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Homoscedastic controlled calibration model

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Abstract

In the context of the usual calibration model, we consider the case in which the independent variable is unobservable, but a pre-fixed value on its surrogate is available. Thus, considering controlled variables and assuming that the measurement errors have equal variances we propose a new calibration model. Likelihood based methodology is used to estimate the model parameters and the Fisher information matrix is used to construct a confidence interval for the unknown value of the regressor variable. A simulation study is carried out to assess the effect of the measurement error on the estimation of the parameter of interest. This new approach is illustrated with an example.

Keywords: Regression model, linear calibration model, measurement error model, Berkson model.

1 Introduction

In the first stage of a calibration problem, a pair of data sample (x_i, Y_i) , $i = 1, 2, \dots, n$ is observed. In the second stage, it is observed one or more values, which are the responses corresponding to a single unknown value of the regressor variable, X_0 . The first and second stage equations of the usual linear calibration model are defined, respectively, as

$$Y_i = \alpha + \beta x_i + \epsilon_i, \quad i = 1, 2, \dots, n, \quad (1.1)$$

$$Y_{0i} = \alpha + \beta X_0 + \epsilon_i, \quad i = n+1, n+2, \dots, n+k. \quad (1.2)$$

It is considered the following assumptions:

- x_1, x_2, \dots, x_n take fixed values, which are considered as true values.
- $\epsilon_1, \epsilon_2, \dots, \epsilon_{n+k}$ are independent and normally distributed with mean 0 and variance σ_ϵ^2 .

The model parameters are α, β, X_0 and σ_ϵ^2 and the main interest is to estimate the quantity X_0 .

The maximum likelihood estimators of the usual calibration model are given by

$$\hat{\alpha} = \bar{Y} - \hat{\beta}\bar{x}, \quad \hat{\beta} = \frac{S_{xY}}{S_{xx}}, \quad \hat{X}_0 = \frac{\bar{Y}_0 - \hat{\alpha}}{\hat{\beta}}, \quad (1.3)$$

$$\sigma_\epsilon^2 = \frac{1}{n+k} \left[\sum_{i=1}^n (Y_i - \hat{\alpha} - \hat{\beta}x_i)^2 + \sum_{i=n+1}^{n+k} (Y_{0i} - \bar{Y}_0)^2 \right], \quad (1.4)$$

where

$$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i, \quad \bar{Y} = \frac{1}{n} \sum_{i=1}^n Y_i, \quad S_{xY} = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})(Y_i - \bar{Y}),$$

$$S_{xx} = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2, \quad \bar{Y}_0 = \frac{1}{n} \sum_{i=n+1}^{n+k} Y_{0i}.$$

In [10] an approximate expression is derived for the variance of the estimator \hat{X}_0 , which is derived through the propagation error law. Another approximation for the variance of \hat{X}_0 is given by the Fisher information of $\theta = (\alpha, \beta, X_0, \sigma_\epsilon^2)$ which, after some length algebraic manipulations, it can be shown to be given by

$$I(\theta) = \frac{1}{\sigma_\epsilon^2} \begin{pmatrix} n+k & kX_0 + n\bar{x} & k\beta & 0 \\ kX_0 + n\bar{x} & kX_0^2 + \sum_{i=1}^n x_i^2 & \kappa\beta X_0 & 0 \\ k\beta & \kappa\beta X_0 & k\beta^2 & 0 \\ 0 & 0 & 0 & \frac{n+k}{2\sigma_\epsilon^2} \end{pmatrix}. \quad (1.5)$$

The maximum likelihood estimator of $\hat{\theta} = (\hat{\alpha}, \hat{\beta}, \hat{X}_0, \hat{\sigma}_\epsilon^2)$ has approximately normal distribution with mean θ and covariance matrix $I(\theta)^{-1}$, when $k = qn$, $q \in Q^+$ and $n \rightarrow \infty$. Thus, the approximation of order n^{-1} for the variance of \hat{X}_0 is given by

$$V_1(\hat{X}_0) = \frac{\sigma_\epsilon^2}{\beta^2} \left[\frac{1}{k} + \frac{1}{n} + \frac{(\bar{X} - X_0)^2}{nS_{xx}} \right]. \quad (1.6)$$

On the other hand, in [4] the size k of the second stage is considered fixed, so that expanding \hat{X}_0 in Taylor series around the point (α, β) and ignoring terms of order less than n^{-2} , we can find the following approximations for the bias and variance of \hat{X}_0 , respectively,

$$\text{Bias}(\hat{X}_0) = \frac{\sigma_\epsilon^2(X_0 - \bar{x})}{n\beta^2 S_{xx}}, \quad (1.7)$$

$$V_2(\hat{X}_0) = \frac{\sigma_\epsilon^2}{\beta^2} \left[\frac{1}{k} + \frac{1}{n} + \frac{(\bar{X} - X_0)^2}{nS_{xx}} + \frac{3\sigma_\epsilon^2}{nk\beta^2 S_{xx}} \right]. \quad (1.8)$$

In order to construct a confidence interval for X_0 , we consider that

$$\frac{\hat{X}_0 - X_0}{\sqrt{\hat{V}(\hat{X}_0)}} \xrightarrow{D} N(0, 1), \quad (1.9)$$

where $\hat{V}(\hat{X}_0)$ is the estimated variance computed according to (1.6) or (1.8). Hence, the approximated confidence interval for X_0 with a confidence level $(1 - \alpha)$, is given by

$$\left(\hat{X}_0 - z_{\frac{\alpha}{2}} \sqrt{\hat{V}(\hat{X}_0)}, \hat{X}_0 + z_{\frac{\alpha}{2}} \sqrt{\hat{V}(\hat{X}_0)} \right), \quad (1.10)$$

where $z_{\frac{\alpha}{2}}$ is the quantile of order $(1 - \frac{\alpha}{2})$ of the standard normal distribution.

The usual calibration problem has been discussed in the literature for several decades (see [1]-[6]). An illustration of this model is presented for example in [7]. We can find a review of the literature on statistical calibration in [8], where some approaches to the solution of the calibration problem are summarized.

This model encounters applications in different areas, but it is not well suited in some instances as, for example, in chemical analysis, where the preparation process of standard solutions are subject to measurement error ([10]).

There exists some situations, as mentioned above, where the independent variable, x_i , is measured with error. In this case, [11] defines two types of observations: *controlled* and *uncontrolled*.

In the *uncontrolled* situation, the usual procedure to obtain the true value of the independent variable x_i generates an error and the observed value is

$$X_i = x_i + \delta_i, \quad i = 1, \dots, n. \quad (1.11)$$

We have that x_i is an unknown quantity, δ_i is a measurement error and X_i is a random variable. Assuming that x_i is a parameter the model defined by (1.1) and (1.11) is named as functional model ([12]). In this case there exists correlation between the model error and the variable X_i . Assuming that x_i is a random variable the model (1.1) and (1.11) is called as structural model ([12]). On the other hand, the model defined by (1.1), (1.2) and (1.11) is called as the functional or structural calibration model if x_i is assumed as a parameter or a random variable, respectively ([13]).

The *controlled* observation is defined by a pre-fixed value X_i according to the experimenter convenience and a procedure is established in order to attain the pre-fixed value. The experiment gives the unobserved x_i and it is such that

$$x_i = X_i - \delta_i, \quad i = 1, \dots, n. \quad (1.12)$$

In this case, the fixed quantity is X_i , the measurement error is δ_i and x_i is the random variable. The model (1.1) and (1.12) is known as Berkson regression model ([9]). Notice that the model error and the quantity X_i are independent. The model defined by (1.1), (1.2) and (1.12) has not been considered before in the measurement error literature and in this work it will be called as the *controlled calibration model*.

In the calibration model defined by (1.1), (1.2) and (1.11), the values of the regressor, X_i , from the first stage are randomly generated, whereas in the controlled calibration model, (1.1), (1.2) and (1.12), they are assumed as pre-fixed by the experimenter.

This work is organized as follows. In Section 2, we derive the maximum likelihood estimators of the homoscedastic controlled calibration model by considering both cases: σ_δ^2 *unknown* and *known*. In Section 3, a simulation study is undertaken to investigate the sensitivity of parameter estimates of the proposed model. In Section 4, an example is presented to illustrate our new approach. In Section 5, the concluding remark is presented.

2 Parameter estimation

In this section we study the controlled calibration model. From the equations (1.1), (1.2) and (1.12) we can write

$$Y_i = \alpha + \beta X_i + (\epsilon_i - \beta \delta_i), \quad i = 1, 2, \dots, n, \quad (2.1)$$

$$Y_{0i} = \alpha + \beta X_0 + \epsilon_i, \quad i = n+1, n+2, \dots, n+k. \quad (2.2)$$

with the following assumptions for the random errors

- ϵ_i are independent $N(0, \sigma_\epsilon^2)$ random variables.
- $E(\delta_i) = 0, V(\delta_i) = \sigma_\delta^2$.
- $\text{cov}(\delta_i, \delta_j) = 0$ for any $i \neq j$.

- $\text{cov}(\epsilon_i, \delta_j) = 0$ for all i, j .

Some comments are in order here. The variable X_i in (2.1) is controlled and the error model $(\epsilon_i - \beta\delta_i)$ is independent of X_i . The error model in (2.2) is only in function of error measure ϵ_i related to Y_{0i} , this model assume that there is not error in the preparation sample related to parameter X_0 . We define the homoscedastic controlled calibration model by considering that the errors δ_i are independent and normally distributed with mean 0 and constant variance, σ_δ^2 . The study of this model is carried out following similar analysis to the usual calibration model as summarized above.

The maximum likelihood estimator for the homoscedastic controlled calibration model is derived in the following. The logarithm of the likelihood function is given by:

$$l(\alpha, \beta, X_0, \sigma_\epsilon^2, \sigma_\delta^2) \propto -\frac{n}{2} \log(\sigma_\epsilon^2 + \beta^2 \sigma_\delta^2) - \frac{k}{2} \log(\sigma_\epsilon^2) - \frac{1}{2} \left[\frac{1}{\sigma_\epsilon^2 + \beta^2 \sigma_\delta^2} \sum_{i=1}^n (Y_i - \alpha - \beta X_i)^2 + \frac{1}{\sigma_\epsilon^2} \sum_{i=n+1}^{n+k} (Y_{0i} - \alpha - \beta X_0)^2 \right]. \quad (2.3)$$

Solving $\partial l / \partial \alpha = 0$ and $\partial l / \partial X_0 = 0$ we have the maximum likelihood estimator of α and X_0 , which are given, respectively, by

$$\hat{\alpha} = \bar{Y} - \hat{\beta} \bar{X} \quad \text{and} \quad \hat{X}_0 = \frac{\bar{Y}_0 - \hat{\alpha}}{\hat{\beta}}. \quad (2.4)$$

From (2.3) and (2.4), it follows that the likelihood for $(\beta, \sigma_\epsilon^2, \sigma_\delta^2)$ can be written as

$$l(\beta, \sigma_\epsilon^2, \sigma_\delta^2) \propto -\frac{n}{2} \log(\sigma_\epsilon^2 + \beta^2 \sigma_\delta^2) - \frac{k}{2} \log(\sigma_\epsilon^2) - \frac{1}{2} \left[\frac{1}{\sigma_\epsilon^2 + \beta^2 \sigma_\delta^2} \sum_{i=1}^n ((Y_i - \bar{Y}) - \beta(X_i - \bar{X}))^2 + \frac{1}{\sigma_\epsilon^2} \sum_{i=n+1}^{n+k} (Y_{0i} - \bar{Y}_0)^2 \right]. \quad (2.5)$$

Next, we consider two cases for σ_δ^2 . Firstly, we obtain the maximum likelihood estimator of β , σ_ϵ^2 and σ_δ^2 from (2.5). In the second case we assume that the variance σ_δ^2 is known and obtain the maximum likelihood estimators for β and σ_ϵ^2 .

Case 1: unknown variance σ_δ^2

Taking the partial derivative of (2.5) with respect to β , σ_ϵ^2 and σ_δ^2 and equating to zero we obtain, respectively,

$$\hat{\beta} \hat{\sigma}_\delta^2 (\hat{\sigma}_\epsilon^2 + \hat{\beta}^2 \hat{\sigma}_\delta^2 - S_{YY} + \hat{\beta} S_{XY}) = (S_{XY} - \hat{\beta} S_{XX}) \hat{\sigma}_\epsilon^2, \quad (2.6)$$

$$\hat{\sigma}_\epsilon^2 + \hat{\beta}^2 \hat{\sigma}_\delta^2 = S_{YY} - 2\hat{\beta}S_{XY} + \hat{\beta}^2 S_{XX}, \quad (2.7)$$

$$\frac{kS_{Y_0Y_0}}{(\hat{\sigma}_\epsilon^2)^2} - \frac{k}{\hat{\sigma}_\epsilon^2} = \frac{n}{\hat{\sigma}_\epsilon^2 + \hat{\beta}^2 \hat{\sigma}_\delta^2} - \frac{n(S_{YY} - 2\hat{\beta}S_{XY} + \hat{\beta}^2 S_{XX})}{(\hat{\sigma}_\epsilon^2 + \hat{\beta}^2 \hat{\sigma}_\delta^2)^2}, \quad (2.8)$$

where $S_{XX} = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2$, $S_{XY} = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})(Y_i - \bar{Y})$, $S_{YY} = \frac{1}{n} \sum_{i=1}^n (Y_i - \bar{Y})^2$ and $S_{Y_0Y_0} = \frac{1}{k} \sum_{i=n+1}^{n+k} (Y_{0i} - \bar{Y}_0)^2$, and the relevant estimator notation has been introduced. From (2.6) and (2.7) we have the following equations:

$$(\hat{\beta}S_{XX} - S_{XY})(S_{YY} - 2\hat{\beta}S_{XY} + \hat{\beta}^2 S_{XX}) = 0,$$

hence

$$\hat{\beta}S_{XX} - S_{XY} = 0 \quad \text{or} \quad (2.9)$$

$$S_{YY} - 2\hat{\beta}S_{XY} + \hat{\beta}^2 S_{XX} = 0. \quad (2.10)$$

Therefore, from (2.9), we have that $\hat{\beta} = S_{XY}/S_{XX}$. But, according to the Cauchy-Schwarz inequality, $S_{XX}S_{YY} \geq S_{XY}^2$, hence (2.10) has real roots if and only if $Y_i = cX_i$, where c is a constant.

The estimator of σ_δ^2 can be obtained from the equation (2.7)

$$\hat{\sigma}_\delta^2 = \frac{(S_{YY} - 2\hat{\beta}S_{XY} + \hat{\beta}^2 S_{XX}) - \hat{\sigma}_\epsilon^2}{\hat{\beta}^2}.$$

Likewise, from equations (2.7) and (2.8) we obtain the estimator of the variance σ_ϵ^2

$$\hat{\sigma}_\epsilon^2 = S_{Y_0Y_0}. \quad (2.11)$$

In order to find the variance of \hat{X}_0 , we need to derive the Fisher information matrix of $\theta = (\alpha, \beta, X_0, \sigma_\delta^2, \sigma_\epsilon^2)$, which can be shown to be given by

$$I(\theta) = \begin{pmatrix} \frac{n}{\gamma} + \frac{k}{\sigma_\epsilon^2} & \frac{n\bar{X}}{\gamma} + \frac{kX_0}{\sigma_\epsilon^2} & \frac{k\beta}{\sigma_\epsilon^2} & 0 & 0 \\ \frac{n\bar{X}}{\gamma} + \frac{kX_0}{\sigma_\epsilon^2} & \frac{\sum_{i=1}^n X_i^2}{\gamma} + \frac{2n\beta^2 \sigma_\delta^4}{\gamma^2} + \frac{kX_0^2}{\sigma_\epsilon^2} & \frac{k\beta X_0}{\sigma_\epsilon^2} & \frac{n\beta^3 \sigma_\delta^2}{\gamma^2} & \frac{n\beta \sigma_\delta^2}{\gamma^2} \\ \frac{k\beta}{\sigma_\epsilon^2} & \frac{k\beta X_0}{\sigma_\epsilon^2} & \frac{k\beta^2}{\sigma_\epsilon^2} & 0 & 0 \\ 0 & \frac{n\beta^3 \sigma_\delta^2}{\gamma^2} & 0 & \frac{n\beta^4}{2\gamma^2} & \frac{n\beta^2}{2\gamma^2} \\ 0 & \frac{n\beta \sigma_\delta^2}{\gamma^2} & 0 & \frac{n\beta^2}{2\gamma^2} & \frac{n}{2\gamma^2} + \frac{k}{2\sigma_\epsilon^2} \end{pmatrix},$$

where

$$\gamma = \beta^2 \sigma_\delta^2 + \sigma_\epsilon^2. \quad (2.12)$$

When $k = qn$, $q \in Q^+$ and $n \rightarrow \infty$, the estimator $\hat{\theta}$ is approximately normally distributed with mean θ and variance $I(\theta)^{-1}$, thus we have that the approximate variance to order n^{-1} for \hat{X}_0 is given by

$$V_1(\hat{X}_0) = \frac{\sigma_\epsilon^2}{\beta^2} \left[\frac{1}{k} + \frac{\gamma}{n\sigma_\epsilon^2} + \frac{\gamma}{\sigma_\epsilon^2} \frac{(\bar{X} - X_0)^2}{nS_{XX}} \right]. \quad (2.13)$$

Considering k fixed and expanding \hat{X}_0 in a Taylor series around (α, β) and ignoring terms of order less than n^{-2} , it can be shown that the bias and variance of \hat{X}_0 (the proof is given in Appendix A), are given by

$$\text{Bias}(\hat{X}_0) = \frac{\gamma(\bar{X} - X_0)}{n\beta^2 S_{XX}}, \quad (2.14)$$

$$V_2(\hat{X}_0) = \frac{\sigma_\epsilon^2}{\beta^2} \left[\frac{1}{k} + \frac{\gamma}{n\sigma_\epsilon^2} + \frac{\gamma(\bar{X} - X_0)^2}{n\sigma_\epsilon^2 S_{XX}} + \frac{3\gamma}{nk\beta^2 S_{XX}} \right]. \quad (2.15)$$

We can observe that the estimator of X_0 is biased, but it is asymptotically unbiased.

With relation to the variance of the estimator \hat{X}_0 , let us notice that when $k = qn$, $q \in Q^+$, and ignoring the terms of order less than n^{-1} the variance in (2.15) coincide with the variance given in (2.13), which was found through the Fisher information. Equation (2.13) consider large sample sizes in the first and second stage (n and k), whereas (2.15) consider large sample sizes in the first stage and a fixed sample size in the second stage.

Notice that when $\sigma_\delta^2 = 0$, (2.13) and (2.15) coincide with (1.6) and (1.8) of the usual model, respectively.

Caso 2: known variance σ_δ^2

Assuming now that σ_δ^2 is known and equating to zero the partial derivative of (2.5) with respect to the parameters β and σ_ϵ^2 , we have the following equations, respectively,

$$\hat{\beta}\sigma_\delta^2(\hat{\sigma}_\epsilon^2 + \hat{\beta}^2\sigma_\delta^2 - S_{YY} + \hat{\beta}S_{XY}) = (S_{XY} - \hat{\beta}S_{XX})\hat{\sigma}_\epsilon^2 \quad \text{and} \quad (2.16)$$

$$\frac{kS_{Y_0Y_0}}{(\hat{\sigma}_\epsilon^2)^2} - \frac{k}{\hat{\sigma}_\epsilon^2} = \frac{n}{\hat{\sigma}_\epsilon^2 + \hat{\beta}^2\sigma_\delta^2} - \frac{S_{YY} - 2\hat{\beta}S_{XY} + \hat{\beta}^2S_{XX}}{(\hat{\sigma}_\epsilon^2 + \hat{\beta}^2\sigma_\delta^2)^2}. \quad (2.17)$$

The estimates of β and σ_ϵ^2 are obtained using some iterative method to solve (2.16) and (2.17).

Similarly, as in Case 1, the Fisher information matrix of $\theta = (\alpha, \beta, X_0, \sigma_\epsilon^2)$ is given by

$$I(\theta) = \begin{pmatrix} \frac{n}{\gamma} + \frac{k}{\sigma_\epsilon^2} & \frac{n\bar{X}}{\gamma} + \frac{kX_0}{\sigma_\epsilon^2} & \frac{k\beta}{\sigma_\epsilon^2} & 0 \\ \frac{n\bar{X}}{\gamma} + \frac{kX_0}{\sigma_\epsilon^2} & \frac{\sum_{i=1}^n X_i^2}{\gamma} + \frac{2n\beta^2\sigma_\delta^4}{\gamma^2} + \frac{kX_0^2}{\sigma_\epsilon^2} & \frac{k\beta X_0}{\sigma_\epsilon^2} & \frac{n\beta\sigma_\delta^2}{\gamma^2} \\ \frac{k\beta}{\sigma_\epsilon^2} & \frac{k\beta X_0}{\sigma_\epsilon^2} & \frac{k\beta^2}{\sigma_\epsilon^2} & 0 \\ 0 & \frac{n\beta\sigma_\delta^2}{\gamma^2} & 0 & \frac{n}{2\gamma^2} + \frac{k}{2\sigma_\epsilon^2} \end{pmatrix}, \quad (2.18)$$

where γ is defined in (2.12).

The large sample variance of \hat{X}_0 follows by inverting the Fisher information matrix and is given by

$$V(\hat{X}_0) = \frac{\sigma_\epsilon^2}{\beta^2} \left[\frac{1}{k} + \frac{\gamma}{n\sigma_\epsilon^2} + \frac{\gamma}{\sigma_\epsilon^2} E \right], \quad (2.19)$$

where,

$$E = \frac{nX_0^2\sigma_\epsilon^4 + kX_0^2\gamma^2 - 2nX_0\bar{X}\sigma_\epsilon^4 - 2kX_0\bar{X}\gamma^2 + n\bar{X}^2\sigma_\epsilon^4 + k\bar{X}^2\gamma^2}{(n\sigma_\epsilon^4 + k\gamma^2) \sum_{i=1}^n X_i^2 + 2nk\beta^2\gamma\sigma_\delta^4 - n^2\bar{X}^2\sigma_\epsilon^4 - nk\bar{X}^2\gamma^2}.$$

Notice that if $\sigma_\delta^2 = 0$, the expression (2.19) is reduced to (1.6).

To construct a confidence interval for X_0 , for both cases σ_δ^2 *unknown* and *known*, we consider the interval (1.10), where $\hat{V}(\hat{X}_{0C})$ is the estimated variance that follows from (2.13), (2.15) or (2.19).

3 Simulation study

In this section we present a simulation study for both cases of the homoscedastic controlled calibration model: σ_δ^2 known and unknown. The objective of this section is to study the performance of the estimators of the proposed model (Proposed-M) and verify the impact by considering erratically the usual model (Usual-M).

It was considered 5000 samples generated from the homoscedastic controlled calibration model. In all samples, the value of the parameters α and β were 0.1 and 2, respectively. The range of values for the controlled variable was [0,2]. The fixed values for the controlled variable were $x_1 = 0$, $x_i = x_{i-1} + \frac{2}{n-1}$, $i = 2, \dots, n$, and the parameter values X_0 were 0.01 (extreme inferior value), 0.8 (near to the central value) and 1.9 (extreme superior value). It was considered $\sigma_\epsilon^2 = 0.04$ and the parameter values of σ_δ^2 were 0.01 and 0.1, which are named, respectively, as small and large variances. For the first and second stages we consider the sample of sizes $n = 5, 20, 100$ and $k = 2, 20, 100$, respectively.

The empirical mean bias is given by $\sum_{j=1}^{5000} (\hat{X}_0 - X_0)/5000$ and the empirical mean squared error (MSE) is given by $\sum_{j=1}^{5000} (\hat{X}_0 - X_0)^2/5000$. The mean estimated variance of \hat{X}_0 is given by $\sum_{j=1}^{5000} \hat{V}(\hat{X}_0)/5000$, with $\hat{V}(\hat{X}_0) = \hat{V}_1(\hat{X}_0)$ or $\hat{V}_2(\hat{X}_0)$, where $\hat{V}_1(\hat{X}_0)$ is the estimated variance of (1.6), (2.13) or (2.19) and $\hat{V}_2(\hat{X}_0)$ is the estimated variance of (2.15). The theoretical variances of \hat{X}_0 denoted as $V_1(\hat{X}_0)$ and $V_2(\hat{X}_0)$, are referred, respectively, to the expressions (1.6), (2.13) or (2.19) and (2.15) evaluated on the relevant parameter values. In Appendix B it is presented the simulation results.

Tables B1, B2, B5 and B6 present the empirical bias, the empirical mean squares error, the theoretical variance and the estimated variance of X_0 . In these tables, it is considered only the variance (1.6) of the usual model, because based on a simulation study in [15] it was shown that the variances (1.6) and (1.8) give similar results.

Tables B3, B4 and B7 present the covering percentages and the confidence interval amplitudes constructed with a 95% confidence level for the parameter X_0 . In Table B3, the covering percentages $\%_1$ and $\%_2$ and amplitudes A_1 and

A_2 are referred to the confidence intervals constructed using the equations (2.13) and (2.19).

Tables B1-B4 consider the homoscedastic controlled calibration model assuming that σ_f^2 is unknown.

In Table B1 the empirical bias and MSE of \hat{X}_0 are little and an addition in the size of the variance σ_f^2 , described in Table B2, causes an increasing in the bias and MSE. Moreover, we have that the bias and MSE of \hat{X}_0 are smaller when X_0 is near to the center value of the variation interval of the variable X . These tables show that for all n, k and X_0 , the theoretical variances obtained using the expressions (2.19) and (2.15) are equal. This fact occurs also for the mean estimated variances. We verify also that when $n \geq 20$ and $k \geq 20$ the theoretical variances and the mean estimated variances from the proposed model are approximately equal. Observing these tables, we can also notice that there exists differences between the mean estimated variances of the usual and proposed models.

Analyzing Tables B3 and B4, we observe that for all n and X_0 when it is adopted erratically the usual model, the amplitudes decrease very much as the size of k increases. This causes the covering percentage to decrease moving away from 95%. Whereas, adopting the proposed model it is observed that when k increases the confidence interval amplitude decreases, but the covering percentages increase approaching 95%. Notice that the covering percentage $\%_1$ and $\%_2$ and the amplitudes A_1 and A_2 are approximately equal, the amplitudes are very small for $X_0 = 0.8$. In these tables, we observe that when $k = 20$ or 100 and when n increases the amplitudes of the intervals decrease and the covering percentages approaches 95%. In most cases, the covering percentage obtained through the proposed model are greater than that for the usual model results and are close to 95%.

Tables B5 and B7 describe the results for the controlled homoscedastic calibration model with σ_f^2 known. The iterative method Quasi-Newton [14] has been used.

In Tables B5 and B6 we have that the empirical bias and SME decrease as the size of n or k increase and they are small when X_0 is near to the central value of the variation interval, $X_0 = 0.8$. When σ_f^2 is small (Table B5), for all n and k , the empirical values of MSE from the usual and proposed model are close to the theoretical variance, but only the mean estimated variance from the proposed model is close to the theoretical variance. When σ_f^2 is large (Table B6), in general, the empirical MSE and the mean estimated variance from the usual and proposed model are different, but the values supplied by the proposed model are very close to the theoretical variance.

Analyzing Table B7, we can make similar comments to the ones we made about Tables B3 and B4.

4 Application

In this section we test our model, considering both cases σ_δ known and unknown, using the data supplied by the chemical laboratory of the "Instituto de Pesquisas Tecnológicas (IPT)" - Brasil. We also consider the usual model in order to observe the performance of the proposed model. Our main interest is to estimate the unknown concentration value X_0 of two samples A and B of the chemical elements chromo and cadmium.

Tables 1 and 4 present the fixed values of concentration of the standard solutions and the corresponding intensities for the chromo and cadmium element, respectively, which are supplied by the plasma spectrometry method. This data is referred to as the first stage of the calibration model.

Tables 2 and 5 present the intensities corresponding to 3 sample solutions from the sample A and B. This data is referred to as the second stage of the calibration model.

Tables 3 and 6 describe the estimates of α , β , X_0 , $V(\hat{X}_0)$, σ_δ^2 and the confidence interval amplitude $U(X_0)$ from the homoscedastic controlled calibration model of the samples A and B for the chemical elements chromo and cadmium. The values of the variance σ_δ^2 considered as known are obtained from an external study carried out by the IPT, which are $\sigma_\delta^2 = 2,5865E - 06$ for the chromo element and $\sigma_\delta^2 = 0.0017E + 02$ for the cadmium element. As seen in Section 2, in order to obtain the estimates of the parameters β and σ_δ^2 of the proposed model when σ_δ^2 is known, iterative methods are required. In order to solve the system of equations (2.16) and (2.17) it was used the Quasi-Newton iterative method. It is also presented the estimates from the usual model. The estimates of the variance of \hat{X}_0 are computed using the relevant expressions (1.6), (2.13) or (2.19). The amplitude $U(X_0)$ is given by the product of the squared root of the estimated variance of \hat{X}_0 and 1.96.

In Tables 3 and 6 we can observe that the estimates of α and β supplied by the usual model is equal to the proposed model when σ_δ^2 is unknown and they are equal for samples A and B, this occurs because the expression of the estimators $\hat{\alpha}$ and $\hat{\beta}$ of both models are equal and they only depend on the first stage of the calibration model. These estimates are slightly different when compared with the estimates from the proposed model when σ_δ^2 is known. With respect to the estimate of X_0 , we observe that there is no difference of the estimates supplied by the usual and the proposed models of the chromo and cadmium element in both samples A and B, respectively. The estimates of the concentration of the sample A, of the elements chromo and cadmium, are outside of the variation range of the standard solution concentrations. We verify that, except to the sample B of the cadmium element, the estimates of the variance of \hat{X}_0 and the amplitude $U(X_0)$ from the usual model are greater than the estimates supplied by the both proposed models.

Table 1: Concentration (mg/g) and intensity of the standard solutions of cromo element.

X_i	Intensity
0,05	6455,900
0,11	13042,933
0,26	32621,733
0,79	97364,500
1,05	129178,100

Table 2: Intensity of the sample solutions A and B of cromo element.

Intensity	
Sample A	Sample B
1465,0	10173,6
1351,0	10516,9
1495,6	10352,2

Table 3: Estimates of α , β , X_0 , $V(\hat{X}_0)$ and the confidence interval amplitude $U(X_0)$ from the usual and proposed model for the samples A and B of cromo element.

Parameters	Sample A			Sample B		
	Usual-M	Proposed-M		Usual-M	Proposed-M	
		unknown σ_i^2	known σ_i^2		unknown σ_i^2	known σ_i^2
α	123,574	123,571	123,889	123,574	123,574	124,021
β	1,23E+05	1,23E+05	1,23E+05	1,23E+05	1,23E+05	1,23E+05
X_0	0,011	0,011	0,011	0,083	0,083	0,083
$V(\hat{X}_0)$	9,80E-07	9,15E-07	1,35E-06	1,16E-06	1,13E-06	1,71E-06
σ_i^2	-	1,00E-06	-	-	5,48E-07	-
$U(\hat{X}_0)$	2,55E-03	2,46E-03	2,99E-03	2,77E-03	2,73E-03	3,36E-03

Table 4: Concentration (mg/g) and intensity of the standard solutions of cadmium element.

X_i	Intensity
0.05	4,89733
0.10	9,706
0,25	23,41333
0.73	69,73
1.01	96,85667

Table 5: Intensity of the sample solutions A and B of cadmium element.

Intensity	
Sample A	Sample B
0,679	5,066
0,6837	5,027
0,6846	5,085

Table 6: Estimates of α , β , X_0 , $V(\hat{X}_0)$ and the confidence interval amplitude $U(X_0)$ from the usual and homoscedastic models for the samples A and B of cadmium element.

Parameters	Sample A			Sample B		
	Usual-M	Proposed-M		Usual-M	Proposed-M	
		unknown σ_1^2	known σ_1^2		unknown σ_1^2	known σ_1^2
α	-0,156	-0,156	-0,158	-0,156	-0,156	-0,158
β	95,828	95,828	95,831	95,828	95,828	95,831
X_0	8,75E-03	8,75E-03	8,77E-03	0,054	0,054	0,054
$V(\hat{X}_0)$	4,06E-06	3,72E-06	1,26E-06	3,81E-06	3,32E-06	1,17E-06
σ_0^2	-	8,31E-06	-	-	8,24E-06	-
$U(\hat{X}_0)$	5,18E-03	4,96E-03	2,89E-03	5,02E-03	4,68E-03	2,78E-03

5 Concluding remarks

In general, the simulation study reveals that the proposed model is sensible to the presence of error related to the independent variable and gives better results in contrast to the usual model results. It was noticed that when the error variance σ_1^2 increases, the mean estimated variance of \hat{X}_0 obtained using the usual model moves away from the theoretical value. In the example above, the confidence interval amplitude from the proposed models are supplied by the incorporation of error due to the lecture of equipment and the preparation of the standard solutions. It is observed that despite the classical model only considers the error originated from the lecture of the equipment, the amplitude is greater than the obtained by the new approach.

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Appendix

A Bias and variance for the maximum likelihood estimator

In the following we derive the bias (2.14) and the variance (2.15) of the estimator \hat{X}_0 from the homoscedastic controlled calibration model when σ_ϵ^2 is known.

Considering the model (2.1) and (2.2), the estimator $\hat{X}_0 = (\bar{Y}_0 - \hat{\alpha})/\hat{\beta}$ can be expressed as

$$\hat{X}_0 = \bar{X} + \frac{\beta(X_0 - \bar{X}) + \bar{\epsilon}_0 - \bar{\phi}}{\hat{\beta}}, \quad (\text{A.1})$$

where $\bar{\epsilon}_0 = \sum_{i=n+1}^{n+k} \epsilon_i/k$ and $\bar{\phi} = \sum_{i=1}^n (\epsilon_i - \beta\delta_i)/n$.

Considering k fixed, expanding $1/\hat{\beta}$ in a Taylor series around β and ignoring terms of order less than n^{-2} , we obtain the expected value of (A.1), given by

$$E(\hat{X}_0) = X_0 + \frac{\gamma(\bar{X} - X_0)}{n\beta^2 S_{XX}}. \quad (\text{A.2})$$

From this last equation we get the bias (2.14).

To derive the variance (2.15) we take the variance of (A.1), which is given by

$$V(\hat{X}_0) = \beta^2(X_0 - \bar{X})^2 V\left(\frac{1}{\hat{\beta}}\right) + V\left(\frac{\bar{\epsilon}_0}{\hat{\beta}}\right) + V\left(\frac{\bar{\phi}}{\hat{\beta}}\right). \quad (\text{A.3})$$

We call attention to the fact that (A.3) is only expressed as a function of the related variances because the corresponding covariances are zero. The variances $V(1/\hat{\beta})$, $V(\bar{\epsilon}_0/\hat{\beta})$ and $V(\bar{\phi}/\hat{\beta})$ can be obtained by expanding $1/\hat{\beta}$, $\bar{\epsilon}_0/\hat{\beta}$ and $\bar{\phi}/\hat{\beta}$ in a Taylor series around β and ignoring terms of order less than n^{-2} . They are given by

$$V(1/\hat{\beta}) = \frac{V(\hat{\beta})}{\beta^4}, \quad (\text{A.4})$$

$$V(\bar{\epsilon}_0/\hat{\beta}) = \frac{\sigma_\epsilon^2}{k\beta^2} + 3\frac{\sigma_\epsilon^2}{k\beta^4} V(\hat{\beta}), \quad (\text{A.5})$$

$$V(\bar{\phi}/\hat{\beta}) = \frac{\gamma}{n\beta^2}. \quad (\text{A.6})$$

Substituing (A.4), (A.5) and (A.6) in (A.3), then, the variance (2.15) is obtained.

B Tables

Table B1. Empirical bias and mean squared error, theoretical variance and the mean estimated variance of \hat{X}_0 , for $\sigma_0^2 = 0,01$ and unknown.

X_0	n	k	Empirical		Theoretical		Mean of $V(X_0)$			
			Bias	MSE	Proposed-M		Usual-M			
					$V_1(X_0)$	$V_2(X_0)$	$V_1(X_0)$	$V_1(X_0)$	$V_2(X_0)$	
0,01	5	2	-0,0060	0,0180	0,0170	0,0170	0,0120	0,0100	0,0100	
		20	-0,0087	0,0130	0,0120	0,0120	0,0072	0,0120	0,0120	
		100	-0,0060	0,0130	0,0120	0,0120	0,0065	0,0120	0,0120	
	20	2	-0,0038	0,0086	0,0087	0,0087	0,0120	0,0052	0,0053	
		20	-0,0028	0,0043	0,0042	0,0042	0,0033	0,0040	0,0040	
		100	-0,0032	0,0038	0,0038	0,0038	0,0022	0,0036	0,0036	
	100	2	-0,0023	0,0058	0,0058	0,0058	0,0100	0,0027	0,0027	
		20	-0,0002	0,0013	0,0013	0,0013	0,0016	0,0012	0,0012	
		100	-0,0007	0,0008	0,0009	0,0009	0,0007	0,0009	0,0009	
	0,8	5	2	-0,0011	0,0091	0,0093	0,0094	0,0079	0,0045	0,0046
			20	-0,0034	0,0050	0,0048	0,0048	0,0029	0,0045	0,0046
			100	-0,0007	0,0047	0,0044	0,0044	0,0024	0,0045	0,0045
20		2	0,0005	0,0063	0,0061	0,0061	0,0095	0,0028	0,0029	
		20	0,0007	0,0016	0,0016	0,0016	0,0015	0,0015	0,0015	
		100	-0,0001	0,0012	0,0012	0,0012	0,0008	0,0012	0,0012	
100		2	0,0005	0,0050	0,0052	0,0052	0,0099	0,0021	0,0021	
		20	-0,0001	0,0007	0,0007	0,0007	0,0011	0,0007	0,0007	
		100	-0,0003	0,0003	0,0003	0,0003	0,0003	0,0003	0,0003	
1,9		5	2	0,0041	0,0160	0,0150	0,0160	0,0120	0,0093	0,0094
			20	0,0026	0,0110	0,0110	0,0110	0,0065	0,0110	0,0110
			100	0,0076	0,0110	0,0110	0,0110	0,0058	0,0110	0,0110
	20	2	0,0006	0,0079	0,0082	0,0082	0,0110	0,0049	0,0049	
		20	0,0010	0,0039	0,0037	0,0037	0,0030	0,0035	0,0035	
		100	0,0008	0,0033	0,0033	0,0033	0,0019	0,0031	0,0031	
	100	2	0,0020	0,0057	0,0057	0,0057	0,0100	0,0025	0,0025	
		20	0,0003	0,0012	0,0012	0,0012	0,0015	0,0011	0,0011	
		100	0,0003	0,0008	0,0008	0,0008	0,0006	0,0008	0,0008	

Table B2. Empirical bias and mean squared error, theoretical variance and the mean estimated variance of \hat{X}_0 , for $\sigma_\beta^2 = 0, 1$ and unknown.

X_0	n	k	Empirical		Theoretical		Mean of $V(\hat{X}_0)$			
			Bias	MSE	Proposed-M		Usual-M	Proposed-M		
					$V_1(X_0)$	$V_2(X_0)$		$V_1(X_0)$	$V_2(X_0)$	
0,01	5	2	-0,0510	0,1000	0,0700	0,0710	0,0770	0,0680	0,0690	
		20	-0,0500	0,0950	0,0660	0,0660	0,0220	0,0660	0,0660	
		100	-0,0510	0,0950	0,0650	0,0650	0,0130	0,0730	0,0730	
	20	2	-0,0180	0,0280	0,0250	0,0250	0,0670	0,0240	0,0240	
		20	-0,0160	0,0230	0,0210	0,0210	0,0140	0,0210	0,0210	
		100	-0,0170	0,0230	0,0200	0,0200	0,0055	0,0210	0,0210	
	100	2	-0,0016	0,0094	0,0093	0,0093	0,0580	0,0069	0,0069	
		20	-0,0026	0,0048	0,0018	0,0048	0,0082	0,0048	0,0048	
		100	-0,0033	0,0043	0,0044	0,0044	0,0029	0,0044	0,0044	
	0,8	5	2	-0,0084	0,0370	0,0290	0,0290	0,0460	0,0250	0,0250
			20	-0,0095	0,0270	0,0240	0,0240	0,0071	0,0200	0,0200
			100	-0,0072	0,0290	0,0240	0,0240	0,0037	0,0200	0,0200
20		2	-0,0030	0,0120	0,0110	0,0110	0,0530	0,0085	0,0086	
		20	-0,0040	0,0068	0,0066	0,0066	0,0061	0,0064	0,0064	
		100	-0,0031	0,0063	0,0062	0,0062	0,0017	0,0060	0,0060	
100		2	-0,0011	0,0063	0,0062	0,0063	0,0550	0,0038	0,0038	
		20	-0,0015	0,0017	0,0017	0,0017	0,0057	0,0017	0,0017	
		100	-0,0011	0,0014	0,0013	0,0013	0,0013	0,0013	0,0013	
1,9		5	2	0,0430	0,1090	0,0630	0,0630	0,0830	0,0750	0,0750
			20	0,0450	0,0860	0,0530	0,0530	0,0210	0,0650	0,0650
			100	0,0410	0,0860	0,0530	0,0530	0,0110	0,0600	0,0600
	20	2	0,0160	0,0260	0,0230	0,0230	0,0650	0,0210	0,0210	
		20	0,0140	0,0190	0,0180	0,0180	0,0130	0,0180	0,0180	
		100	0,0170	0,0200	0,0150	0,0130	0,0048	0,0180	0,0180	
	100	2	0,0050	0,0088	0,0087	0,0088	0,0570	0,0063	0,0063	
		20	0,0030	0,0013	0,0012	0,0012	0,0078	0,0042	0,0042	
		100	0,0020	0,0039	0,0038	0,0038	0,0026	0,0038	0,0038	

Table B3. Covering percentage (%) and amplitude (A) of the intervals with a 95% confidence level for the parameter X_0 , when $\sigma_\delta^2 = 0,01$ and unknown.

X_0	n	k	Usual-M		Proposed-M			
			%	A	% ₁	A ₁	% ₂	A ₂
0,01	5	2	83,01	0,40	79,34	0,36	79,37	0,36
		20	84,95	0,32	91,15	0,41	91,15	0,41
		100	83,72	0,31	92,24	0,42	92,24	0,42
	20	2	96,46	0,42	83,48	0,28	83,52	0,28
		20	90,19	0,22	92,47	0,24	92,47	0,24
		100	86,16	0,18	92,78	0,23	92,78	0,23
	100	2	98,84	0,40	73,16	0,19	73,16	0,19
		20	96,71	0,16	94,14	0,14	94,14	0,14
		100	91,90	0,11	94,68	0,12	94,68	0,12
0,8	5	2	85,43	0,32	74,33	0,24	74,39	0,24
		20	85,16	0,21	91,34	0,26	91,34	0,26
		100	85,01	0,19	92,50	0,25	92,50	0,25
	20	2	97,90	0,38	73,55	0,20	73,55	0,20
		20	93,55	0,15	93,89	0,15	93,89	0,15
		100	86,53	0,11	93,12	0,13	93,12	0,13
	100	2	99,41	0,39	65,05	0,16	65,05	0,16
		20	98,51	0,13	91,05	0,10	94,05	0,10
		100	91,56	0,07	94,86	0,07	94,86	0,07
1,9	5	2	82,17	0,39	76,05	0,35	78,13	0,35
		20	84,50	0,31	90,92	0,39	90,92	0,39
		100	84,75	0,29	92,83	0,39	92,83	0,39
	20	2	96,79	0,41	83,09	0,26	83,11	0,26
		20	91,32	0,21	93,29	0,23	93,31	0,23
		100	86,43	0,17	93,32	0,22	93,32	0,22
	100	2	98,88	0,10	73,06	0,19	73,06	0,19
		20	97,12	0,15	94,31	0,13	94,31	0,13
		100	92,56	0,10	94,74	0,11	94,74	0,11

Table B4. Covering percentage (%) and amplitude (A) of the intervals with a 95% confidence level for the parameter X_0 , when $\sigma_0^2 = 0, 1$ and unknown.

X_0	n	k	Usual-M		Proposed-M			
			%	A	% ₁	A ₁	% ₂	A ₂
0,01	5	2	84,89	0,94	80,73	0,85	80,79	0,86
		20	64,10	0,51	82,75	0,86	82,75	0,86
		100	52,09	0,39	82,42	0,86	82,42	0,86
	20	2	99,10	0,99	91,04	0,58	91,10	0,58
		20	87,10	0,45	92,60	0,55	92,62	0,55
		100	65,70	0,28	92,16	0,55	92,18	0,55
	100	2	100,00	0,94	87,60	0,32	87,66	0,32
		20	98,82	0,36	94,88	0,27	94,88	0,27
		100	89,12	0,21	94,84	0,26	94,84	0,26
0,8	5	2	90,27	0,73	80,63	0,52	80,75	0,52
		20	64,39	0,31	82,68	0,51	82,74	0,51
		100	50,57	0,23	84,08	0,50	84,08	0,50
	20	2	99,92	0,88	87,30	0,35	87,50	0,35
		20	91,80	0,30	92,78	0,31	92,82	0,31
		100	67,46	0,16	92,38	0,30	92,38	0,30
	100	2	100,00	0,91	77,88	0,22	77,98	0,22
		20	99,91	0,29	94,98	0,16	95,04	0,16
		100	91,60	0,14	94,92	0,14	94,92	0,14
1,9	5	2	85,63	0,91	81,12	0,81	81,42	0,81
		20	61,71	0,49	81,89	0,82	81,89	0,82
		100	50,71	0,37	81,24	0,81	81,24	0,81
	20	2	99,51	0,97	91,12	0,54	91,18	0,55
		20	88,10	0,13	92,74	0,52	92,76	0,52
		100	66,11	0,26	92,86	0,51	92,86	0,51
	100	2	100,00	0,93	86,38	0,30	86,38	0,30
		20	99,12	0,35	94,76	0,25	94,76	0,25
		100	89,10	0,20	95,00	0,24	95,00	0,24

Table B5. Empirical bias and mean squared error, theoretical variance and the mean estimated variance of \hat{X}_0 , for $\sigma_0^2 = 0, 01$ and known.

X_0	n	k	Empirical				Theoretical	Mean of $V(X_0)$		
			Usual-M		Proposed-M		Proposed-M	Usual-M	Proposed-M	
			Bias	MSE	Bias	MSE	$V(X_0)$			
0,01	5	2	-0,0290	0,0210	-0,0280	0,0210	0,0170	0,0180	0,0160	
		20	-0,0290	0,0140	-0,0320	0,0140	0,0120	0,0081	0,0130	
		100	-0,0240	0,0140	-0,0270	0,0140	0,0120	0,0070	0,0130	
	20	2	-0,0081	0,0091	-0,0064	0,0090	0,0086	0,0130	0,0076	
		20	-0,0060	0,0043	-0,0072	0,0043	0,0041	0,0034	0,0041	
		100	-0,0038	0,0038	-0,0060	0,0038	0,0037	0,0022	0,0038	
	100	2	-0,0011	0,0056	-0,0005	0,0056	0,0058	0,0100	0,0053	
		20	-0,0002	0,0013	-0,0001	0,0013	0,0013	0,0016	0,0012	
		100	-0,0009	0,0009	-0,0012	0,0009	0,0009	0,0007	0,0009	
	0,8	5	2	-0,0074	0,0110	-0,0072	0,0100	0,0093	0,0120	0,0085
			20	-0,0046	0,0051	-0,0051	0,0052	0,0048	0,0032	0,0049
			100	-0,0076	0,0048	-0,0082	0,0048	0,0044	0,0025	0,0046
20		2	-0,0034	0,0063	-0,0031	0,0063	0,0061	0,0100	0,0052	
		20	0,0001	0,0016	0,0000	0,0016	0,0016	0,0015	0,0016	
		100	-0,0009	0,0012	-0,0013	0,0012	0,0012	0,0008	0,0012	
100		2	0,0000	0,0053	0,0002	0,0053	0,0052	0,0099	0,0048	
		20	0,0000	0,0007	0,0000	0,0007	0,0007	0,0011	0,0007	
		100	-0,0001	0,0003	-0,0002	0,0003	0,0003	0,0003	0,0003	
1,9		5	2	0,0200	0,0180	0,0200	0,0180	0,0150	0,0170	0,0140
			20	0,0240	0,0120	0,0260	0,0130	0,0110	0,0071	0,0120
			100	0,0200	0,0130	0,0230	0,0130	0,0100	0,0062	0,0110
	20	2	0,0037	0,0032	0,0021	0,0031	0,0082	0,0120	0,0071	
		20	0,0059	0,0037	0,0066	0,0037	0,0037	0,0030	0,0036	
		100	0,0033	0,0032	0,0051	0,0032	0,0032	0,0020	0,0033	
	100	2	0,0020	0,0058	0,0015	0,0057	0,0057	0,0100	0,0053	
		20	0,0003	0,0012	0,0002	0,0012	0,0012	0,0015	0,0011	
		100	0,0003	0,0008	0,0006	0,0008	0,0008	0,0006	0,0008	

Table B6. Empirical bias and mean squared error, theoretical variance and the mean estimated variance of \hat{X}_0 , for $\sigma_\delta^2 = 0, 1$ and known.

X_0	n	k	Empirical				Theoretical	Mean of $V(X_0)$		
			Usual-M		Proposed-M		Proposed-M	Usual-M	Proposed-M	
			Bias	MSE	Bias	MSE	$V(X_0)$			
0,01	5	2	-0,4330	0,5590	-0,3830	0,4580	0,0590	0,3650	0,2310	
		20	-0,1140	0,1310	0,1140	1,0880	0,0540	0,0250	0,0760	
		100	-0,1890	0,1540	-0,0290	0,7730	0,0540	0,0200	0,1250	
	20	2	-0,0930	0,0430	-0,0770	0,0360	0,0210	0,0950	0,0380	
		20	-0,0490	0,0210	-0,0510	0,0210	0,0160	0,0150	0,0180	
		100	-0,0430	0,0190	-0,0250	0,0640	0,0150	0,0058	0,0170	
	100	2	-0,0200	0,0110	-0,0160	0,0097	0,0084	0,0630	0,0110	
		20	-0,0077	0,0041	-0,0085	0,0039	0,0037	0,0084	0,0038	
		100	-0,0066	0,0037	-0,0087	0,0037	0,0033	0,0029	0,0033	
	0,8	5	2	-0,0500	0,0620	-0,0130	0,0550	0,0280	0,1150	0,0620
			20	-0,0450	0,0380	0,0820	0,0810	0,0240	0,0086	0,0320
			100	-0,0530	0,0510	-0,0069	0,0980	0,0230	0,0055	0,0360
20		2	-0,0280	0,0150	-0,0240	0,0140	0,0110	0,0740	0,0210	
		2	-0,0079	0,0068	-0,0085	0,0069	0,0064	0,0065	0,0067	
		100	-0,0055	0,0065	-0,0030	0,0079	0,0060	0,0018	0,0062	
100		2	-0,0030	0,0067	-0,0021	0,0065	0,0062	0,0600	0,0091	
		20	-0,0018	0,0018	-0,0018	0,0017	0,0017	0,0058	0,0017	
		100	-0,0021	0,0013	-0,0025	0,0013	0,0013	0,0013	0,0013	
1,9		5	2	0,3480	0,3770	0,3070	0,3000	0,0530	0,2850	0,1760
			20	0,1400	0,1630	-0,3310	0,9370	0,0490	0,0300	0,0780
			100	0,0410	0,0180	0,0270	0,0510	0,0140	0,0051	0,0150
	20	2	0,0970	0,0430	0,0790	0,0350	0,0190	0,0930	0,0350	
		20	0,1400	0,1630	-0,3310	0,9370	0,0490	0,0300	0,0780	
		100	0,1670	0,1300	-0,0005	0,7090	0,0480	0,0160	0,1120	
	100	2	0,0200	0,0093	0,0160	0,0087	0,0080	0,0620	0,0110	
		20	0,0120	0,0039	0,0130	0,0037	0,0033	0,0080	0,0035	
		100	0,0072	0,0031	0,0089	0,0031	0,0029	0,0027	0,0030	

Table B7. Covering percentage (%) and amplitude (A) of the intervals with a 95% confidence level for the parameter X_0 , when $\sigma_x^2 = 0,01$, and 0,1 and known.

X_0	n	k	$\sigma_x^2 = 0,01$				$\sigma_x^2 = 0,1$			
			Usual-M		Proposed-M		Usual-M		Proposed-M	
			%	A	%	A	%	A	%	A
0,01	5	2	92,10	0,51	91,20	0,18	95,06	1,89	92,40	1,49
		20	87,32	0,34	95,18	0,44	63,38	0,59	64,47	1,09
		100	81,50	0,32	95,19	0,44	52,69	0,48	89,24	1,18
	20	2	97,46	0,43	90,12	0,33	99,87	1,17	96,27	0,71
		20	91,00	0,23	94,03	0,25	92,76	0,48	94,48	0,52
		100	86,73	0,19	95,21	0,24	70,38	0,30	90,35	0,51
	100	2	97,01	0,43	90,00	0,33	100,00	0,98	93,41	0,40
		20	92,34	0,23	95,26	0,25	99,77	0,36	95,09	0,24
		100	85,93	0,19	94,55	0,24	92,70	0,21	94,42	0,23
0,8	5	2	94,33	0,41	89,28	0,35	98,77	1,31	97,54	0,98
		20	86,84	0,22	95,03	0,27	61,85	0,34	81,25	0,69
		100	85,65	0,19	95,56	0,27	49,29	0,27	87,82	0,69
	20	2	98,35	0,39	88,41	0,27	100,00	1,03	94,09	0,53
		20	93,84	0,15	91,41	0,15	94,44	0,32	95,11	0,32
		100	85,98	0,11	91,32	0,14	70,38	0,17	92,41	0,31
	100	2	98,08	0,39	88,22	0,27	100,00	0,95	92,25	0,34
		20	92,75	0,15	91,96	0,15	99,89	0,30	94,89	0,16
		100	87,17	0,11	91,60	0,14	95,00	0,14	94,88	0,14
1,9	5	2	92,30	0,50	90,61	0,16	96,26	1,78	92,14	1,45
		20	86,96	0,33	95,13	0,42	63,58	0,56	67,24	1,03
		100	85,84	0,30	94,73	0,42	49,30	0,46	83,75	1,21
	20	2	97,61	0,43	89,92	0,32	100,00	1,17	96,27	0,70
		20	91,60	0,21	91,27	0,23	94,26	0,46	94,95	0,49
		100	86,16	0,17	91,99	0,23	72,44	0,28	94,18	0,48
	100	2	97,04	0,43	89,70	0,32	100,00	0,97	94,27	0,39
		20	91,21	0,21	93,85	0,23	99,59	0,35	95,18	0,23
		100	87,04	0,17	93,11	0,23	93,38	0,20	94,98	0,21

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