f}) = - \int_a^b d\alpha(s) \cdot \tilde{f}(s) = \int_a^b \alpha(s) \cdot f(s) ds$$

where we applied Theorem 2.4 in the last equality. The isometry follows from $\|H\| = \|\hat{H}\| = SV[\alpha]$.

Remark: as we mentioned in the remark that follows Theorem 1.4, from $H_\alpha(\chi_{[a,t]} x) = \int_a^t \alpha(s)x \, ds$ we cannot deduce that $\alpha(t+)x = \frac{d^+}{dt} H_\alpha(\chi_{[a,t]} x)$.

From 2.1, Theorems 1.6 and 2.5 follows

Theorem 2.6 - The mapping

$$\alpha \in \tilde{C}^r \cdot SV_b^{+u}([c,d] \times [a,b], L(X, Y)) \mapsto H_\alpha \in L[K([a,b], X), C([c,d], Y)]$$

where $(H_\alpha f)(t) = \int_a^b \alpha(t,s) \cdot f(s) \, ds$, is an isometry (i.e. $\|H_\alpha\| = SV^u[\alpha]$) of the first Banach space onto the second. We have

$$\int_a^{b'} \alpha(t,s)x \, ds = [H_\alpha(\chi_{[a,s]} x)](t), \quad s \in [a,b], \quad t \in [c,d], \quad x \in X.$$

3. Linear Kurzweil-Henstock integral equations

Theorem 3.1 - Let E be a normed space and F a Banach space such that $F \subset E$ with continuous immersion; let $H \in L(E, F)$ be such that for every $f \in E$ the equation $x - Hx = f$ has one and only one solution $x_f \in E$. Then

a) the mapping $f \in E \mapsto x_f \in E$ is bicontinuous;

b) if $I + H + H^2 + H^3 + \dots = (I - H)^{-1}$ is convergent in $L(F)$

then the convergence of this Neumann series takes also place in $L(E)$.

Proof - a): 1) For every $g \in F$ the equation $y - Hy = g$ has one and only one solution $y_g \in F$ and the mapping $g \in F \mapsto y_g \in F$ is bicontinuous. Indeed: since $F \subset E$ the equation $y - Hy = g$ with $g \in F$ has by hypothesis one and only one solution $y_g \in E$; but since $HE \subset F$ we have $Hy_g \in F$ hence $y_g = Hy_g + g \in F$. On the other hand the

mapping $y \in F \mapsto g = y - Hy \in F$ is a continuous bijection, hence, by the closed graph theorem, its inverse $g \in F \mapsto y_g \in F$ is continuous.

2) The equation $x - Hx = f$ with $x, f \in E$, is equivalent to the equation $y - Hy = g$ with $g = Hf$ and $y = x - f$. The mapping $f \in E \mapsto g = Hf \in E$ is continuous; by 1) the mapping $Hf \in F \mapsto y_{Hf} \in F$ is also continuous; since the mapping $y_{Hf} \in F \mapsto y_{Hf} \in E$ is also continuous it follows that the composed mapping $f \in E \mapsto y_{Hf} \in E$ is also continuous, hence so is the mapping $f \in E \mapsto y_{Hf} + f \in E$. The result follows from $y_{Hf} = x_f - f$, i.e., $x_f = y_{Hf} + f$.

b) Let $(I - H)^{-1} = I + H + H^2 + H^3 + \dots$ be convergent in $L(F)$. Since $H \in L(E, F)$ and $F \subseteq E$ is continuous, it follows that the series is also convergent in $L(E)$. It is immediate that if a Neumann series is convergent in some $L(Z)$ (Z not necessarily complete) then it converges to $(I - H)^{-1}$.

Theorem 3.2 - Take $H \in L[K([a, b], X), \mathcal{C}([a, b], X)]$ and α the corresponding kernel by Theorem 2.6 (i.e., $H = H_\alpha$). We suppose that H is such that for every $f \in K([a, b], X)$ the equation $x - Hx = f$, i.e. the linear Fredholm-Kurzweil integral equation

$$x(t) - K \int_a^b \alpha(t, s) \cdot x(s) ds = f(t), \quad a \leq t \leq b$$

has one and only one solution $x_f \in K([a, b], X)$. Then there exists one and only one kernel

$$p \in \tilde{\mathcal{C}}^{SV_b+u}([a, b] \times [a, b], L(X, \dot{X}))$$

such that for every $f \in K([a, b], X)$ we have

$$x_f(t) = f(t) - K \int_a^b p(t, s) \cdot f(s) ds, \quad a \leq t \leq b.$$

Proof: if we apply Theorem 3.1 with $E = K([a, b], X)$ and $F = \mathcal{C}([a, b], X)$ it follows that $(I - H)^{-1} \in L[K([a, b], X)]$. If we define $I - R = (I - H)^{-1}$ it follows that $R = -H(I - H)^{-1} \in L[K([a, b], X), \mathcal{C}([a, b], X)]$ is represented by a kernel $\rho \in \tilde{\mathcal{C}}' \cdot SV_b^{+j u}$.

Remarks - 1) If $H \in L[K([a, b], X), \mathcal{C}([a, b], X)]$ satisfies the hypothesis of Th.3.2 then we still have an analogous result if we replace $K([a, b], X)$ by any dense subspace that contains $\mathcal{C}([a, b], X)$. More generally, if E is a dense subspace of $K([a, b], X)$ that contains $\mathcal{C}([a, b], X)$ and $H \in L[E, \mathcal{C}([a, b], X)]$ is such that for every $f \in E$ the equation $x - Hx = f$ has one and only one solution $x_f \in E$ then Theorem 3.2 remains true if we replace $K([a, b], X)$ by E . Let us mention as example $R_2([a, b], X)$, the subspace formed by the (equivalence classes of) functions $f: [a, b] \rightarrow X$ that are integrable in the improper sense of Riemann with a finite numbers of singularities (points of improper integration) in $[a, b]$. This space too is ultrabornological: see [8], p.359, Example 4.7, F_{11}^α with $\alpha = 1$. The same is also true for the other spaces of functions of this Example 4.7.

2) We still have analogous results if in Theorem 3.2 and in Remark 1 we replace $\mathcal{C}([a, b], X)$ by $G([a, b], X)$ or by $L_\infty([a, b], X)$.

Lemma 3.3 - For $\alpha \in \tilde{\mathcal{C}}' \cdot SV_b^{+j u}([a, b] \times [a, b], L(X, Y))$ and $f \in X([a, b], X)$ the function $t \in [a, b] \mapsto K \int_a^t \alpha(t, s) \cdot f(s) ds \in Y$ is continuous.

Proof: since the step functions are dense in $X([a, b], X)$ it is enough to prove that for every $x \in X$ the function

$$t \in [a, b] \mapsto K \int_a^t \alpha(t, s) x ds \in Y$$

is continuous: for $\varepsilon > 0$ we have

$$\int_a^{t+\varepsilon} \alpha(t+\varepsilon, s) x \, ds = \int_a^t \alpha(t+\varepsilon, s) x \, ds + \int_t^{t+\varepsilon} \alpha(t+\varepsilon, s) x \, ds$$

and the first integral on the right tends to $\int_a^t \alpha(t, s) x \, ds$ (by $(\tilde{C}')$) and the norm of the second integral is $\varepsilon \|\alpha\|_\infty \|x\|$ hence the continuity to the right. The continuity to the left is proved in an analogous way.

Remark: in an analogous way one proves that for $\alpha \in \tilde{G}^\sigma \cdot SV_b^{+f\bar{u}}$ $[\tilde{L}_\infty^\sigma \cdot SV_b^{+f\bar{u}}]$ the integral of Lemma 3.3 is a regulated (bounded measurable) function of $t \in [a, b]$.

We say that an operator $H \in L[K([a, b], X), \mathcal{C}([a, b], Y)]$ is causal if for every $f \in K$ and every $t \in [a, b]$ we have

$$f|_{[a, t]} = 0 \quad \text{implies} \quad (Hf)|_{[a, t]} = 0$$

Lemma 3.3 says that for $\alpha \in \tilde{C}^\sigma \cdot SV_b^{+f\bar{u}}$ with $\alpha(t, s) = 0$ for $s > t$ (we write $\alpha \in \tilde{C}_0^\sigma \cdot SV^{+f\bar{u}}([a, b] \times [a, b], L(X, \dot{X}))$) the operator $H = H_\alpha$ is causal. Reciprocally every causal operator $H \in L[K, \mathcal{C}]$ is of the form $H = H_\alpha$ with $\alpha \in \tilde{C}_0^\sigma \cdot SV^{+f\bar{u}}$: indeed, if H_α represents H then for every $t \in [a, b]$ and $x \in X$ we have $0 = [H_\alpha(\chi_{[t, b]} x)](t) = \int_t^b \alpha(t, s) x \, ds$ hence the result (Cf. the Remark that follows the proof of Theorem 1.4: the function $s \in [a, b] \mapsto \langle \alpha(t, s) x, y \rangle \in \mathbb{R}$ is of bounded variation continuous to the right). Hence we proved the

Theorem 3.4 - The mapping

$$\alpha \in \tilde{C}_0^\sigma \cdot SV^{+f\bar{u}}([a, b] \times [a, b], L(X, \dot{X})) \longmapsto H_\alpha \in L[K([a, b], X), \mathcal{C}([a, b], Y)]$$

is an isometry onto the subspace of causal operators.

Remark: we have the corresponding results, with analogous proofs if we replace $\mathcal{C}([a, b], Y)$ by $G([a, b], Y)$ or by $L_\infty([a, b], Y)$.

Let us now consider the linear Volterra-Kurzweil integral equation

$$(V) \quad x(t) - K \int_a^t \alpha(t,s) \cdot x(s) \, ds = f(t), \quad a \leq t \leq b$$

with $x, f \in X([a,b], X)$ and $\alpha \in \widetilde{C}_0^\sigma \cdot SV^{+u}([a,b] \times [a,b], L(X, \dot{X}))$ i.e. H_α is a causal operator.

Theorem 3.5 - For every $f \in X([a,b], X)$ the equation (V) has one and only one solution $x_f \in X([a,b], X)$ and the bijection $f \mapsto x_f$ too is causal and may be written as

$$(\rho) \quad x_f(t) = f(t) - K \int_a^t \rho(t,s) \cdot f(s) \, ds, \quad a \leq t \leq b$$

where $\rho \in \widetilde{C}_0^\sigma \cdot SV^{+u}([a,b] \times [a,b], L(X, \dot{X}))$. We have the Neumann series $I - H_\rho = I + H_\alpha + H_\alpha^2 + H_\alpha^3 + \dots$ that is convergent in $L[K([a,b], X)]$.

Proof: we define $g(t) = K \int_a^t \alpha(t,s) \cdot f(s) \, ds$ and $y = x - f$. The equation (V) is equivalent to the equation

$$(V_1) \quad y(t) - K \int_a^t \alpha(t,s) \cdot y(s) \, ds = g(t), \quad a \leq t \leq b$$

with $g, y \in \mathcal{C}([a,b], X)$ (since $H_\alpha \in L[K, \mathcal{C}]$) and hence $g = H_\alpha f$ and $y = g + E_\alpha y$. If we define $K(t,s)x_0 = -\int_s^t \alpha(t,\sigma)x_0 \, d\sigma$ for $x_0 \in X$ and $a \leq s \leq t \leq b$ then the equation (V_1) is equivalent to the linear Volterra-Stieltjes integral equation

$$(V_2) \quad y(t) - \int_a^t d_s K(t,s) \cdot y(s) = g(t), \quad a \leq t \leq b$$

(with $g = E_\alpha f$ and $y = x - f$). In order to prove that for every $g \in \mathcal{C}([a,b], X)$ the equation (V_2) has one and only one solution $y_g \in \mathcal{C}([a,b], X)$ (and that the operator $g \mapsto y_g$ is causal) by Theorem 3.8 of [12] it is enough to prove that

1) For every $t \in [a, b[$ the operator $I - K(t^\dagger, t)$ is invertible (in $L(X)$).

2) There exists a division $s_0 = a < s_1 < s_2 < \dots < s_n = b$ of $[a, b]$ such that

$$\sup_{s_{i-1} \leq t \leq s_i} SV_{[s_{i-1}, t]}[K^t] < 1 \quad \text{for } i = 1, 2, \dots, n$$

The proof of 1) is immediate since $K(t^+, t) = 0$:

$$\|K(t+\varepsilon, t)x_0\| = \left\| \int_t^{t+\varepsilon} \alpha(t+\varepsilon, \sigma)x_0 \, d\sigma \right\| \leq \varepsilon \|\alpha\|_\infty \|x_0\| \leq \varepsilon SV^\alpha(\alpha) \|x_0\|.$$

2) follows from

$$SV_{[s_{i-1}, t]}[K^t] \leq V_{[s_{i-1}, t]}[K^t] \leq (t-s_{i-1}) \|\alpha\|_\infty \leq (t-s_{i-1}) SV^\alpha(\alpha)$$

where $V_{[s_{i-1}, t]}[K^t]$ denotes the variation of K^t in the interval $[s_{i-1}, t]$.

The assertion on the Neumann series of the resolvent of (V_2) in $L(\mathcal{C}([a, b], X))$ follows from Theorem 3.9 of [12]. From Theorem 3.1 follows the same result in $L[K([a, b], X)]$ and since F_K is causal, where $(F_K g)(t) = \int_a^t d_s K(t, s) \cdot g(s) = (H_K g)(t)$, $a \leq t \leq b$, the same is true for $(F_K)^n$ and hence for the operator represented by the Neumann series, i.e., for $(I - F_K)^{-1}$. The same result for H_K follows from $F_K = H_K$ (and from $I - H_F = (I - H_K)^{-1}$).

Remarks - 1) We have still an analogous result if we replace $K([a, b], X)$ by $R_2([a, b], X)$ or the other spaces mentioned in Remark 1 that follows Theorem 3.2.

2) Analogously we may replace $\mathcal{C}([a, b], X)$ by $G([a, b], X)$ or by $L_\infty([a, b], X)$.

For $\alpha: [a, b] \rightarrow L(X, Y)$ and $f: [a, b] \rightarrow X$ it is easy to define the Kurzweil-Stieltjes integral $\int_a^b d\alpha(t) \cdot f(t)$, a generalization of the Ward or Perron-Stieltjes numerical integral, see [21].

If $\alpha \in SV([a, b], L(X, Y))$ we define

$$K_\alpha([a, b], X) = \left\{ f \in X^{[a, b]} \mid \exists \int_a^b d\alpha(t) \cdot f(t) \in Y \right\}$$

and the seminorm $\|f\|_\alpha = \sup_{a \leq t \leq b} \left\| \int_a^t d\alpha(s) \cdot f(s) \right\|$. Without some restriction on α , $K_\alpha([a, b], X)$ may not be ultrabornological (example of Luiz Fichmann). Elsewhere we will study the Fredholm-Kurzweil-Stieltjes integral equations and the Volterra-Kurzweil-Stieltjes integral equations.

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