

Limiting one-point distribution of periodic TASEP

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Abstract

The relaxation time limit of the one-point distribution of the spatially periodic totally asymmetric simple exclusion process is expected to be the universal one point distribution for the models in the KPZ universality class in a periodic domain. Unlike the infinite line case, the limiting one point distribution depends non-trivially on the scaled time parameter. We study several properties of this distribution for the case of the periodic step and flat initial conditions. We show that the distribution changes from a Tracy-Widom distribution in the small time limit to the Gaussian distribution in the large time limit, and also obtain right tail estimate for all time. Furthermore, we establish a connection to integrable differential equations such as the KP equation, coupled systems of mKdV and nonlinear heat equations, and the KdV equation.

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1 Introduction

The scaled height field of the models in the KPZ universality class is expected to converge to a universal field in the large time limit. The limit, the KPZ fixed point, was constructed recently by Matetski, Quastel and Remenik, [32] and also by Dauvergne, Ortmann and Virag [17]. For the so-called step initial condition, the one-point marginal F_{KPZ} of the KPZ fixed point is given by (see, for example, [7, 28, 42, 5, 15]) the scaled GUE Tracy-Widom distribution

$$F_{\text{KPZ}}(x; \tau, \gamma) = F_{\text{GUE}}\left(\frac{x}{\tau^{1/3}} + \frac{\gamma^2}{4\tau^{4/3}}\right) \quad (1.1)$$

where τ, γ, x denote the time, location, and height parameters, respectively. From its expression it is apparent that F_{KPZ} is invariant under the KPZ re-scaling $(\tau, \gamma, x) \mapsto (\alpha^3\tau, \alpha^2\gamma, \alpha x)$ for all $\alpha > 0$.

In this paper, we study the analogue of the GUE Tracy-Widom distribution which arises when the infinite line is changed to a periodic domain. The spatial periodicity introduces the following new feature. Let L denote the period and t the time. For the models in the KPZ universality class, the height functions at two locations at the same time are critically correlated if the distance is $O(t^{2/3})$. Hence, in the periodic case, all points are critically correlated if $t = O(L^{3/2})$, which is called the relaxation time scale. Since the periodicity effect should diminish when $t \ll L^{3/2}$ and amplify when $t \gg L^{3/2}$, the scaled time parameter $\tau = tL^{-3/2}$ measures the effect of the periodicity. As a result, the relaxation time limit of the one-point distribution depends on τ non-trivially and it is not invariant under the KPZ re-scaling.

The relaxation time limit (for both one-point and multi-point distributions) was evaluated¹ for the periodic totally asymmetric simple exclusion process (TASEP) in [38, 8, 31, 9, 10]. Assume the periodic step initial condition; this means that for the fixed density of particles $\rho \in (0, 1)$, we impose at time 0 that consecutive ρL are sites occupied, the next $(1 - \rho)L$ unoccupied sites, and this pattern repeats, see Figure 1. The one-point distribution converges, as $t = \mathcal{O}(L^{3/2}) \rightarrow \infty$, to a distribution F independent of ρ . This limit was computed explicitly in a physics work [38] and a rigorous work [8], and it takes the form²

$$F(x; \tau, \gamma) = \oint e^{xA_1(z) + \tau A_2(z) + 2B(z)} \det(\mathbb{I} - \mathbb{K}_z) \frac{dz}{2\pi iz}. \quad (1.2)$$

The contour is a small circle enclosing the origin in the complex plane. The functions A_1, A_2, B are given in terms of polylog functions, and they are independent of the physical parameters τ, γ and x . The last term in the integral is a Fredholm determinant, and the operator $\mathbb{K}_z = \mathbb{K}_z(x, \gamma, \tau)$ depends on all the physical parameters x, γ, τ and also on the integration variable z . All these objects are introduced explicitly in Section 2.2.

It was shown that F is a distribution function. Since it is a limit for a model in a periodic domain, the distribution function $F(x; \tau, \gamma)$ is periodic in γ , and its period is normalized so that $F(x; \tau, \gamma+1) = F(x; \tau, \gamma)$. The function F is expected to be the universal relaxation time limit of the one-point distribution of the KPZ universality in a periodic domain for the periodic step initial condition. In other words, it is expected to be the marginal of the periodic KPZ fixed point. The goal of this paper is to study several properties of $F(x; \tau, \gamma)$.

¹See [26, 20, 36, 24, 25, 16, 37] for other properties of periodic models in the KPZ universality class.

²We follow the formula of [8]. The formula obtained in [38] has a different form but recently [39] verified that the two formulas are equivalent.

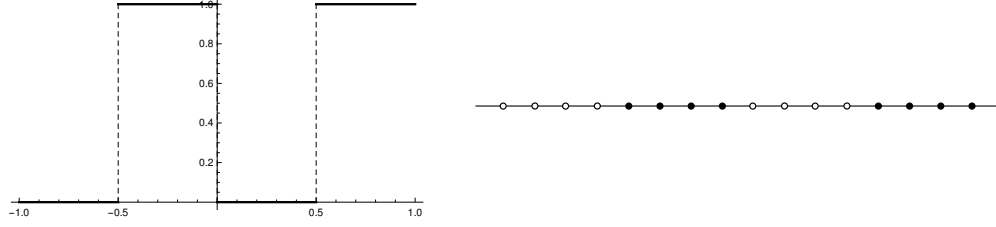


Figure 1: The density profile and particle configuration for periodic step initial condition when $\rho = 1/2$.

1.1 Analytic structure of F and F_{KPZ}

The invariance of F_{KPZ} through the KPZ re-scaling tells us that F_{KPZ} can be recast as a function of one single variable, namely (1.1), and all one needs to know about F_{KPZ} is encoded in F_{GUE} . In contrast, its periodic counterpart F does not enjoy the same invariance and truly depends on the three parameters (τ, γ, x) .

For a better comparison between F and F_{KPZ} , we unwrap the dependence of F_{KPZ} on the parameters (τ, γ, x) from F_{GUE} . Using the representation (1.1) the distribution F_{KPZ} takes the form

$$F_{\text{KPZ}}(x; \tau, \gamma) = \det(\mathbb{I} - \mathbb{K}_{\text{KPZ}})_{L^2(0, \infty)} = \det(\mathbb{I} - \mathbb{A}_{-\gamma} \mathbb{A}_{\gamma})_{L^2(0, \infty)} \quad (1.3)$$

where $\mathbb{K}_{\text{KPZ}} = \mathbb{A}_{-\gamma} \mathbb{A}_{\gamma}$, with \mathbb{A}_{γ} being the operator acting on $L^2(0, \infty)$ with the kernel \mathbf{A}_{γ} ,

$$\mathbf{A}_{\gamma}(s, t) = \mathcal{A}_{\gamma}(s + x + t)$$

and

$$\mathcal{A}_{\gamma}(s) = \mathcal{A}_{\gamma}(s; \tau) := \frac{e^{\frac{\gamma^3}{12\tau} + \frac{\gamma s}{2\tau}}}{\tau^{1/3}} \text{Ai}\left(\frac{s}{\tau^{1/3}} + \frac{\gamma^2}{4\tau^{4/3}}\right) = \frac{1}{2\pi i} \int_{\Lambda_-} e^{-\frac{\tau}{3}u^3 + \frac{\gamma}{2}u^2 + su} du. \quad (1.4)$$

Here Ai denotes the Airy function. Note that the function \mathcal{A}_{γ} satisfies the KPZ scaling invariance: $\mathcal{A}_{\gamma}(s; \tau) = \alpha^{-1} \mathcal{A}_{\alpha^2 \gamma}(\alpha s; \alpha^3 \tau)$. The kernel for the product operator \mathbb{K}_{KPZ} is

$$\mathbf{K}_{\text{KPZ}}(s, t) = \int_0^\infty \mathcal{A}_{-\gamma}(s + x + u) \mathcal{A}_{\gamma}(u + x + t) du, \quad s, t \geq 0.$$

In (1.4), Λ_- is any unbounded oriented contour from $e^{-i\theta_1}\infty$ to $e^{i\theta_2}\infty$ for some $\theta_1, \theta_2 \in (\pi/2, 5\pi/6)$; see Figure 2.

Let us now turn to a representation of F . The definition (1.2) obtained in [8] involves the operator \mathbb{K}_z which acts on the discrete space $\ell^2(\mathcal{S}_-)$, with (see Figure 2)³

$$\mathcal{S}_- = \mathcal{S}_-(z) := \{w \in \mathbb{C} \mid e^{-w^2/2} = z, \text{Re } w < 0\} = \{w = -\sqrt{-2 \log z + 4\pi i k}, k \in \mathbb{Z}\}. \quad (1.5)$$

This set is a discrete subset of the hyperbola

$$\Lambda_- = \Lambda_-(z) = \{w \in \mathbb{C} \mid |e^{-w^2/2}| = |z|, \text{Re } w < 0\} = \{w \in \mathbb{C} \mid \text{Re}(w^2) = -2 \log |z|, \text{Re } w < 0\}$$

which we could use for (1.4). Our first result is the following.

Lemma 1.1. *The identity*

$$\det(\mathbb{I} - \mathbb{K}_z)_{\ell^2(\mathcal{S}_-)} = \det(\mathbb{I} - \mathbb{T}_{-\gamma} \mathbb{T}_{\gamma})_{L^2(0, \infty)}$$

³The elements of the larger set $\mathcal{S}(z) := \{w \in \mathbb{C} \mid e^{-w^2/2} = z\}$ that contains \mathcal{S}_- are called Bethe roots since they arise in the Bethe ansatz analysis for the periodic TASEP.

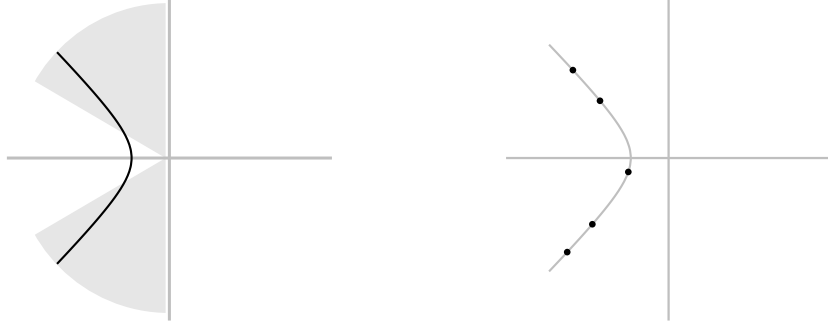


Figure 2: The left picture is an example of the contour Λ_- . The right picture is the discrete set \mathcal{S}_- .

holds true, where $\mathbb{T}_\gamma : L^2(0, \infty) \rightarrow L^2(0, \infty)$ is the trace class operator defined by its kernel

$$\mathbf{T}_\gamma(s, t) := \mathcal{T}_\gamma(s + x + t), \quad \mathcal{T}_\gamma(s) = \mathcal{T}_\gamma(s; \tau, z) := \sum_{\xi \in \mathcal{S}_-} \frac{e^{-\frac{\tau}{3}\xi^3 + \frac{\gamma}{2}\xi^2 + s\xi - Q(\xi)}}{-\xi}, \quad (1.6)$$

where $Q(\xi)$ is a polylog integral whose formula is given in (2.3).

We emphasize that $Q(\xi)$ does not depend on any of the parameters τ, γ, x and z . Its exact expression is not relevant at the moment. We also note that \mathcal{T}_γ depends on z through the set $\mathcal{S}_- = \mathcal{S}_-(z)$. Using the above lemma, (1.2) updates to

$$F(x; \tau, \gamma) = \oint e^{xA_1(z) + \tau A_2(z) + 2B(z)} \det(\mathbb{I} - \mathbb{T}_{-\gamma} \mathbb{T}_\gamma)_{L^2(0, \infty)} \frac{dz}{2\pi i z} \quad (1.7)$$

where the kernel for the product $\mathbb{T}_{-\gamma} \mathbb{T}_\gamma$ is

$$(s, t) \mapsto \int_0^\infty \mathcal{T}_{-\gamma}(s + x + u) \mathcal{T}_\gamma(u + x + t) du, \quad s, t \geq 0. \quad (1.8)$$

If we were to neglect the term Q in (1.6), the formula of $\mathcal{T}_\gamma(s)$ would be

$$\sum_{\xi \in \mathcal{S}_-} \frac{e^{-\frac{\tau}{3}\xi^3 + \frac{\gamma}{2}\xi^2 + s\xi}}{-\xi}. \quad (1.9)$$

The set \mathcal{S}_- is a discrete subset of Λ_- . The spacing between two neighboring points of \mathcal{S}_- is approximately $\frac{2\pi i}{-\xi}$. Hence, (1.9) is a discretization of the rescaled Airy function \mathcal{A}_γ in (1.4), and this discretization depends on the variable z because $\mathcal{S}_- = \mathcal{S}_-(z)$. Consequently, the formula (1.7) of F is a linear superposition of modified (due to Q) discrete versions of $F_{\text{KPZ}}(x; \tau, \gamma)$.

The formula (1.9) is a sum over a discrete set, so it is not invariant under the KPZ rescaling. However, the discrete set explains the spatial periodicity: observing that $e^{-\xi^2/2} = z$ for $\xi \in \mathcal{S}_-$ the identities

$$\mathcal{T}_{\gamma+1}(s) = z^{-1} \mathcal{T}_\gamma(s) \quad \text{and} \quad \mathcal{T}_{-\gamma-1}(s) = z \mathcal{T}_\gamma(s),$$

follow, and hence the product kernel (1.8) is invariant under $\gamma \mapsto \gamma + 1$.

1.2 Integrable differential equations

In the previous subsection, we discussed Airy-like operator formulas for $\det(\mathbb{I} - \mathbb{K}_z)$ and $\det(\mathbb{I} - \mathbb{K}_{\text{KPZ}})$. In Lemmas 2.2 and 2.3 we will show that both determinants also admit a representation in terms of so-called IKS-integrable operators, and these in turn can be canonically associated to Riemann-Hilbert problems. Exploring the connection of Riemann-Hilbert problems with integrable differential equations we obtain the next result.

Theorem 1.2. *The second log derivatives of the Fredholm determinants of \mathbb{K}_z and \mathbb{K}_{KPZ} decompose as*

$$\partial_{xx} \log \det(\mathbb{I} - \mathbb{K}_{\text{KPZ}}) = P_{\text{KPZ}}(\tau, \gamma, x) R_{\text{KPZ}}(\tau, \gamma, x) \quad \text{and} \quad \partial_{xx} \log \det(\mathbb{I} - \mathbb{K}_z) = P_{\text{per}}(\tau, \gamma, x) R_{\text{per}}(\tau, \gamma, x),$$

where $(p, r) = (P_{\text{KPZ}}, R_{\text{KPZ}})$ or $(P_{\text{per}}, R_{\text{per}})$ is a solution to the following two systems of differential equations.

(a) As a function of τ and x , they satisfy a system of coupled modified Korteweg-de Vries (mKdV) equations⁴

$$\begin{cases} 3p_\tau + p_{xxx} + 6prp_x = 0, \\ 3r_\tau + r_{xxx} + 6prr_x = 0. \end{cases} \quad (1.10)$$

(b) As a function of γ and x , they satisfy a system of coupled nonlinear heat equations

$$\begin{cases} p_\gamma = -p_{xx} - 2p^2r, \\ r_\gamma = r_{xx} + 2pr^2. \end{cases} \quad (1.11)$$

Finally, the symmetry property

$$p(\gamma) = -r(-\gamma) \quad (1.12)$$

also holds.

The coupled systems and the symmetry (1.12) imply that p itself solves non-local differential equations

$$3p_\tau(\gamma) + p_{xxx}(\gamma) - 6p(\gamma)p(-\gamma)p_x(\gamma) = 0 \quad (1.13)$$

and

$$p_\gamma(\gamma) + p_{xx}(\gamma) - 2p(\gamma)^2p(-\gamma) = 0. \quad (1.14)$$

For the particular case when $\gamma = 0$, which will be discussed in Theorem 8.4 for the periodic TASEP with flat initial condition, Equation (1.13) becomes the defocusing mKdV equation⁵ $3p_\tau + p_{xxx} - 6p^2p_x = 0$.

It is simple to show (see Section 7.3) that the compatibility of the two systems (1.10)–(1.11) yield

Corollary 1.3 (KP equation). *The second log derivative of the Fredholm determinants*

$$U_{\text{per}}(\tau, \gamma, x) = \partial_{xx} \log \det(\mathbb{I} - \mathbb{K}_z), \quad U_{\text{KPZ}}(\tau, \gamma, x) = \partial_{xx} \log \det(\mathbb{I} - \mathbb{K}_{\text{KPZ}})$$

are solutions to the second Kadomtsev-Petviashvili (KP-II) equation⁶

$$12u_{\gamma\gamma} + (12u_\tau + 12uu_x + u_{xxx})_x = 0. \quad (1.15)$$

⁴The scale $\tau \mapsto 3\tau$ changes the equations to more standard form $p_\tau + p_{xxx} + 6prp_x = 0$ and $r_\tau + r_{xxx} + 6prr_x = 0$.

⁵The scale $\tau \mapsto 3\tau$ transform the equation to the standard form $p_\tau + p_{xxx} - 6p^2p_x = 0$. If the sign of the nonlinear term changes, $p_\tau + p_{xxx} + 6p^2p_x = 0$, the equation becomes the focusing mKdV equation instead of the defocusing mKdV equation.

⁶The scaled function $v(\tau, \gamma, x) = 2u(12\tau, \pm 2\gamma, x)$ changes the equation to more standard form $3\lambda v_{\gamma\gamma} + (v_\tau + 6vv_x + v_{xxx})_x$ with $\lambda = 1$. The equation with $\lambda = -1$ is called the KP-I equation.

For $u = U_{\text{KPZ}}$, Corollary 1.3 was obtained recently by Quastel and Remenik [40]. The relation (1.1) tells us that U_{KPZ} is a self-similar solution to (1.15),

$$U_{\text{KPZ}}(\tau, \gamma, x) = \tau^{-3/2} \phi_0 \left(\frac{x}{\tau^{1/3}} + \frac{\gamma^2}{4\tau^{4/3}} \right),$$

for some function ϕ_0 . Equation (1.15), in turn, gives us that $\phi_0 = -\phi^2$, where ϕ solves the second Painlevé equation, from which one can recover the Painlevé formula of F_{GUE} [41].

The above result is new for $u = U_{\text{per}}$. In this case, the results should be interpreted as that the equations hold for (τ, γ, x) and z in a neighborhood of (τ_0, γ_0, x_0) and z_0 in which $\det(\mathbb{I} - \mathbb{K}_z) \neq 0$. The complement of the zero set of this Fredholm determinant is an open set of full measure since the Fredholm determinant is an analytic function of these four variables. Assuming that the solution exists for all x and decays to 0 sufficiently fast as $x \rightarrow \infty$, the function F can be written as

$$F(x; \tau, \gamma) = \oint e^{xA_1(z) + \tau A_2(z) + 2B(z)} E(x, \tau, \gamma; z) \frac{dz}{2\pi i z}, \quad E(\tau, \gamma, x; z) := \exp \left(\int_x^\infty (y - x) U_{\text{per}}(\tau, \gamma, y; z) dy \right)$$

where $U_{\text{per}}(\tau, \gamma, x; z)$ is a *complex* solution of the KP equation with the initial condition determined by z . This is a periodic analogue of the Painlevé formula of F_{GUE} .

The solutions U_{per} , P_{per} and R_{per} above are infinite dimensional solitons (with complex velocities) since the associated Riemann-Hilbert problem is discrete; see Section 7. This way, F is a superposition of (the tau function of the) solutions integrated over a parameter z which determines the initial/boundary condition of the solution. In contrast, the purely continuous nature of the associated Riemann-Hilbert problem for U_{KPZ} , P_{KPZ} , R_{KPZ} indicate that these solutions are not solitons.

The KP equation was first introduced by Kadomtsev and Petviashvili [29] in 1970 and it is an universal model for the study of two-dimensional shallow water waves that generalize the mKdV equation to two spatial dimensions. The connection between the KP equation and the KPZ universality class was first observed by Quastel and Remenik in [40]. They considered the one-time/multi-location marginals of the KPZ fixed point on the infinite line with general initial condition, and proved that a log derivative of the distribution can be expressed in terms of a matrix KP equation. This result was used to find large deviation results and also further extended in [30]. As mentioned before, if we consider the one-point function and step initial condition, Quastel-Remenik's result is Corollary 1.3 for $u = U_{\text{KPZ}}$.⁷ In the context of periodic TASEP, Prohac [39] noticed that $\partial_{xx} \det(\mathbb{I} - \mathbb{K}_z)$ is “a reminiscent of soliton solutions for the KP equation”, and that the analogue Fredholm determinant for the *flat* initial condition is connected to the KdV equation. Our Corollary 1.3 establishes a precise connection for $\partial_{xx} \det(\mathbb{I} - \mathbb{K}_z)$ with the KP equation, and in Corollary 8.5 we rediscover Prohac's observation for the flat initial condition.

Solutions of integrable systems consisting of infinitely many solitons have attracted a great deal of recent interest, see for instance [21, 23] and the references therein.

We used the connection to an IKS-integrable operator to derive integrable differential equations for the step initial condition. This connection extends to the flat initial condition as well. However, it is not clear if it extends to general initial conditions. Nonetheless, the authors in [40, 30] used differential identities of the kernel to derive the KP equation for general initial conditions. As pointed out in [40], this method had appeared in several papers in the past, among which are the papers [35, 34] that derive the KP equation for a general class of kernels. It is straightforward to check that the general result of [34] is applicable to the kernel $\mathbb{T}_{-\gamma} \mathbb{T}_\gamma$ for the periodic case and gives an alternative proof for Corollary 1.3. Indeed, it can be used to derive the KP equation for general initial conditions for the periodic case. To state the result briefly, we recall that in [10] an extension of (1.2) was obtained for periodic TASEP with general initial condition

⁷The paper [40] used the notation $\gamma \mapsto 2\gamma$ so that the KP equation takes the form $3u_{\gamma\gamma} + (12u_\tau + 12uu_x + u_{xxx})_x = 0$.

satisfying certain technical assumptions. The limiting distribution takes the form

$$F_{\text{ic}}(x; \tau, \gamma) = \oint E_{\text{ic}}(z) e^{xA_1(z) + \tau A_2(z) + 2B(z)} \det(\mathbb{I} - \mathbb{K}_z^{\text{ic}}) \frac{dz}{2\pi iz}, \quad (1.16)$$

where the operator \mathbb{K}_z^{ic} depends on z, x, γ, τ , and also on the initial condition. All these quantities will be discussed in Section 2.5 below.

Theorem 1.4. *The function*

$$u = U_{\text{ic}}(\tau, \gamma, x) := \partial_{xx} \det \log(\mathbb{I} - \mathbb{K}_z^{\text{ic}})$$

solves the KP equation (1.15).

The analysis just discussed in this subsection can be extended to multi-time, multi-location distributions, and the results will be announced elsewhere.

1.3 Asymptotic properties of F

We also study in detail the distribution (1.2) in various asymptotic regimes.

1.3.1 Large time limit

The function F depends non-trivially on τ . We consider the large τ limit first.

Theorem 1.5 (Large τ limit). *For each fixed $x \in \mathbb{R}$ and $\gamma \in \mathbb{R}$,*

$$\lim_{\tau \rightarrow \infty} F\left(-\tau + \frac{\pi^{1/4}}{\sqrt{2}} x \tau^{1/2}; \tau, \gamma\right) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^x e^{-\frac{y^2}{2}} dy.$$

This result was conjectured in [8, (4.14)] and the above theorem confirms it. This is a natural result to expect since heuristically the model degenerates to a one dimensional random growth model along the time direction when $t \gg L^{3/2}$ in the periodic TASEP. However, the proof using the formula of F turns out to be technical. The leading non-trivial contribution to the Fredholm determinant comes from the trace of \mathbb{K}_z . We then still need to analyze the integral over z . To evaluate this integral asymptotically using the method of steepest-descent, it turned out that we need to consider an analytic continuation of polylog functions on a Riemann surface and the main contribution comes from a boundary point on a new sheet of the Riemann surface. Recently motivated by the same function $F(x; \tau, \gamma)$, Prolhac [39] studied Riemann surfaces associated to general polylog functions. In this paper, we carry out the analytic continuation directly for polylog functions of positive half integer index.

1.3.2 Small time limit

Next result is the small τ limit.

Theorem 1.6 (Small τ limit for $\gamma = 0$). *For every $x_0 \in \mathbb{R}$, there exist constants $C, c, \epsilon > 0$ and $\tau_0 > 0$ such that*

$$\left| F(\tau^{1/3} x; \tau, 0) - F_{\text{GUE}}(x) \right| \leq C e^{-\epsilon \tau^{-2/3}} e^{-c(x-x_0)}, \quad 0 < \tau < \tau_0, \quad x \geq x_0.$$

In particular,

$$\lim_{\tau \rightarrow 0} F(\tau^{1/3} x; \tau, 0) = F_{\text{GUE}}(x)$$

uniformly for $x \geq x_0$.

When τ is small, the periodicity effect becomes small, and hence in the limit $\tau \rightarrow 0$ we expect that the periodic model reduces to the non-periodic model on the line. Recall that the initial condition is given by *periodic* step initial condition. Hence, if the model were the TASEP on the infinite line, the locations at which the initial density profile changes from 0 to 1 generate shocks. At a shock location, the large time limit of the one-point distribution is not given by F_{GUE} but F_{GUE}^2 (see, for example, [22]). Based on this observation, it was conjectured in [8, (4.13)] that

$$\lim_{\tau \rightarrow 0} F\left(\tau^{1/3}x - \frac{\gamma^2}{4\tau}; \tau, \gamma\right) = \begin{cases} F_{\text{GUE}}(x), & -\frac{1}{2} < \gamma < \frac{1}{2}, \\ (F_{\text{GUE}}(x))^2, & \gamma = \frac{1}{2}. \end{cases} \quad (1.17)$$

The above result confirms this conjecture when $\gamma = 0$. The proof consists of showing that a conjugated version of the operator \mathbb{K}_z converges to the Airy operator, and that $e^{xA_1(z) + \tau A_2(z) + 2B(z)}$ converges to 1 when z is scaled appropriately. The convergence to the Airy kernel becomes substantially complicated when $\gamma \neq 0$. Although we believe that our arguments could be improved to analyze the case when γ is sufficiently small, it is not yet clear how to extend the analysis to the case when $|\gamma|$ is close to $1/2$.

1.3.3 Right tail estimate

We also study the right tail of the distribution function F . Recall that it is periodic in γ with period 1, so it is enough to consider $\gamma \in (-1/2, 1/2]$.

Theorem 1.7 (Right tail estimate). *For every fixed $\tau > 0$ and γ , there is a constant $c > 0$ such that*

$$1 - F(x; \tau, \gamma) = \left(1 - F_{\text{GUE}}\left(\frac{x}{\tau^{1/3}} + \frac{\gamma^2}{4\tau^{4/3}}\right)\right) \left(1 + \mathcal{O}(e^{-cx^{1/2}})\right) \quad \text{for } -\frac{1}{2} < \gamma < \frac{1}{2}$$

and

$$1 - F(x; \tau, \gamma) = 2 \left(1 - F_{\text{GUE}}\left(\frac{x}{\tau^{1/3}} + \frac{\gamma^2}{4\tau^{4/3}}\right)\right) \left(1 + \mathcal{O}(e^{-cx^{1/2}})\right) \quad \text{for } \gamma = \frac{1}{2}$$

as $x \rightarrow \infty$.

The above result implies that

$$1 - F\left(\tau^{1/3}x - \frac{\gamma^2}{4\tau}; \tau, \gamma\right) = \begin{cases} (1 - F_{\text{GUE}}(x)) \left(1 + \mathcal{O}(e^{-cx^{1/2}})\right), & -\frac{1}{2} < \gamma < \frac{1}{2}, \\ (1 - F_{\text{GUE}}(x))^2 \left(1 + \mathcal{O}(e^{-cx^{1/2}})\right), & \gamma = \frac{1}{2}, \end{cases}$$

as $x \rightarrow \infty$. This result is consistent with the conjectured small τ limit (1.17).

At this stage we cannot compare the above result with the large τ limit in Theorem 1.5, as in order to make the parameters in the same form we would need to consider the left tail as $x \rightarrow -\infty$, which we do not pursue in this paper.

1.4 Flat initial condition

If the periodic TASEP starts with the flat initial condition, the limit of the one point distribution takes a slightly different form. All of the above results have an analogue for the flat initial condition which we discuss in Section 8.

1.5 Organization of the paper

In Section 2 we state the definition of the function $F(x; \tau, \gamma)$ and obtain alternative representations for it. Lemma 1.1 and Theorem 1.4 are also proven in Section 2. Section 3 discusses several analytic continuation properties of the polylog function, which we use in Section 4 to evaluate the large τ limit. These two sections are the most technical part of this paper. We obtain the small τ limit in Section 5 and the right tail estimate in Section 6. The connection to integrable differential equations is discussed in Section 7. The flat initial condition is discussed in Section 8. Some proofs for auxiliary results used in Section 7 are given in Appendix A and B.

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2 One point distribution

2.1 Periodic TASEP with step initial condition

We first review the limit theorem of the one point distribution of the periodic TASEP. Let N and L be the number of particles and fundamental period, respectively, where $0 < N < L$. Consider the situation when $L, N \rightarrow \infty$ with density of particles $N/L \rightarrow \rho \in (0, 1)$. We take the periodic step initial condition; at time zero, each of the sites $-N+1, \dots, -1, 0$ is occupied by a particle and the sites $1, \dots, L-N$ are empty, and this pattern is extended periodically with period L . We denote by $\mathcal{H}(j, t)$ the height function at site j at time t . At $j = 0$, it is defined to be 2 times the number of particles that have moved from the site 0 to 1 up to time t . For $j \geq 1$, it is defined to be $\mathcal{H}(j, t) = \mathcal{H}(0, t) + \sum_{k=1}^j (1 - 2\eta_k(t))$ where $\eta_k(t)$ is the occupation variable that takes value 1 if the site j is occupied and value 0 if it is empty at time t . For $j \leq -1$, it is defined to be $\mathcal{H}(j, t) = \mathcal{H}(0, t) - \sum_{k=j+1}^0 (1 - 2\eta_k(t))$.

It was shown⁸ in [8, Theorem 3.4]⁹ that with the scale of the position and time given by

$$s = \gamma L, \quad t = \tau \frac{L^{3/2}}{\sqrt{\rho(1-\rho)}}$$

for parameters $\gamma \in (-\frac{1}{2}, \frac{1}{2}]$ and $\tau > 0$, we have the limit theorem

$$\lim_{L \rightarrow \infty} \mathbb{P} \left(\frac{\mathcal{H}(t(1-2\rho) + s, t) - (1-2\rho)s - (1-2\rho+2\rho^2)t}{-2\rho^{1/2}(1-\rho)^{1/2}L^{1/2}} \leq x \right) = F(x; \tau, \gamma) \quad (2.1)$$

for any fixed $x \in \mathbb{R}$. The function $F(x; \tau, \gamma)$ is the one in (1.2) and we describe it explicitly in the next subsection. Note that the height at time t is evaluated at the location $j = t(1-2\rho) + s$, where s measures the

⁸It was also shown in a non-rigorous paper [38].

⁹Theorem 3.4 of [8] states the result in terms of the current, but it is easy to translate the results in terms of the height function. Furthermore, the limit in Theorem 3.4 of [8] is given as $F(\tau^{1/3}x; \tau, \gamma)$, but in this paper, we use a slightly different scaling, which has the effect of changing $\tau^{1/3}x$ to x . See Theorem 2.1 of [9] for the explicit statement in terms of the height function.

relative distance from the location $t(1-2\rho)$. The reason for this shift is that the periodic step initial condition generate shocks that travel at speed $1-2\rho$, and we consider the moving frame along the shock direction. Also note that the time, relative position, and average-adjusted height have orders $\mathcal{O}(L^{3/2})$, $\mathcal{O}(L)$, and $\mathcal{O}(L^{1/2})$, which are consistent with the 3 : 2 : 1 KPZ scale, and the time and period are related as $t = \mathcal{O}(L^{3/2})$ which is the relaxation time scale.

2.2 Definition of the one point distribution function

We define the function $F(x; \tau, \gamma)$ in (1.2) explicitly. Let Li_s be the polylog function; see Section 3 for their properties. Set

$$A_1(z) := -\frac{1}{\sqrt{2\pi}} \text{Li}_{3/2}(z), \quad A_2(z) := -\frac{1}{\sqrt{2\pi}} \text{Li}_{5/2}(z), \quad B(z) := \frac{1}{4\pi} \int_0^z \frac{(\text{Li}_{1/2}(y))^2}{y} dy. \quad (2.2)$$

To introduce the operator \mathbb{K}_z , first define the function

$$Q(\xi) := \sqrt{\frac{2}{\pi}} \int_{-\infty}^{\xi} \text{Li}_{1/2}(e^{-s^2/2}) ds \quad \text{for} \quad \frac{3\pi}{4} < \arg \xi < \frac{5\pi}{4}, \quad (2.3)$$

where the path of integration is contained in the sector $\arg(s) \in (3\pi/4, 5\pi/4)$ so that $e^{-s^2/2} \in \mathbb{C} \setminus [1, \infty)$, and as such the polylog is well defined. Alternatively, the representation

$$Q(\xi) = - \int_{-i\infty}^{i\infty} \frac{\log(1 - e^{-\xi^2/2} e^{u^2/2})}{u - \xi} \frac{du}{\pi i}, \quad \frac{3\pi}{4} < \arg \xi < \frac{5\pi}{4}, \quad (2.4)$$

also holds (see [8, (4.8)]). The function Q is analytic in the sector.

We set, for $3\pi/4 < \arg \xi < 5\pi/4$,

$$\Phi(\xi) = \Phi(\xi; \tau, x) = -\frac{1}{3} \tau \xi^3 + x\xi - Q(\xi) \quad (2.5)$$

and define the integral operator \mathbb{K}_z acting on functions over \mathcal{S}_- via the kernel

$$\mathbf{K}_z(\xi_1, \xi_2) = \mathbf{K}_z(\xi_1, \xi_2; \tau, \gamma, x) = \sum_{\eta \in \mathcal{S}_-} \frac{e^{\Phi(\xi_1) + \Phi(\eta) + \frac{\gamma}{2}(\xi_1^2 - \eta^2)}}{\xi_1 \eta (\xi_1 + \eta) (\eta + \xi_2)}, \quad \xi_1, \xi_2 \in \mathcal{S}_-, \quad (2.6)$$

where \mathcal{S}_- is the discrete set defined in (1.5). Note that the kernel depends on z since the set \mathcal{S}_- depends on z . Due to the growth properties of Φ , it is direct to check that the series definition of the Fredholm determinant $\det(\mathbb{I} - \mathbb{K}_z)$ is well-defined even though the kernel does not decay fast enough as $\xi_2 \rightarrow \infty$ on \mathcal{S}_- . It is also direct to check that $\det(\mathbb{I} - \mathbb{K}_z)$ is analytic in $0 < |z| < 1$.

Definition 2.1. The function in (1.2) is defined by

$$F(x; \tau, \gamma) = \oint e^{xA_1(z) + \tau A_2(z) + 2B(z)} \det(\mathbb{I} - \mathbb{K}_z) \frac{dz}{2\pi i z} \quad (2.7)$$

where the contour is a circle $|z| = R$ with $0 < R < 1$, oriented counterclockwise.

It was shown in [8] that $F(x; \tau, \gamma)$ is a distribution function, and it satisfies the spatial periodicity $F(x; \tau, \gamma + 1) = F(x; \tau, \gamma)$.

The above kernel can be conjugated to a symmetric kernel (using the same notation)

$$\mathbb{K}_z(\xi_1, \xi_2) = \sum_{\eta \in \mathcal{S}_-} \frac{e^{\frac{1}{2}\Phi(\xi_1) + \Phi(\eta) + \frac{1}{2}\Phi(\xi_2) + \frac{\gamma}{4}(\xi_1^2 - 2\eta^2 + \xi_2^2)}}{\sqrt{-\xi_1}\sqrt{-\eta}(\xi_1 + \eta)(\eta + \xi_2)\sqrt{-\eta}\sqrt{-\xi_2}}, \quad \xi_1, \xi_2 \in \mathcal{S}_-, \quad (2.8)$$

without changing the Fredholm determinant, and this kernel properly defines a trace class operator $\mathbb{K}_z : \ell^2(\mathcal{S}_-) \rightarrow \ell^2(\mathcal{S}_-)$ (see Subsection 2.3). This kernel is symmetric but not self-adjoint since it is complex-valued.

2.3 Proof of Lemma 1.1

Lemma 1.1 claims that $\det(\mathbb{I} - \mathbb{K}_z)_{\ell^2(\mathcal{S}_-)} = \det(\mathbb{I} - \mathbb{T}_{-\gamma}\mathbb{T}_\gamma)_{L^2(0, \infty)}$ with \mathbb{T}_γ being the operator on $L^2(0, \infty)$ defined by the kernel (1.6). The rest of this subsection proves this claim.

From the formula (2.8), \mathbb{K}_z is the product of two operators

$$\mathbb{K}_z = \mathbb{J}\mathbb{J}^T \quad (2.9)$$

where $\mathbb{J} : \ell^2(\mathcal{S}_-) \rightarrow \ell^2(\mathcal{S}_-)$ has the kernel

$$\mathbf{J}(\xi, \eta) = \frac{e^{\frac{1}{2}(\Phi(\xi) + \Phi(\eta)) + \frac{\gamma}{4}(\xi^2 - \eta^2)}}{\sqrt{-\xi}(\xi + \eta)\sqrt{-\eta}}, \quad \xi, \eta \in \mathcal{S}_-. \quad (2.10)$$

The operator $\mathbb{J}^T : \ell^2(\mathcal{S}_-) \rightarrow \ell^2(\mathcal{S}_-)$ is obtained from \mathbb{J} from the kernel

$$\mathbf{J}^T(\eta, \xi; \gamma) = \mathbf{J}(\xi, \eta; \gamma) = \mathbf{J}(\eta, \xi; -\gamma). \quad (2.11)$$

Using the identity $\frac{1}{\eta + \xi} = -\int_0^\infty e^{s(\eta + \xi)} ds$ that holds for $\eta, \xi \in \mathcal{S}_-$, we can write

$$\mathbb{J} = -\mathbb{G}_{-\gamma}\mathbb{G}_\gamma^T, \quad (2.12)$$

where $\mathbb{G}_\gamma : L^2(0, \infty) \rightarrow \ell^2(\mathcal{S}_-)$ is the operator defined by the kernel

$$\mathbf{G}_\gamma(\xi, s) = \frac{e^{\frac{1}{2}\Phi(\xi) - \frac{\gamma}{4}\xi^2 + s\xi}}{\sqrt{-\xi}} \quad \text{for } \xi \in \mathcal{S}_- \text{ and } s \in (0, \infty).$$

It is immediate that \mathbb{G}_γ is Hilbert-Schmidt. Consequently, \mathbb{J}, \mathbb{J}^T and \mathbb{K}_z are all trace class operators. From the decompositions above,

$$\det(\mathbb{I} - \mathbb{K}_z) = \det(\mathbb{I} - \mathbb{J}\mathbb{J}^T) = \det(\mathbb{I} - \mathbb{G}_{-\gamma}\mathbb{G}_\gamma^T\mathbb{G}_\gamma\mathbb{G}_{-\gamma}^T) = \det(\mathbb{I} - \mathbb{G}_\gamma^T\mathbb{G}_\gamma\mathbb{G}_{-\gamma}^T\mathbb{G}_{-\gamma}).$$

Setting $\mathbb{T}_\gamma = \mathbb{G}_{-\gamma}^T\mathbb{G}_{-\gamma}$, we find that \mathbb{T}_γ is trace class and its kernel is (1.6). This proves Lemma 1.1.

2.4 Integrable operator formula

There is another representation for $\det(\mathbb{I} - \mathbb{K}_{\text{KPZ}})$ as well as $\det(\mathbb{I} - \mathbb{K}_z)$. These representations will be used in Section 7 when we derive integrable differential equations.

For $|z| < 1$, recall the set \mathcal{S}_- in (1.5), and also let Λ_- be an unbounded oriented contour from $e^{-i\theta_1}\infty$

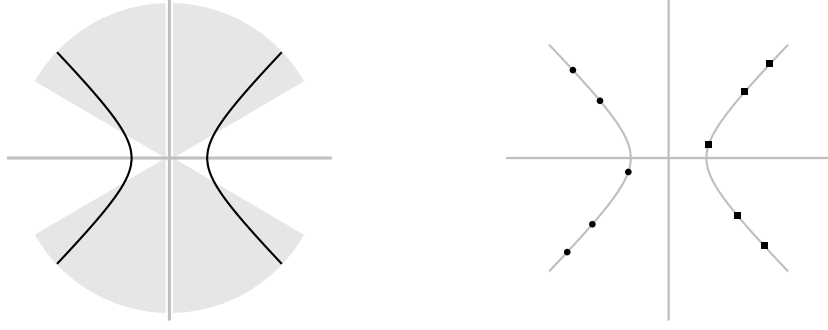


Figure 3: The left picture is the set $\Lambda = \Lambda_+ \cup \Lambda_-$. In the right picture, the sets \mathcal{S}_+ and \mathcal{S}_- are represented by the squares and the dots, respectively. The dashed curves are the hyperbolas. Compare this figure with Figure 2.

to $e^{i\theta_2}\infty$ for some $\theta_1, \theta_2 \in (\pi/2, 5\pi/6)$. Define (see Figure 3)

$$\begin{aligned} \mathcal{S} = \mathcal{S}(z) &:= \mathcal{S}_+ \cup \mathcal{S}_- \quad \text{with } \mathcal{S}_+ := -\mathcal{S}_-, \text{ and} \\ \Lambda &:= \Lambda_+ \cup \Lambda_- \quad \text{with } \Lambda_+ := -\Lambda_-. \end{aligned} \quad (2.13)$$

In addition, set

$$V(u) = V(u; \tau, \gamma, x) := -\frac{\tau}{3}u^3 + \frac{\gamma}{2}u^2 + xu, \quad u \in \mathbb{C}, \quad (2.14)$$

and denote by σ_3 the third Pauli matrix,

$$\sigma_3 := \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad \text{so in particular,} \quad e^{\pm \frac{1}{2}V(u)\sigma_3} = \begin{pmatrix} e^{\pm \frac{1}{2}V(u)} & 0 \\ 0 & e^{\mp \frac{1}{2}V(u)} \end{pmatrix}.$$

Lemma 2.2. *Let χ_+ and χ_- be the indicator functions of \mathcal{S}_+ and \mathcal{S}_- , respectively, and define vector functions*

$$\vec{f}(u) = e^{-\frac{1}{2}V(u)\sigma_3} \vec{f}_0(u) \quad \text{and} \quad \vec{g}(u) = e^{\frac{1}{2}V(u)\sigma_3} \vec{g}_0(u),$$

with

$$\vec{f}_0(u) = \begin{pmatrix} \frac{e^{\frac{1}{2}Q(u)}}{\sqrt{u}} \chi_+(u) \\ e^{-\frac{1}{2}Q(u)} \chi_-(u) \end{pmatrix} \quad \text{and} \quad \vec{g}_0(u) = \begin{pmatrix} -\frac{e^{-\frac{1}{2}Q(u)}}{\sqrt{-u}} \chi_-(u) \\ \frac{e^{\frac{1}{2}Q(u)}}{\sqrt{u}} \chi_+(u) \end{pmatrix}.$$

Then

$$\det(\mathbb{I} - \mathbb{K}_z)_{\ell^2(\mathcal{S}_-)} = \det(\mathbb{I} - \mathbb{H})_{\ell^2(\mathcal{S})}$$

where \mathbb{H} is the trace class operator acting on $\ell^2(\mathcal{S})$ with kernel

$$\mathbf{H}(u, v) = \frac{\vec{f}(u)^T \vec{g}(v)}{u - v}, \quad u \neq v, \quad \text{and} \quad \mathbf{H}(u, u) = 0. \quad (2.15)$$

Proof. Recall that $\mathbb{K}_z = \mathbb{J}\mathbb{J}^T$ in (2.9) where $\mathbb{J} : \ell^2(\mathcal{S}_-) \rightarrow \ell^2(\mathcal{S}_-)$ has the kernel \mathbf{J} given by (2.10). Noting that $\mathcal{S}_+ = -\mathcal{S}_-$, we set $\mathbb{W} : \ell^2(\mathcal{S}_+) \rightarrow \ell^2(\mathcal{S}_-)$ to be the reflection operator defined by $(\mathbb{W}h)(u) = h(-u)$ and write $\mathbb{K}_z = \mathbb{J}_1\mathbb{J}_2$, where $\mathbb{J}_1 = \mathbb{J}\mathbb{W} : \ell^2(\mathcal{S}_+) \rightarrow \ell^2(\mathcal{S}_-)$ and $\mathbb{J}_2 = \mathbb{W}^T\mathbb{J}^T : \ell^2(\mathcal{S}_-) \rightarrow \ell^2(\mathcal{S}_+)$. Since \mathcal{S}_- and \mathcal{S}_+

are disjoint, we have $\ell^2(\mathcal{S}_-) \oplus \ell^2(\mathcal{S}_+) = \ell^2(\mathcal{S}_- \cup \mathcal{S}_+)$, and

$$\det(\mathbb{I} - \mathbb{K}_z)_{\ell^2(\mathcal{S}_-)} = \det \left(\mathbb{I} - \begin{pmatrix} 0 & \mathbb{J}_1 \\ \mathbb{J}_2 & 0 \end{pmatrix} \right)_{\ell^2(\mathcal{S}_-) \oplus \ell^2(\mathcal{S}_+)} = \det(\mathbb{I} - \mathbb{H})_{\ell^2(\mathcal{S}_- \cup \mathcal{S}_+)}$$

where \mathbb{H} is the operator on $\ell^2(\mathcal{S}_- \cup \mathcal{S}_+)$ with the kernel

$$\begin{aligned} \mathbf{H}(u, v) &= \chi_+(u) \mathbf{J}_2(u, v) \chi_-(v) + \chi_-(u) \mathbf{J}_1(u, v) \chi_+(v) \\ &= \chi_+(u) \frac{e^{\frac{1}{2}\Phi(v) - \frac{1}{2}\Phi(u) + \frac{\gamma}{4}(v^2 - u^2)}}{\sqrt{u}\sqrt{-v}(v - u)} \chi_-(v) + \chi_-(u) \frac{e^{\frac{1}{2}\Phi(u) - \frac{1}{2}\Phi(v) + \frac{\gamma}{4}(u^2 - v^2)}}{\sqrt{-u}\sqrt{v}(u - v)} \chi_+(v) \end{aligned}$$

for $u, v \in \mathcal{S}_+ \cup \mathcal{S}_-$. Because \mathbb{J} is trace class and \mathbb{W} is bounded, the operator \mathbb{H} is trace class. The result now follows by inserting the formula $\Phi(\xi) = -\frac{1}{3}\tau\xi^3 + x\xi - Q(\xi)$ (see 2.5). \square

There is an analogue to the previous result for $\det(\mathbb{I} - \mathbb{K}_{\text{KPZ}})$. For the case when $\tau = 1$ and $\gamma = 0$, the next result is a particular instance of a known representation for the Airy₂ process [11, 12].

Lemma 2.3. *Let χ_{Λ_+} and χ_{Λ_-} be the characteristic functions of the contours Λ_+ and Λ_- in (2.13). Define the vector functions*

$$\vec{a}(u) = e^{-\frac{1}{2}V(u)\sigma_3} \vec{a}_0(u), \quad \vec{b}(u) = e^{\frac{1}{2}V(u)\sigma_3} \vec{b}_0(u), \quad \text{with} \quad a_0(u) = \begin{pmatrix} \chi_{\Lambda_+}(u) \\ -\chi_{\Lambda_-}(u) \end{pmatrix}, \quad b_0(u) = \begin{pmatrix} \chi_{\Lambda_-}(u) \\ \chi_{\Lambda_+}(u) \end{pmatrix}.$$

Then,

$$\det(\mathbb{I} - \mathbb{K}_{\text{KPZ}})_{L^2(0, \infty)} = \det(\mathbb{I} - \mathbb{F})_{L^2(\Lambda)}$$

where $\mathbb{F} : L^2(\Lambda) \rightarrow L^2(\Lambda)$ acts with kernel

$$\mathbf{F}(u, v) = \frac{1}{2\pi i} \frac{\vec{a}(u)^T \vec{b}(v)}{u - v}, \quad u \neq v \quad \text{and} \quad \mathbf{F}(u, u) = 0. \quad (2.16)$$

Proof. The definition of the kernel \mathbf{A}_γ in (1.4) gives the decomposition $\mathbb{A}_\gamma = \mathbb{B}_\gamma^T \mathbb{B}_\gamma$, where $\mathbb{B}_\gamma : L^2(0, \infty) \rightarrow L^2(\Lambda_-)$ acts with kernel

$$\mathbf{B}_\gamma(\eta, v) = \frac{1}{\sqrt{2\pi i}} e^{\frac{1}{2}V(\eta) + \eta v}, \quad \eta \in \Lambda_-, v > 0,$$

where V is given in (2.14). Manipulating the Fredholm determinants,

$$\det(\mathbb{I} - \mathbb{K}_{\text{KPZ}})_{L^2(0, \infty)} = \det(\mathbb{I} - \mathbb{A}_{-\gamma} \mathbb{A}_\gamma)_{L^2(0, \infty)} = \det(\mathbb{I} - \mathbb{B}_\gamma \mathbb{B}_{-\gamma}^T \mathbb{B}_{-\gamma} \mathbb{B}_\gamma^T)_{L^2(\Lambda)} = \det(\mathbb{I} - \mathbb{B} \mathbb{B}^T)_{L^2(\Lambda)},$$

where $\mathbb{B} = \mathbb{B}_\gamma \mathbb{B}_{-\gamma}^T$. The rest of the proof follows exactly as in the proof of Lemma 2.2: the role of \mathbb{K}_z is played by $\mathbb{B} \mathbb{B}^T$ and the operator \mathbb{J} is now \mathbb{B} . \square

The form (2.15) or (2.16) of the kernels is saying that the operators \mathbb{F} and \mathbb{H} are IKS-integrable, which is a class of operators that was first singled out by Its, Izergin, Korepin and Slavnov [27]. In Section 7 we discuss and explore this structure in detail.

2.5 The periodic TASEP with general initial condition: proof of Theorem 1.4

The distribution function (1.16) was obtained in [10] in the context of periodic TASEP, and extends (2.1) to a large class of initial conditions. The prefactor $E_{\text{ic}}(z)$ in (1.16) depends on the initial condition and also

on the variable z but is independent of the parameters x, τ and γ . The operator $\mathbb{K}_z^{\text{ic}} : \ell^2(\mathcal{S}_-) \rightarrow \ell^2(\mathcal{S}_-)$ is a generalization of \mathbb{K}_z and acts with kernel¹⁰

$$\mathbb{K}_z^{\text{ic}}(\xi_1, \xi_2) = \sum_{\eta \in \mathcal{S}_-} \chi_{\text{ic}}(-\eta, \xi_2) \frac{e^{\frac{1}{2}\Phi(\xi_1) + \Phi(\eta) + \frac{1}{2}\Phi(\xi_2) + \frac{\gamma}{4}(\xi_1^2 - 2\eta^2 + \xi_2^2)}}{\sqrt{-\xi_1}\sqrt{-\eta}(\xi_1 + \eta)(\eta + \xi_2)\sqrt{-\eta}\sqrt{-\xi_2}}, \quad \xi_1, \xi_2 \in \mathcal{S}_-, \quad (2.17)$$

where $\chi_{\text{ic}}(-\eta, \xi_2) = \chi_{\text{ic}}(-\eta, \xi_2; z)$ depends on the initial condition and on the parameter z but not on x, γ, τ .

The class of initial conditions for which this formula is valid is stated in rather technical terms, and verifying that a given initial condition falls into this class may be involved, even if the initial condition is simple. The formulation of \mathbb{K}_z^{ic} as above is enough for our purposes, so we refer the reader to [10] for more details on these conditions. It is worth mentioning that this setting just introduced is valid for the step, flat and step-flat initial conditions.

Similarly as in (2.9), we write

$$\mathbb{K}_z^{\text{ic}} = \mathbb{J}\mathbb{J}^{\text{ic}},$$

where $\mathbb{J} : \ell^2(\mathcal{S}_-) \rightarrow \ell^2(\mathcal{S}_-)$ is as in (2.9) and $\mathbb{J}^{\text{ic}} : \ell^2(\mathcal{S}_-) \rightarrow \ell^2(\mathcal{S}_-)$ is defined by the kernel

$$\mathbf{J}^{\text{ic}}(\xi, \eta) = \chi_{\text{ic}}(-\xi, \eta) \mathbf{J}^T(\xi, \eta) = \chi_{\text{ic}}(-\xi, \eta) \mathbf{J}(\eta, \xi), \quad \xi, \eta \in \mathcal{S}_-.$$

We take advantage of the same decomposition (2.12) and manipulate

$$\det(\mathbb{I} - \mathbb{K}_z^{\text{ic}}) = \det(\mathbb{I} + \mathbb{G}_{-\gamma} \mathbb{G}_{\gamma}^T \mathbb{J}^{\text{ic}}) = \det(\mathbb{I} - \mathbb{T}^{\text{ic}}),$$

where $\mathbb{T}^{\text{ic}} : L^2(0, \infty) \rightarrow L^2(0, \infty)$ is the product $\mathbb{T}^{\text{ic}} = -\mathbb{G}_{\gamma}^T \mathbb{J}^{\text{ic}} \mathbb{G}_{-\gamma}$ and has kernel

$$\mathbf{T}^{\text{ic}}(u, v) = - \sum_{\xi, \eta \in \mathcal{S}_-} \frac{\chi_{\text{ic}}(-\eta, \xi)}{\xi(\xi + \eta)\eta} e^{\Phi(\xi) + \Phi(\eta) + \frac{\gamma}{2}(\xi^2 - \eta^2) + u\eta + v\xi}, \quad u, v > 0.$$

It is convenient to rescale the kernel and consider the auxiliary operator

$$\widehat{\mathbb{T}}^{\text{ic}} = \widehat{\mathbf{T}}^{\text{ic}}(\tau, \gamma, x) = -\mathbf{T}^{\text{ic}}(-3\tau, 2\gamma, x) \quad (2.18)$$

which has explicit kernel

$$\widehat{\mathbf{T}}^{\text{ic}}(u, v) = \widehat{\mathbf{T}}^{\text{ic}}(u, v; \tau, \gamma, x) = \sum_{\eta, \xi \in \mathcal{S}_-} \frac{\chi_{\text{ic}}(-\xi, \eta) e^{Q(\xi) + Q(\eta)}}{\xi(\xi + \eta)\eta} e^{\tau(\xi^3 + \eta^3) + \gamma(\xi^2 - \eta^2) + (u+x)\xi + (v+x)\eta}, \quad u, v > 0.$$

In particular, the differential identities

$$\partial_x \widehat{\mathbf{T}}^{\text{ic}} = \partial_u \widehat{\mathbf{T}}^{\text{ic}} + \partial_v \widehat{\mathbf{T}}^{\text{ic}}, \quad \partial_{\gamma} \widehat{\mathbf{T}}^{\text{ic}} = \partial_{uu} \widehat{\mathbf{T}}^{\text{ic}} - \partial_{vv} \widehat{\mathbf{T}}^{\text{ic}}, \quad \partial_{\tau} \widehat{\mathbf{T}}^{\text{ic}} = \partial_{uuu} \widehat{\mathbf{T}}^{\text{ic}} + \partial_{vvv} \widehat{\mathbf{T}}^{\text{ic}}.$$

are of straightforward verification. By [34, Theorem 3.1], these identities imply that $\widehat{u} = \partial_{xx} \log \det(\mathbb{I} + \widehat{\mathbb{T}}^{\text{ic}})$ satisfies the KP equation in the form

$$3\widehat{u}_{\gamma\gamma} + (\widehat{u}_{xxx} + 12\widehat{u}\widehat{u}_x - 4\widehat{u}_{\tau})_x = 0. \quad (2.19)$$

In the definition of $\widehat{\mathbf{T}}^{\text{ic}}(u, v; \tau, \gamma, x)$ we should only consider $\tau < 0$ to ensure the series is convergent. On the other hand, the KP equation is an evolution equation in the time variable τ , so naturally with $\tau > 0$.

¹⁰The original formulation in [10] is a modified version of (2.6), which can then be conjugated to (2.17).

Nevertheless, we are safe to apply [34, Theorem 3.1] here also for $\tau < 0$, as the arguments therein are of algebraic nature, relying on τ solely as a variable without physical meaning and no restriction on its sign. Having in mind (2.18), Theorem 1.4 now follows from (2.19).

3 Analytic continuation of polylog functions

The formula (2.7) of $F(x; \tau, \gamma)$ involves polylog functions $\text{Li}_{1/2}(z)$, $\text{Li}_{3/2}(z)$ and $\text{Li}_{5/2}(z)$. In the first subsection, we summarize some basic properties of polylog functions used in this paper. In the remaining subsections, we establish some analytic continuation properties of polylog functions and their combinations. The results of this section will be used only in Subsection 4.3 for the large τ limit of $F(x; \tau, \gamma)$.

Throughout this paper, $\log z$ denotes the principal branch of the logarithmic function with branch cut along $(-\infty, 0]$, and z^α denotes $z^\alpha = e^{\alpha \log z}$.

3.1 Polylog functions

For $\text{Re } s > 0$, the polylog function is defined by the series

$$\text{Li}_s(z) := \sum_{k=1}^{\infty} \frac{z^k}{k^s}, \quad |z| < 1, \quad (3.1)$$

and it extends analytically using the integral representation

$$\text{Li}_s(z) = \frac{z}{\Gamma(s)} \int_0^\infty \frac{t^{s-1}}{e^t - z} dt, \quad z \in \mathbb{C} \setminus [1, \infty). \quad (3.2)$$

From this representation, Paulsen [33, Proposition 3] showed that if s is not an integer, then

$$\text{Li}_s(z) = \Gamma(1-s)(-\log z)^{s-1} + \zeta(s) + \sum_{n=1}^{\infty} (z-1)^n \sum_{m=1}^n \frac{S_n^{(m)} \zeta(s-m)}{n!} \quad \text{as } z \rightarrow 1, \quad (3.3)$$

where ζ is the Riemann zeta function and $S_n^{(m)}$ are the Stirling numbers of the first kind.

Observe that the function $f(t) = (-t)^{s-1}$ has branch cut along $(0, +\infty)$ and it satisfies the identity

$$(-t)_+^{s-1} - (-t)_-^{s-1} = 2i|t|^{s-1} \sin(\pi s), \quad t > 0,$$

where $f_\pm(t)$ denotes the limit of $f(t \pm i\epsilon)$ as $\epsilon \searrow 0$. Thus, for $s \in \mathbb{C}$ satisfying $s \notin \mathbb{Z}$ and $\text{Re}(s) > 0$, we can rewrite the integral representation (3.2) as a complex contour integral given by

$$\text{Li}_s(z) = -\frac{\Gamma(1-s)z}{2\pi i} \int_\Lambda \frac{(-t)^{s-1}}{e^t - z} dt, \quad z \in \mathbb{C} \setminus [1, \infty), \quad (3.4)$$

where we used the reflection formula $\Gamma(s) \sin(\pi s) = \frac{\pi}{\Gamma(1-s)}$. Here, Λ is an unbounded contour that starts and ends at $+\infty$, lies in the strip $\{t \in \mathbb{C} : |\text{Im } t| < \pi\}$, encircles the positive axis with counterclockwise orientation, and separates the point $\log z$ from the interval $[0, \infty)$, see Figure 4.

3.2 Analytic continuation

Define the set

$$\mathcal{R}_1 = \mathbb{C} \setminus ((-\infty, 0] \cup [1, \infty)).$$

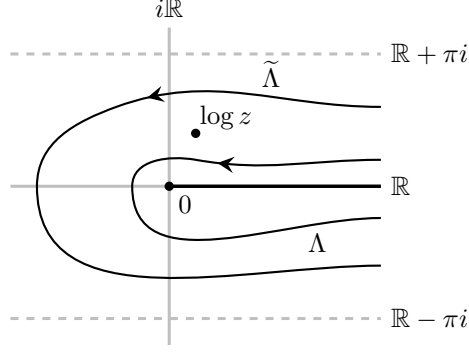


Figure 4: The contours Λ and $\tilde{\Lambda}$ used in the integral representations of Li_s and F_s .

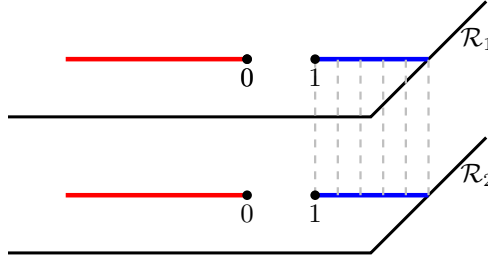


Figure 5: The two sheets \mathcal{R}_1 and \mathcal{R}_2 that constitute the Riemann surface \mathcal{R} . They are glued along the interval $[1, +\infty)$ but not along $(-\infty, 0]$.

Let \mathcal{R}_2 be another copy of \mathcal{R}_1 and define a (non-compact two sheeted) Riemann surface \mathcal{R} by gluing \mathcal{R}_1 and \mathcal{R}_2 along *only* $[1, \infty)$, see Figure 5. The only branch point¹¹ of the surface is $z = 1$ and the local parameter near $z = 1$ is given by $z - 1 = w^2$, $w \in \mathbb{C}$. For $j = 1, 2$, we occasionally use the notation $p^{(j)}$ to denote the point on the sheet \mathcal{R}_j that projects onto $p \in \mathbb{C}$. This notion is well defined as long as $p \notin (-\infty, 0) \cup (1, \infty)$. In particular, $1^{(1)} = 1^{(2)}$ so we simply write $1^{(j)} = 1 \in \mathcal{R}$ in this case.

Define the function

$$u_0(z) := -(-2 \log z)^{1/2}, \quad z \in \mathcal{R}_1. \quad (3.5)$$

From the choice of the branch of the logarithm and the square root, $u_0(z)$ is analytic in \mathcal{R}_1 . This function is one of the Bethe roots, see (1.5). This particular Bethe root will play an important role in the large τ limit. Note that $u_{0+}(x) = -u_{0-}(x)$ for $x > 1$.

Lemma 3.1. *The function*

$$U_0(z) := \begin{cases} u_0(z), & z \in \mathcal{R}_1, \\ -u_0(z), & z \in \mathcal{R}_2 \end{cases} \quad (3.6)$$

is analytic on \mathcal{R} . The only zero of U_0 is the branch point $z = 1$, which is a simple zero. As a consequence,

¹¹The Riemann surface \mathcal{R} here is bordered. We could extend \mathcal{R} to a non-compact Riemann surface without boundaries which is the fundamental covering surface for the polylog. In this extended surface $0^{(2)}$ would also be a branch point. Hence we sometimes refer to $0^{(2)}$ loosely as a branch point.

$\frac{1}{U_0(z)}$ is a meromorphic function on \mathcal{R} with a simple pole at $z = 1$ and no other poles.

Proof. The analytic properties of U_0 are straightforward to check. The fact that U_0 has a simple zero at $z = 1$ is easily verified using the local coordinates $z - 1 = w^2$. \square

Now consider the polylog Li_s . For the rest of this section, we assume that s is a positive half integer,

$$s \in \mathbb{Z} + \frac{1}{2}, \quad s > 0,$$

which is the case relevant to our purposes. We use the formula (3.4) to extend the polylog to the Riemann surface \mathcal{R} . To this end, we introduce an auxiliary function

$$P_s(z) = \int_{\tilde{\Lambda}} \frac{(-t)^{s-1}}{e^t - z} dt, \quad z \in \mathbb{C} \setminus (-\infty, 0],$$

where $\tilde{\Lambda}$ is a contour going from $+\infty + i0$ to $+\infty - i0$, encircling both the segment $[0, +\infty)$ and the point $\log z$, and being contained in the horizontal strip $|\text{Im } t| < \pi$; see Figure 4. The condition $z \notin (-\infty, 0]$ implies that $\log z$ is in the horizontal strip $|\text{Im } t| < \pi$, and hence we can indeed choose such a contour $\tilde{\Lambda}$ contained in the horizontal strip $|\text{Im } t| < \pi$. Note that unlike $\text{Li}_s(z)$, the function $P_s(z)$ is analytic across the segment $[1, \infty)$. Given a point $z \in \mathcal{R}_1$, deforming the contour Λ in (3.4) to $\tilde{\Lambda}$ we obtain the identity

$$\int_{\Lambda} \frac{(-t)^{s-1}}{e^t - z} dt = P_s(z) - 2\pi i \text{Res}_{t=\log z} \left(\frac{(-t)^{s-1}}{e^t - z} \right) = P_s(z) - 2\pi i \frac{(-\log z)^{s-1}}{z}.$$

Hence, writing $\log z$ in terms of $u_0(z)$ in (3.5), we get

$$\text{Li}_s(z) = -\frac{\Gamma(1-s)}{2\pi i} z P_s(z) + 2^{1-s} \Gamma(1-s) (-u_0(z))^{2s-2} \quad \text{for } z \in \mathcal{R}_1. \quad (3.7)$$

This formula implies the following extension result.

Lemma 3.2. *Assume that $2s$ is a positive odd integer. The function*

$$\mathbb{L}_s(z) := \begin{cases} \text{Li}_s(z) & \text{for } z \in \mathcal{R}_1, \\ \text{Li}_s(z) - 2^{2-s} \Gamma(1-s) (-u_0(z))^{2s-2} & \text{for } z \in \mathcal{R}_2, \end{cases} \quad (3.8)$$

is analytic on \mathcal{R} for $s \neq \frac{1}{2}$. For $s = \frac{1}{2}$, $\mathbb{L}_{1/2}$ is meromorphic with a simple pole at $z = 1$ and no other poles.

Proof. We set $\mathbb{L}_s(z) = -\frac{\Gamma(1-s)}{2\pi i} z P_s(z) + 2^{1-s} \Gamma(1-s) (-U_0(z))^{2s-2}$ where $U_0(z)$ given by (3.6). Using $(-1)^{2s-2} = -1$ and (3.7), we observe that this function is equal to (3.8) on each sheet. For $s = 1/2$, we note that $(-U_0(z))^{2s-2} = -\frac{1}{U_0(z)}$. \square

3.3 Extension of the functions f_1 and f_2

In the asymptotic analysis of $F(x; \tau, \gamma)$ as $\tau \rightarrow \infty$ in the next section, we need to extend several functions involving polylog to the Riemann surface \mathcal{R} . These functions are defined below as f_1 , f_2 , and E and appear later in (4.9). In this subsection we discuss the analytic extension and properties of f_1 and f_2 , and postpone the discussion of E to the next subsection.

The functions $f_1(z)$ and $f_2(z)$ are given by

$$f_1(z) := \frac{1}{\sqrt{2\pi}} \text{Li}_{3/2}(z) - \frac{1}{\sqrt{2\pi}} \text{Li}_{5/2}(z) - 2u_0(z) - \frac{2}{3} u_0(z)^3, \quad f_2(z) := 2u_0(z) - \frac{1}{\sqrt{2\pi}} \text{Li}_{3/2}(z).$$

Define

$$f_1(z) := \frac{1}{\sqrt{2\pi}} L_{3/2}(z) - \frac{1}{\sqrt{2\pi}} L_{5/2}(z) - 2U_0(z) - \frac{2}{3}U_0(z)^3$$

and

$$f_2(z) := 2U_0(z) - \frac{1}{\sqrt{2\pi}} L_{3/2}(z).$$

These functions are analytic on \mathcal{R} . They satisfy $f_1 = f_1$ and $f_2 = f_2$ on the first sheet \mathcal{R}_1 . For later use, we state the formula on the second sheet explicitly. Using (3.6) and (3.8), and $\Gamma(-1/2) = -2\sqrt{\pi}$ and $\Gamma(-3/2) = 4\sqrt{\pi}/3$, we find the following.

Lemma 3.3. *The functions f_1 and f_2 are analytic on \mathcal{R} and satisfy*

$$f_1(z) = \frac{1}{\sqrt{2\pi}} \text{Li}_{3/2}(z) - \frac{1}{\sqrt{2\pi}} \text{Li}_{5/2}(z) \quad \text{and} \quad f_2(z) = -\frac{1}{\sqrt{2\pi}} \text{Li}_{3/2}(z) \quad \text{for } z \in \mathcal{R}_2.$$

In addition, the functions f_1 and f_2 have continuous boundary values $f_1(z \pm i0)$ and $f_2(z \pm i0)$ for z on the interval $(-\infty, 0)$ in the boundary of \mathcal{R}_1 .

3.4 Extension of the function E

We now consider the function

$$E(z) := e^{2B(z) - 2Q(u_0(z))}.$$

Changing the variables in the definition (2.3) of Q and using $u'_0(t) = -1/(tu_0(t))$,

$$Q(u_0(z)) = \sqrt{\frac{2}{\pi}} \int_{-\infty}^{u_0(z)} \text{Li}_{1/2}(e^{-y^2/2}) dy = -\sqrt{\frac{2}{\pi}} \int_0^z \frac{\text{Li}_{1/2}(t)}{tu_0(t)} dt \quad \text{for } 0 < |z| < 1 \text{ with } z \notin (-1, 0),$$

where the integration contour for the second integral is in the same domain as z . Combined with the definition (2.2) of B , we have

$$2B(z) - 2Q(u_0(z)) = \frac{1}{2\pi} \int_0^z \frac{\text{Li}_{1/2}(t)}{t} \left(\text{Li}_{1/2}(t) + \frac{2^{5/2}\sqrt{\pi}}{u_0(t)} \right) dt \quad (3.9)$$

for $0 < |z| < 1$ with $z \notin (-1, 0)$.

Define the function

$$g(z) := \frac{L_{1/2}(z)}{2\pi z} \left(L_{1/2}(z) + \frac{2^{5/2}\sqrt{\pi}}{U_0(z)} \right) \quad \text{for } z \in \mathcal{R}. \quad (3.10)$$

On the first sheet \mathcal{R}_1 this function agrees with the integrand of (3.9). It is analytic on \mathcal{R} except possibly at the branch point $z = 1$ (note that $z = 0$ is not on \mathcal{R}).

We look at the limit as $z \rightarrow 1$. Using (3.3) and (3.8), we find that

$$g(z) = -\frac{3}{u_0(z)^2} + \mathcal{O}(u_0(z)^{-1}) = \frac{3}{2(z-1)} + \mathcal{O}((z-1)^{-1/2}) \quad (3.11)$$

as $z \rightarrow 1$. In terms of the local coordinates $z - 1 = w^2$,

$$g(z)dz = \left(\frac{3}{w} + \mathcal{O}(1) \right) dw,$$

which implies that $\text{Res}_{z=1} \mathbf{g}(z)dz = 3$. Due to the pole of \mathbf{g} , the integral $\int_{0(1)}^z \mathbf{g}(t)dt$ depends on the choice of the path on \mathcal{R} . However, since the residue of \mathbf{g} at the pole is an integer, $\exp\left(\int_{0(1)}^z \mathbf{g}(t)dt\right)$ does not depend on the choice of path.

Lemma 3.4. *The function*

$$\mathbf{E}(z) := \exp\left(\int_{0(1)}^z \mathbf{g}(t)dt\right) = \exp\left(\int_{0(1)}^z \frac{\mathbf{L}_{1/2}(z)}{2\pi z} \left(\mathbf{L}_{1/2}(z) + \frac{2^{5/2}\sqrt{\pi}}{\mathbf{U}_0(z)}\right) dt\right)$$

is well defined and analytic on \mathcal{R} . We have $\mathbf{E}(z) = E(z)$ on $z \in \mathcal{R}_1$ satisfying $0 < |z| < 1$. Furthermore, \mathbf{E} has a zero of order 3 at the branch point $z = 1$. Finally, $\mathbf{E}(z)$ has continuous boundary values $\mathbf{E}(z \pm i0)$ for z on the interval $(-\infty, 0)$ in the boundary of \mathcal{R}_1 .

Proof. For $z \neq 1$, the value of $\mathbf{E}(z)$ does not depend on the choice of path of the integral on the Riemann surface since the residue of \mathbf{g} at the pole 1 is an integer. Being an integral of an analytic function, it is analytic possibly except at $z = 1$. As $z \rightarrow 1$, we have from (3.11)

$$\int_{0(1)}^z \mathbf{g}(t)dt = \frac{3}{2} \log(z-1) + \mathcal{O}(1),$$

which implies that $\mathbf{E}(z) = (z-1)^{3/2} f(z) = w^3 f(1+w^2)$ for an analytic function f and the local coordinates $z-1 = w^2$. This analysis shows that \mathbf{E} is analytic near $z = 1$ and it has a zero of order 3 at $z = 1$.

The continuity of the boundary values of \mathbf{E} follow from continuity of the boundary values for $\text{Li}_{1/2}$ and u_0 away from $z = 0$. \square

3.5 Behavior of the function $\mathbf{E}(z)$ near $z = 0$ on the second sheet

We conclude this section with the behavior of $\mathbf{E}(z)$ as $z \rightarrow 0^{(2)}$ on the second sheet \mathcal{R}_2 . The following result will be used in the proof of Lemma 4.9 in the next section.

Lemma 3.5. *We have*

$$\mathbf{E}(z) = -4u_0(z)^4(1 + \mathcal{O}(z^2)) \quad \text{as } z \rightarrow 0^{(2)}.$$

Proof. Fix a small real number $\epsilon \in (0, 1)$. We evaluate the exponent $\int_{0(1)}^z \mathbf{g}(t)dt$ of \mathbf{E} using a specific path that consists of several pieces:

$$\int_{0(1)}^z \mathbf{g}(t)dt = \int_{0(1)}^{\epsilon^{(1)}} \mathbf{g}(t)dt + \int_{\epsilon^{(1)}}^{(1-\epsilon)^{(1)}} \mathbf{g}(t)dt + \int_{(1-\epsilon)^{(1)}}^{(1-\epsilon)^{(2)}} \mathbf{g}(t)dt + \int_{(1-\epsilon)^{(2)}}^{\epsilon^{(2)}} \mathbf{g}(t)dt + \int_{\epsilon^{(2)}}^z \mathbf{g}(t)dt.$$

The contours for the second and fourth integrals are straight line segments. The first and last integrals are over contours such that $|t|$ stays small. The third integral is over a contour that satisfies that $|t-1|$ stays small. Note that the first four integrals do not depend on z .

Consider the third integral. By (3.10) and using the local coordinates $1-t = w^2$,

$$\lim_{\epsilon \rightarrow 0} \int_{(1-\epsilon)^{(1)}}^{(1-\epsilon)^{(2)}} \mathbf{g}(t)dt = \lim_{\epsilon \rightarrow 0} \int_{\sqrt{\epsilon}}^{-\sqrt{\epsilon}} \frac{3}{w} dw = \pm 3\pi i,$$

where the sign depends on the direction that the path goes around the branch point $z = 1$. Since $\mathbf{E}(z)$ is the exponential of the integral and $e^{3\pi i} = e^{-3\pi i} = -1$, both signs give the same contribution to $\mathbf{E}(z)$.

Now consider the first and the last integrals. From (3.10) and (3.8),

$$\mathbf{g}(z) = \frac{1}{2\pi z} \operatorname{Li}_{1/2}(z) \left(\operatorname{Li}_{1/2}(z) + \frac{2^{5/2}\sqrt{\pi}}{u_0(z)} \right) \quad \text{for } z \in \mathcal{R}_1 \quad (3.12)$$

and

$$\mathbf{g}(z) = \frac{1}{2\pi z} \left(\operatorname{Li}_{1/2}(z) + \frac{2^{3/2}\sqrt{\pi}}{u_0(z)} \right) \left(\operatorname{Li}_{1/2}(z) - \frac{2^{3/2}\sqrt{\pi}}{u_0(z)} \right) \quad \text{for } z \in \mathcal{R}_2. \quad (3.13)$$

Since $\operatorname{Li}_{1/2}(z) = z + \mathcal{O}(z^2)$ (see (3.1)),

$$\mathbf{g}(z) = -\frac{2}{\sqrt{\pi}(-\log z)^{1/2}} + \mathcal{O}(1) \quad \text{as } z \rightarrow 0^{(1)}$$

and

$$\mathbf{g}(z) = -\frac{4}{zu_0(z)^2} + \frac{\operatorname{Li}_{1/2}(z)^2}{2\pi z} = \frac{2}{z \log z} + \mathcal{O}(z) \quad \text{as } z \rightarrow 0^{(2)}.$$

Hence,

$$\lim_{\epsilon \rightarrow 0} \int_{0^{(1)}}^{\epsilon^{(1)}} \mathbf{g}(t) dt = -\frac{2}{\sqrt{\pi}} \lim_{\epsilon \rightarrow 0} \int_0^\epsilon \frac{1}{(-\log z)^{1/2}} dz = 0,$$

and for small enough $|z|$ and ϵ ,

$$\int_{\epsilon^{(2)}}^z \mathbf{g}(t) dt = 2 \int_\epsilon^z \frac{dt}{t \log t} + \mathcal{O}(z^2) + \mathcal{O}(\epsilon^2) = 2 \log(-\log z) - 2 \log(-\log \epsilon) + \mathcal{O}(z^2) + \mathcal{O}(\epsilon^2).$$

Finally, for the second and the fourth integrals, we have from (3.12) and (3.13),

$$\int_{\epsilon^{(1)}}^{(1-\epsilon)^{(1)}} \mathbf{g}(t) dt + \int_{(1-\epsilon)^{(2)}}^{\epsilon^{(2)}} \mathbf{g}(t) dt = \frac{2^{3/2}}{\sqrt{\pi}} \int_\epsilon^{1-\epsilon} \left(\operatorname{Li}_{1/2}(t) + \frac{\sqrt{2\pi}}{u_0(t)} \right) \frac{dt}{tu_0(t)}.$$

A direction computation shows that

$$\frac{2^{3/2}}{\sqrt{\pi}} \int_\epsilon^{1-\epsilon} \frac{\sqrt{2\pi}}{tu_0(t)^2} dt = -2 \int_\epsilon^{1-\epsilon} \frac{dt}{t \log t} = -2 \log(-\log(1-\epsilon)) + 2 \log(-\log \epsilon).$$

We postpone the computation of the remaining part of the integral.

Combining all together and taking $\epsilon \rightarrow 0$ first, we find that

$$\mathbf{E}(z) = -(-\log z)^2 (1 + \mathcal{O}(z^2)) e^C$$

as $z \rightarrow 0^{(2)}$, where

$$C = \lim_{\epsilon \rightarrow 0} \left[\frac{2^{3/2}}{\sqrt{\pi}} \int_\epsilon^{1-\epsilon} \operatorname{Li}_{1/2}(t) \frac{dt}{tu_0(t)} - 2 \log(-\log(1-\epsilon)) \right].$$

We now find the value of C using the lemma below. We may replace $\log(-\log(1-\epsilon))$ in the integral in the formula by $\log(\epsilon)$, and replace ϵ in the lower limit of the integral by 0 because the integral is convergent at $t = 0$. After that we change the variable t to $u_0(t) = -(-2 \log t)^{1/2}$ and find

$$C = \lim_{\epsilon \rightarrow 0} \left[-\frac{2^{3/2}}{\sqrt{\pi}} \int_{-\infty}^{-(2 \log(1-\epsilon))^{1/2}} \operatorname{Li}_{1/2}(e^{-t^2/2}) dt - 2 \log \epsilon \right].$$

Since $\text{Li}_{1/2}(e^{-t^2/2}) = \mathcal{O}(t^{-1})$ as $t \rightarrow 0$, which follows from (3.3), we may replace the upper limit of the integral by $-\sqrt{2\epsilon}$. Changing $\sqrt{2\epsilon} = \delta$, and using the evenness of the integrand, we find that $C = 4 \log 2$ from the lemma below. This completes the proof. \square

Lemma 3.6. *We have*

$$\lim_{\delta \rightarrow 0^+} \int_{\delta}^{\infty} \text{Li}_{1/2}(e^{-t^2/2}) dt + \sqrt{2\pi} \log(\delta) = -\sqrt{\frac{\pi}{2}} \log 2.$$

Proof. Using the power series formula (3.1) for the polylog and changing variables,

$$\int_{\delta}^{\infty} \text{Li}_{1/2}(e^{-t^2/2}) dt = \sum_{k=1}^{\infty} \frac{1}{k} \int_{\sqrt{k}\delta}^{\infty} e^{-t^2/2} dt = \int_{\delta}^{\infty} e^{-t^2/2} h([t^2\delta^{-2}]) dt$$

where $h(n) := 1 + \frac{1}{2} + \dots + \frac{1}{n}$ is the n -th partial sum of the harmonic series. We have

$$h(n) = \log n + \gamma + \epsilon_n,$$

where γ is the Euler-Mascheroni constant, and $\epsilon_n = O(n^{-1})$ as $n \rightarrow \infty$. Set $\tilde{\epsilon}_y := \epsilon_{[y]} + \log[y] - \log y$ and note that there is a constant $C > 0$ such that $|\tilde{\epsilon}_y| \leq \frac{C}{y}$ for all $y \geq 1$. Hence,

$$\int_{\delta}^{\infty} \text{Li}_{1/2}(e^{-t^2/2}) dt = \int_{\delta}^{\infty} e^{-t^2/2} (\log(t^2\delta^{-2}) + \gamma + \tilde{\epsilon}_{t^2\delta^{-2}}) dt.$$

Note that

$$\int_0^{\infty} e^{-t^2/2} dt = \sqrt{\frac{\pi}{2}} \quad \text{and} \quad \int_0^{\infty} e^{-t^2/2} \log(t^2) dt = -\sqrt{\frac{\pi}{2}} (\gamma + \log 2).$$

On the other hand,

$$\left| \int_{\delta}^{\infty} e^{-t^2/2} \tilde{\epsilon}_{t^2\delta^{-2}} dt \right| \leq C\delta^2 \left(\int_{\delta}^1 \frac{1}{t^2} dt + \int_1^{\infty} e^{-t^2/2} dt \right) = O(\delta).$$

Combining the above equations, we obtain the result. \square

4 Large time limit

Recall the distribution function F in (2.7). In this section we consider the large τ limit of $F(x_{\tau}; \tau, \gamma)$ with

$$x_{\tau} = -\tau + \frac{\pi^{1/4}}{\sqrt{2}} x \tau^{1/2}, \quad x \in \mathbb{R} \text{ fixed}, \quad (4.1)$$

and prove Theorem 1.5. This section is split into four subsections. In the first subsection, we analyze the asymptotics of the Fredholm determinant in the integrand of (2.7) and show that all but the first two terms of the Fredholm series expansion are exponentially small. In the second subsection, we show that the main contribution to $F(x_{\tau}; \tau, \gamma)$ comes from the integral involving the trace of the operator \mathbb{K}_z and then show that the integral can be expressed as a single integral involving polylog functions. In the third subsection we evaluate the integral using the method of steepest descent and, finally, in the fourth subsection we combine all the ingredients to prove Theorem 1.5.

4.1 Asymptotic analysis of the Fredholm determinant

The formula (2.7) of $F(x_\tau; \tau, \gamma)$ is given by an integral of the variable $z \in \mathbb{D} \setminus \{0\}$ where \mathbb{D} denotes the open unit disk. It is convenient to write

$$z = e^{\log |z|} e^{i\theta_0(z)/2}, \quad \theta = \theta_0(z) = \begin{cases} 2 \arg z, & \arg z \in [0, \pi], \\ -2(2\pi - \arg z), & \arg z \in (\pi, 2\pi). \end{cases}$$

Note that $\theta_0(z) \in (-2\pi, 2\pi]$. Using the above notation, the set \mathcal{S}_- (recall (1.5)), which is the set of solutions of $e^{-\xi^2/2} = z$ with $\operatorname{Re} \xi < 0$, can be enumerated as $\mathcal{S}_- = \{u_k\}_{k \in \mathbb{Z}}$ where

$$u_k = u_k(z) = -(-2 \log |z| + i\theta_k)^{1/2}, \quad \theta_k := -\theta_0(z) + 4\pi k.$$

In particular

$$u_0(z) = -(-2 \log |z| + i\theta_0)^{1/2} = -(-2 \log z)^{1/2}$$

agrees with the previous definition in (3.5). We denote the real part and the imaginary part of u_k by x_k and y_k :

$$u_k = u_k(z) = x_k + iy_k = x_k(z) + iy_k(z).$$

These values x_k and y_k satisfy the relations

$$x_k^2 - y_k^2 = -2 \log |z|, \quad 2x_k y_k = \theta_k. \quad (4.2)$$

Solving for x_k^2 , we have

$$(x_k(z))^2 = -\log |z| + \sqrt{(\log |z|)^2 + \theta_k^2/4}. \quad (4.3)$$

Also note that

$$\theta_k^2 \geq 4 \left(2k - \frac{\theta_0}{2\pi}\right)^2 \pi^2 \geq 4(2|k| - 1)^2 \pi^2 \quad \text{for } k \neq 0. \quad (4.4)$$

Recall the formula (2.5) of the function Φ appearing in (2.6). With the change $x \mapsto x_\tau$ in (4.1), it becomes

$$\Phi_\tau(\xi) := \Phi(\xi; z, x_\tau, \tau) = -\tau \left(\frac{1}{3} \xi^3 + \xi \right) + \tau^{1/2} \frac{\pi^{1/4} x}{\sqrt{2}} \xi - Q(\xi) \quad (4.5)$$

where Q is defined in (2.3). Using (4.2), we write

$$\operatorname{Re} \Phi_\tau(u_k) = -\frac{\tau}{3} p_z(x_k) + \tau^{1/2} \frac{\pi^{1/4} x}{\sqrt{2}} x_k - \operatorname{Re} Q(u_k) \quad (4.6)$$

for $u_k = x_k + iy_k \in \mathcal{S}_-$, where

$$p_z(w) := -2w^3 + 3w(1 - 2 \log |z|).$$

In the next few results, we estimate $\operatorname{Re} \Phi_\tau(u)$ for u on \mathcal{S}_- . These results involve constants which are given numerically to several digits and will be later combined to estimate a Fredholm determinant from its series. The exact value of these constants, as they appear here, could be relaxed at the cost of estimating the very first few terms of the series for the Fredholm determinant separately, taking advantage of the alternating signs that appear when computing determinants. However, we opt for giving these precise values of the constants and use only the first term of the series.

Lemma 4.1. *There is a constant $\delta \in (0, 1)$ such that*

$$p_z(x_k(z)) \geq \begin{cases} -1.42, & k = 0, \\ 5.81|k|^{3/2}, & k \neq 0, \end{cases}$$

for $1 - \delta \leq |z| \leq 1$.

Proof. From the definition of \mathcal{S}_- we have $x_k(z) < 0$. Thus, for all $|z|$ that satisfies the inequality $\log |z| \geq \frac{1}{2}(1 - 3 \cdot \sqrt[3]{2 \cdot 0.71 \cdot 0.71}) \approx -0.00136$,

$$p_z(x_k(z)) \geq -2x_k(z)^3 + 3\sqrt[3]{2 \cdot 0.71 \cdot 0.71}x_k(z) \geq -1.42.$$

Now, consider $k \neq 0$. Using (4.3), recalling $x_k(z) < 0$, and combining with (4.4),

$$x_k(z) \leq -\sqrt{-\log |z| + (2|k| - 1)\pi}, \quad k \neq 0.$$

The function $p_z(w)$ decreases in $w \in (-\infty, w_c)$ with $w_c = -\frac{1}{2}\sqrt{1 - 2\log |z|}$. For $k \neq 0$, we see that $-\sqrt{-\log |z| + (2|k| - 1)\pi} < w_c$, and hence,

$$\begin{aligned} p_z(x_k(z)) &\geq p_k(-\sqrt{-\log |z| + (2|k| - 1)\pi}) \\ &= (4\log |z| + (4|k| - 2)\pi - 3)\sqrt{-\log |z| + (2|k| - 1)\pi} \\ &\geq (4|k| - 2.9565)\sqrt{2|k| - 1}\pi^{3/2} \geq 1.0435\pi^{3/2}|k|^{3/2} \end{aligned}$$

provided $\log |z| > \frac{\pi}{4}(3/\pi - 0.9565) \approx -0.0012$. This completes the proof. \square

Corollary 4.2. *There exists a constant $\delta \in (0, 1)$ such that for every $\delta_1 \in (0, \delta)$, we can find $\tau_0 > 0$ so that*

$$\operatorname{Re} \Phi_\tau(u_k(z)) \leq \begin{cases} 0.4734\tau, & k = 0, \\ -1.9366|k|^{3/2}\tau, & k \neq 0, \end{cases}$$

for all $1 - \delta \leq |z| \leq 1 - \delta_1$ and $\tau \geq \tau_0$.

Proof. We use the formula (4.6) and the last lemma. By (4.3) and (4.4), for every $\epsilon \in (0, 1)$, there is a positive constant $C > 0$ such that $|x_k(z)| \leq C|k|^{1/2}$ for all $k \neq 0$ and $\epsilon \leq |z| \leq 1$. Using this and the fact that x is a fixed constant, we find that the term $\frac{\pi^{1/4}x\tau^{1/2}}{\sqrt{2}}x_k$ of the formula (4.6) is $\mathcal{O}(|k|^{1/2}\tau^{1/2})$ uniformly in $\epsilon \leq |z| \leq 1$. The remaining term of the formula, $\operatorname{Re} Q(u_k(z))$, is uniformly bounded in compacts of $|z| < 1$ as can be seen from the formula (2.4). Hence, we obtain the result for $k \neq 0$. The case $k = 0$ is similar. \square

We also need estimates on the points in \mathcal{S}_- .

Lemma 4.3. *For every fixed $\delta_1 \in (0, 1)$, there exists $c > 0$ such that*

$$|u_k(z)| \geq c\sqrt{|k| + 1} \quad \text{and} \quad |u_j(z) + u_k(z)| \geq c\sqrt{|j| + |k| + 2}$$

for all $0 < |z| < 1 - \delta_1$ and $k, j \in \mathbb{Z}$.

Proof. From (4.3), $x_k^2 \geq -\log |z| + |\theta_k|/2 > -\log(1 - \delta_1) + |\theta_k|/2 > 0$. From (4.4), $|\theta_k| \geq 2(2|k| - 1)\pi$ for $k \neq 0$. Thus, there exists $c > 0$ such that $|u_k|^2 \geq x_k^2 \geq c^2(|k| + 1)$ for all k . This implies the first inequality. The second inequality follows from the first inequality since $x_j, x_k < 0$, and hence

$$|u_j + u_k| \geq -x_j - x_k \geq c\sqrt{|j| + 1} + c\sqrt{|k| + 1} \geq c\sqrt{|j| + |k| + 2}.$$

□

The kernel of the operator \mathbb{K}_z is given by (2.6). With the change $x \mapsto x_\tau$ in (4.1), the kernel becomes

$$\mathbf{K}_z(\xi_1, \xi_2) = \sum_{u \in \mathcal{S}_-} \frac{e^{\Phi_\tau(\xi_1) + \Phi_\tau(u) + \frac{\gamma}{2}(\xi_1^2 - u^2)}}{\xi_1 u(\xi_1 + u)(u + \xi_2)} \quad \text{for } \xi_1, \xi_2 \in \mathcal{S}_-,$$

where Φ_τ is defined in (4.5). We now estimate this kernel.

Lemma 4.4. *There is a constant $\delta \in (0, 1)$ such that for every $\delta_1 \in (0, \delta)$, we can find $\tau_0 > 0$ and $C > 0$ so that*

$$\sum_{k=1}^N |\mathbf{K}_z(\xi, u_{\ell_k})|^2 \leq (C \log N) e^{2 \operatorname{Re} \Phi_\tau(\xi) + 0.9468\tau}$$

for all $\xi \in \mathcal{S}_-$, for all $N \geq 2$ and distinct integers ℓ_1, \dots, ℓ_N , and for all $\tau \geq \tau_0$ and $1 - \delta \leq |z| \leq 1 - \delta_1$.

Proof. Let δ, δ_1 and τ_0 be the constants from Corollary 4.2. Every $\xi \in \mathcal{S}_-$ satisfies $e^{-\xi^2/2} = z$, and hence, $|e^{-\gamma\xi^2/2}| = |z|^\gamma$. Thus, using Lemma 4.3,

$$|\mathbf{K}_z(\xi, u)| \leq \frac{e^{\operatorname{Re} \Phi_\tau(\xi)}}{c^3} f(u) \quad \text{where} \quad f(u) := \sum_{j \in \mathbb{Z}} \frac{e^{\operatorname{Re} \Phi_\tau(u_j)}}{|u_j + u|} \quad (4.7)$$

for $\xi, u \in \mathcal{S}_-$, where the constant $c > 0$ is from Lemma 4.3. For $u = u_\ell$, Corollary 4.2 and Lemma 4.3 imply that

$$f(u_\ell) \leq \frac{e^{0.4734\tau}}{c\sqrt{|\ell|+2}} + \sum_{j \neq 0} \frac{e^{-1.9366|j|^{3/2}\tau}}{c\sqrt{|\ell|+|j|+2}}.$$

for all $\tau \geq \tau_0$. Adjusting the value of τ_0 if needed, the sum is smaller than the single term, and hence,

$$f(u_\ell) \leq \frac{2e^{0.4734\tau}}{c\sqrt{|\ell|+2}}.$$

Inserting the above inequalities into (4.7) and noting that $\sum_{k=1}^N \frac{1}{|\ell|+2} \leq \log N$ since ℓ_1, \dots, ℓ_N are distinct integers, we complete the proof. □

We are now ready to prove the main result of this subsection.

Proposition 4.5. *Change $x \mapsto x_\tau$ as (4.1). There is a constant $\delta \in (0, 1)$ such that for every $\delta_1 \in (0, \delta)$,*

$$\det(\mathbb{I} - \mathbb{K}_z) = 1 - \operatorname{Tr} \mathbb{K}_z + \mathcal{O}(e^{-0.51\tau}) \quad \text{as } \tau \rightarrow \infty,$$

uniformly for $1 - \delta \leq |z| \leq 1 - \delta_1$.

Proof. From the series expansion of Fredholm determinants,

$$\det(\mathbb{I} - \mathbb{K}_z) = 1 - \operatorname{Tr} \mathbb{K}_z + \sum_{N=2}^{\infty} \frac{(-1)^N}{N!} D_N \quad \text{with} \quad D_N := \sum_{\ell_1, \dots, \ell_N \in \mathbb{Z}}^* \det(\mathbf{K}_z(u_{\ell_j}, u_{\ell_k}))_{j,k=1}^N$$

where the superscript $*$ means that the sum is taken over ℓ_j 's that are distinct. For distinct ℓ_j 's, the

Hadamard's inequality and Lemma 4.4 give us that

$$|\det(\mathbf{K}_z(u_{\ell_j}, u_{\ell_k}))_{j,k=1}^N| \leq \prod_{j=1}^N \left(\sum_{k=1}^N |\mathbf{K}_z(u_{\ell_j}, u_{\ell_k})|^2 \right)^{1/2} \leq (C \log N)^{N/2} e^{0.4734\tau N} \prod_{j=1}^N e^{\operatorname{Re} \Phi_\tau(u_{\ell_j})}.$$

Hence,

$$|D_N| \leq (C \log N)^{N/2} e^{0.4734\tau N} \sum_{\ell_1, \dots, \ell_N \in \mathbb{Z}}^* \prod_{j=1}^N e^{\operatorname{Re} \Phi_\tau(u_{\ell_j})}.$$

Considering the case when one of the indices ℓ_j is zero separately and using a symmetry,

$$\begin{aligned} \sum_{\ell_1, \dots, \ell_N \in \mathbb{Z}}^* \prod_{j=1}^N e^{\operatorname{Re} \Phi_\tau(u_{\ell_j})} &= \sum_{\ell_1, \dots, \ell_N \neq 0}^* \prod_{j=1}^N e^{\operatorname{Re} \Phi_\tau(u_{\ell_j})} + N e^{\operatorname{Re} \Phi_\tau(u_0)} \sum_{\ell_2, \dots, \ell_N \neq 0}^* \prod_{j=2}^N e^{\operatorname{Re} \Phi_\tau(u_{\ell_j})} \\ &\leq \left(\sum_{\ell \neq 0} e^{\operatorname{Re} \Phi_\tau(u_\ell)} \right)^N + N e^{\operatorname{Re} \Phi_\tau(u_0)} \left(\sum_{\ell \neq 0} e^{\operatorname{Re} \Phi_\tau(u_\ell)} \right)^{N-1}. \end{aligned}$$

Now, Corollary 4.2 implies that

$$\sum_{\ell \in \mathbb{Z} \setminus \{0\}} e^{\operatorname{Re} \Phi_\tau(u_\ell)} \leq 2 \sum_{\ell=1}^{\infty} e^{-1.9366\ell^{3/2}\tau} \leq \frac{2e^{-1.9366\tau}}{1 - e^{-1.9366\tau}} \quad \text{and} \quad e^{\operatorname{Re} \Phi_\tau(u_0)} \leq e^{0.4734\tau}$$

for all large enough τ . Therefore,

$$\sum_{\ell_1, \dots, \ell_N \in \mathbb{Z}}^* \prod_{j=1}^N e^{\operatorname{Re} \Phi_\tau(u_{\ell_j})} \leq C_1^N e^{-1.9366\tau N} e^{2.41\tau}$$

for a new constant $C_1 > 0$. Thus, adjusting the constant τ_0 if needed, we find that for a yet new constant $C_2 > 0$

$$|D_N| \leq (\sqrt{C_2 \log N})^N e^{-1.4632\tau N + 2.41\tau}$$

for $\tau \geq \tau_0$ and $N \geq 2$. From this and using $N! \geq (N/e)^N$, we conclude that

$$\left| \sum_{N=2}^{\infty} \frac{(-1)^N}{N!} D_N \right| \leq \sum_{N=2}^{\infty} \left(\frac{e\sqrt{C_2 \log N}}{N} \right)^N e^{-1.4632\tau N + 2.41\tau} \leq C_3 \sum_{N=2}^{\infty} e^{-1.4632\tau N + 2.41\tau}$$

for a new constant $C_3 > 0$, and hence we find that the sum is $\mathcal{O}(e^{-0.51\tau})$. □

4.2 From a Fredholm determinant integral to a polylog integral

Proposition 4.5 implies the following result for the distribution function.

Proposition 4.6. *We have*

$$F(x_\tau; \tau, \gamma) = 1 - \oint_{|z|=R} e^{x_\tau A_1(z) + \tau A_2(z) + 2B(z)} \operatorname{Tr}(\mathbb{K}_z) \frac{dz}{2\pi i z} + \mathcal{O}(e^{-0.002\tau})$$

as $\tau \rightarrow \infty$ for any $R \in (0, 1)$.

Proof. Since the integrand in the result is analytic in $0 < |z| < 1$, it is enough to prove the statement for

$R = 1 - \delta$ where $\delta > 0$ is the constant from Proposition 4.5. We insert the result of Proposition 4.5 into the formula (2.7) of $F(x_\tau; \tau, \gamma)$. Since $A_1(z)$, $A_2(z)$, and $B(z)$ are analytic in the unit disc, and they are all 0 at $z = 0$, by the residue theorem, we obtain the term 1. We now consider the error term. Recalling (4.1),

$$\max_{|z|=R} \operatorname{Re}(x_\tau A_1(z) + \tau A_2(z) + 2B(z)) = \frac{\tau}{\sqrt{2\pi}} \max_{|z|=R} \operatorname{Re}(\operatorname{Li}_{3/2}(z) - \operatorname{Li}_{5/2}(z)) + \mathcal{O}(\tau^{1/2}).$$

Using the series representation (3.1) of polylog functions,

$$|\operatorname{Li}_{3/2}(z) - \operatorname{Li}_{5/2}(z)| \leq \sum_{k=1}^{\infty} |z|^k (k^{-3/2} - k^{-5/2}) \leq \zeta(3/2) - \zeta(5/2) < 1.271.$$

Here ζ is the Riemann zeta function. Hence,

$$\max_{|z|=R} \operatorname{Re}(x_\tau A_1(z) + \tau A_2(z) + 2B(z)) < 0.5071\tau \quad (4.8)$$

for all large enough τ , and

$$\oint_{|z|=R} e^{x_\tau A_1(z) + \tau A_2(z) + 2B(z)} \mathcal{O}(e^{-0.51\tau}) dz = \mathcal{O}(e^{-0.002\tau})$$

and we obtain the result. \square

Since the kernel of \mathbb{K}_z is given by a sum, $\operatorname{Tr} \mathbb{K}_z$ is a double sum. We show that the main contribution to the trace comes from a single term of the sum.

Lemma 4.7. *With the change $x \mapsto x_\tau$ in (4.1), there is a constant $\delta \in (0, 1)$ such that for every $\delta_1 \in (0, \delta)$,*

$$\operatorname{Tr} \mathbb{K}_z = \frac{e^{2\Phi_\tau(u_0(z))}}{4u_0(z)^4} + \mathcal{O}(e^{-1.4632\tau}) \quad \text{as } \tau \rightarrow \infty,$$

uniformly for $1 - \delta \leq |z| \leq 1 - \delta_1$.

A direct calculation shows that $2 \operatorname{Re} \Phi_\tau(u_0(-1 \pm i0)) \approx -3.8795\tau$, so the term singled out above is neglectible when compared with the error term for z close to -1 . However, the importance of the formula above comes from its uniformity: when z moves away from -1 , the formula is still valid, and for z sufficiently away from -1 the contribution from the term $e^{2\Phi_\tau(u_0(z))}$ above becomes dominant over the error term.

Later we will use the asymptotic formula above to compute the integral in Proposition 4.6. The major contribution to that integral will come from a critical point $z = z_c$ of the exponent of the integrand and, at this critical point, the contribution that will arise from the term $e^{2\Phi_\tau(u_0(z_c))}$ will indeed be larger than the error term.

Also, the asymptotic formula above has to be interpreted carefully when considering $z < 0$, as the term $\operatorname{Tr} \mathbb{K}_z$ is analytic in $0 < |z| < 1$, but $u_0(z)$ is analytic only in $\mathbb{C} \setminus ((-\infty, 0] \cup [1, \infty))$. Nonetheless, it is easy to check from the definition that $u_0(z)$ and $\frac{1}{u_0(z)}$ are bounded in any compact subset of the open set $\{z : \operatorname{Re} z < 0\}$, including on the line segment $(-\infty, 0)$, and admit continuous boundary values when z approaches $(-\infty, 0)$ from above or below (although these boundary values do not coincide). Therefore, as will be done later without further mention, these asymptotics can be used to integrate $\operatorname{Tr} \mathbb{T}_z$ along any contour that intersects $(-\infty, 0)$ only at its endpoints.

Proof of Lemma 4.7. By the definition of the kernel,

$$\mathrm{Tr} \mathbb{K}_z = \sum_{u \in \mathcal{S}_-} \mathbf{K}_z(u, u) = \sum_{k \in \mathbb{Z}} \sum_{j \in \mathbb{Z}} \frac{e^{\Phi_\tau(u_k) + \Phi_\tau(u_j) + \frac{\gamma}{2}(u_k^2 - u_j^2)}}{u_k u_j (u_j + u_k)^2} = \frac{e^{2\Phi_\tau(u_0)}}{4u_0^4} + \mathrm{REST}$$

where we have set

$$\mathrm{REST} = \sum_{(k,j) \neq (0,0)} \frac{e^{\Phi_\tau(u_k) + \Phi_\tau(u_j) + \frac{\gamma}{2}(u_k^2 - u_j^2)}}{u_k u_j (u_j + u_k)^2}.$$

We estimate REST. Let $\tau_0 > 0$ be the constant from Corollary 4.2. Using $|e^{\frac{\gamma}{2}u_k^2}| = |z|^\gamma$ and Lemma 4.3,

$$|\mathrm{REST}| \leq \frac{1}{c^4} \left[e^{\mathrm{Re} \Phi_\tau(u_0)} \sum_{j \neq 0} e^{\mathrm{Re} \Phi_\tau(u_j)} + \sum_{k \neq 0} e^{\mathrm{Re} \Phi_\tau(u_k)} \sum_{j \in \mathbb{Z}} e^{\mathrm{Re} \Phi_\tau(u_j)} \right].$$

From Corollary 4.2 we have $e^{\mathrm{Re} \Phi_\tau(u_0)} \leq e^{0.4734\tau}$,

$$\sum_{k \neq 0} e^{\mathrm{Re} \Phi_\tau(u_k)} \leq 2 \sum_{k=1}^{\infty} e^{-1.9366|k|^{3/2}\tau} \leq \frac{2e^{-1.9366\tau}}{1 - e^{-1.9366\tau}}$$

and

$$\sum_{j \in \mathbb{Z}} e^{\mathrm{Re} \Phi_\tau(u_j)} \leq e^{0.4734\tau} + \frac{2e^{-1.9366\tau}}{1 - e^{-1.9366\tau}}$$

for all $\tau \geq \tau_0$. Hence, $|\mathrm{REST}| = \mathcal{O}(e^{-1.4632\tau})$ and we obtain the result. \square

We arrived at the main result of this subsection. To state it, we define the functions

$$\begin{aligned} f_1(z) &:= \frac{1}{\sqrt{2\pi}} \mathrm{Li}_{3/2}(z) - \frac{1}{\sqrt{2\pi}} \mathrm{Li}_{5/2}(z) - 2u_0(z) - \frac{2}{3}u_0(z)^3, \\ f_2(z) &:= 2u_0(z) - \frac{1}{\sqrt{2\pi}} \mathrm{Li}_{3/2}(z), \\ E(z) &:= e^{2B(z) - 2Q(u_0(z))} \end{aligned} \tag{4.9}$$

for $z \in \mathbb{C} \setminus ((-\infty, 0] \cup [1, \infty))$, where B and Q are given in (2.2) and (2.3).

Corollary 4.8. *There is a constant $\epsilon \in (0, 1)$ such that*

$$F(x_\tau; \tau, \gamma) = 1 - \frac{1}{8\pi i} \int_{\Gamma} \frac{E(z) e^{\tau f_1(z) + \tau^{1/2} \hat{x} f_2(z)}}{z u_0(z)^4} dz + \mathcal{O}(e^{-0.002\tau}) \quad \text{with } \hat{x} := \frac{\pi^{1/4} x}{\sqrt{2}} \tag{4.10}$$

as $\tau \rightarrow \infty$, where Γ is any simple contour in the domain $\mathbb{C} \setminus ((-\infty, 0] \cup [1, \infty))$ that starts at $a - i0$ and ends at $b + i0$, for any $a, b \in (-1 - \epsilon, -1 + \epsilon)$.

Proof. Observe that the integrand of (4.10) is analytic in $\mathbb{C} \setminus ((-\infty, 0] \cup [1, \infty))$. Let R for the contour in Proposition 4.6 be any number in $[1 - \delta, 1)$ where δ is the constant from Lemma 4.7. We regard the contour as an arc that starts at $-R - i0$ and ends at $-R + i0$. We insert the result of Lemma 4.7 into the formula of Proposition 4.6. By the definitions, $e^{x_\tau A_1(z) + \tau A_2(z) + 2B(z)}$ times $e^{2\Phi_\tau(u_0(z))}$ is $E(z) e^{\tau f_1(z) + \tau^{1/2} \hat{x} f_2(z)}$, and hence we obtain the result when the contour is an arc that starts at $-R - i0$ and ends at $-R + i0$. Since the integrand of (4.10) is analytic in $\mathbb{C} \setminus ((-\infty, 0] \cup [1, \infty))$, we can deform the contour to any other simple contour in the same domain but with the same end points $-R - i0$ and $-R + i0$.

We now show that there is $\epsilon > 0$ such that for any $-1 - \epsilon < a_1 < a_2 < -1 + \epsilon$, the integral over the line segment from $a_1 - i0$ to $a_2 - i0$ or the line segments from $a_1 + i0$ to $a_2 + i0$ are exponentially small in τ . This allows us to change the end points and still have the formula (4.10) valid, thus concluding the proof. Noting $u_0(-1 \pm i0) = -\frac{1 \mp i}{\sqrt{2}}\sqrt{2\pi}$ and using the numerical values $\text{Li}_{3/2}(-1) = -0.7651 \dots$ and $\text{Li}_{5/2}(-1) = -0.8671 \dots$, we see that

$$\text{Re } f_1(-1 \pm i0) = \frac{1}{\sqrt{2\pi}} \text{Li}_{3/2}(-1) - \frac{1}{\sqrt{2\pi}} \text{Li}_{5/2}(-1) + 2\sqrt{\pi} - \frac{4\pi\sqrt{\pi}}{3} = -3.8388 \dots$$

Thus, by continuity of the integrand up to the boundary $(-\infty, 0) \pm i0$, we find that the integrand is $\mathcal{O}(e^{-3\tau})$ in a neighborhood of $z = -1$, as we wanted. \square

4.3 Asymptotic analysis of polylog integral

We now evaluate the integral on the right-hand side of (4.10) as $\tau \rightarrow \infty$ using the method of steepest descent. It turns out that the main contribution to the integral comes from a point on the Riemann surface on which the integrand admits analytic extension.

Recall the Riemann surface \mathcal{R} introduced in Section 3.2. Define the one-form

$$\omega_\tau = \frac{E(z)e^{\tau f_1(z) + \tau^{1/2} \hat{x} f_2(z)}}{8\pi i z U_0(z)^4} dz \quad (4.11)$$

on \mathcal{R} , where E, f_1, f_2, U_0 are extensions of E, f_1, f_2, u_0 defined in Section 3. Using this notation, the equation (4.10) becomes

$$F(x_\tau; \tau, \gamma) = 1 - \int_\Gamma \omega_\tau + \mathcal{O}(e^{-0.002\tau}) \quad (4.12)$$

where Γ is a contour in the first sheet \mathcal{R}_1 , which we now take to start at $-1 - i0$ and end at $-1 + i0$. We will see that as $\tau \rightarrow \infty$, the main contribution to the integral comes from a neighborhood of order $\tau^{-1/2}$ of the point $z = 0^{(2)}$ on the second sheet \mathcal{R}_2 . We deform Γ to a new contour $\Gamma' = \Gamma_1 \cup \Gamma_2 \cup \Gamma_3$ defined as follows (see Figure 6).

- $\Gamma_1 = \gamma_1 \cup \bar{\gamma}_1$ where γ_1 is a contour that starts from the point $-1 - i0$ in the lower half plane, moves in the lower half plane of \mathcal{R}_1 until it hits a point on the branch cut on $(1, \infty)$, and then moves to the upper half plane in the second sheet \mathcal{R}_2 until it ends at a point in the upper imaginary axis. Concretely, we use the contour

$$\gamma_1(t) = e^{-\frac{1}{2}(t^2 - \pi) + i\sqrt{\pi}t} \quad \text{for } -\sqrt{\pi} \leq t \leq \sqrt{\pi}/2,$$

where the part for $-\sqrt{\pi} \leq t \leq 0$ lies on \mathcal{R}_1 and the part for $0 \leq t \leq \sqrt{\pi}/2$ lies on \mathcal{R}_2 . Note that $\gamma_1(-\sqrt{\pi}) = -1 - i0$ and $\gamma_1(0) = e^{\pi/2} > 0$. Also, $\gamma_1(\sqrt{\pi}/2) = ie^{\frac{3\pi}{8}}$ on \mathcal{R}_2 .

- $\Gamma_2 = \gamma_2 \cup \bar{\gamma}_2$, where γ_2 is the line segment on the imaginary axis in \mathcal{R}_2 joining the point $\gamma_2(\sqrt{\pi}/2) = ie^{3\pi/8}$ and the point $i\tau^{-5/12}$.
- Γ_3 is a contour in \mathcal{R}_2 joining the point $i\tau^{-5/12}$ and $-i\tau^{-5/12}$. We take it to be the union of straight line segments with a semicircle, namely

$$\Gamma_3 = \{z = \tau^{-1/2}e^{i\theta} \mid -\pi/2 \leq \theta \leq \pi/2\} \cup \{z = iy \mid \tau^{-1/2} \leq |y| \leq \tau^{-5/12}\},$$

oriented downwards. As we will show, this part gives the main contribution to the integral.

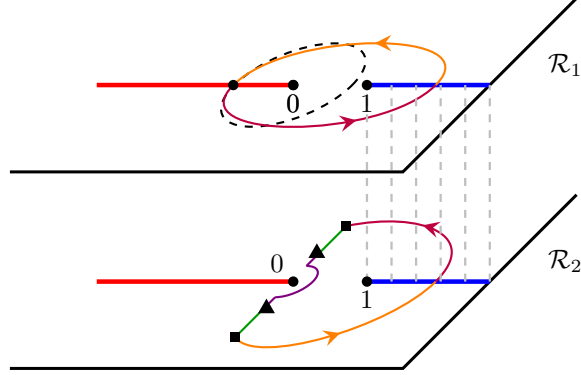


Figure 6: The dashed curve in the first sheet is the original contour Γ . The solid curve is the contour $\Gamma' = \Gamma_1 \cup \Gamma_2 \cup \Gamma_3$. The contour Γ_3 is the arc on the second sheet that connects the two marked triangle points. Γ_2 consists of two straight line segments each connecting one marked triangle point and one marked square point. The remaining part of the solid curve is Γ_1 .

In the above, the notation $\overline{\gamma_j}$ denotes the contour in \mathcal{R} whose intersection with \mathcal{R}_k is the complex conjugation of $\gamma_j \cap \mathcal{R}_k$.

We now evaluate the integral of ω_τ on each part of $\Gamma' = \Gamma_1 \cup \Gamma_2 \cup \Gamma_3$.

Lemma 4.9. *We have*

$$\lim_{\tau \rightarrow \infty} \int_{\Gamma_3} \omega_\tau = \frac{1}{\sqrt{2\pi}} \int_x^\infty e^{-\frac{1}{2}u^2} du.$$

Proof. The contour Γ_3 is on the second sheet \mathcal{R}_2 . From the definition (4.11) of ω_τ , Lemma 3.3, and Lemma 3.5,

$$\int_{\Gamma_3} \omega_\tau = -\frac{1}{2\pi i} \int_{\Gamma_3} e^{H_\tau(z)} (1 + \mathcal{O}(z^2)) \frac{dz}{z}$$

with

$$H_\tau(z) := \frac{\tau}{\sqrt{2\pi}} (\text{Li}_{3/2}(z) - \text{Li}_{5/2}(z)) - \frac{\tau^{1/2}\hat{x}}{\sqrt{2\pi}} \text{Li}_{3/2}(z) = \frac{\tau}{8\sqrt{\pi}} z^2 + \tau \mathcal{O}(z^3) - \frac{\tau^{1/2}\hat{x}}{\sqrt{2\pi}} z + \tau^{1/2} \mathcal{O}(z^2)$$

where the error terms are independent of τ . Using $|z| \leq \tau^{-5/12}$ for the error term and changing the variables $z = \tau^{-1/2}s$, we find that

$$\int_{\Gamma_3} \omega_\tau = -\frac{1}{2\pi i} \int_{\tau^{1/2}\Gamma_3} e^{\frac{1}{8\sqrt{\pi}}s^2 - \frac{\hat{x}}{\sqrt{2\pi}}s + \mathcal{O}(\tau^{-1/4})} \frac{ds}{s} (1 + \mathcal{O}(\tau^{-5/6})).$$

The new contour $\tau^{1/2}\Gamma_3$ consists of the line segment from $-i\tau^{1/12}$ and $-i$, the line segment i and $i\tau^{1/12}$, and the half-circle, $\{z = e^{i\theta} | -\pi/2 \leq \theta \leq \pi/2\}$. It is oriented downwards. Note that the pole $s = 0$ is located to the left of the contour. Reversing the orientation, recalling $\hat{x} = \frac{\pi^{1/4}\hat{x}}{\sqrt{2}}$, and changing the variables $s = i2\pi^{1/4}u$, we find that

$$\lim_{\tau \rightarrow \infty} \int_{\Gamma_3} \omega_\tau = \frac{1}{2\pi i} \int_{-i\infty}^{i\infty} e^{\frac{1}{8\sqrt{\pi}}s^2 - \frac{\hat{x}}{\sqrt{2\pi}}s} \frac{ds}{s} = \frac{1}{2\pi i} \int_{-\infty}^{\infty} e^{-\frac{1}{2}u^2 - i\hat{x}u} \frac{du}{u},$$

where the contour of the middle integral goes around the pole $s = 0$ through the right half plane, and the contour of the last integral goes around the pole $u = 0$ through the lower half plane. Changing variables $u \mapsto u - ix$, it is easy to show that the last integral is a function of x whose derivative is $-\frac{1}{\sqrt{2\pi}}e^{-x^2/2}$ and tends to zero as $x \rightarrow +\infty$. Hence, we find that

$$\frac{1}{2\pi i} \int_{-\infty}^{\infty} e^{-\frac{1}{2}u^2 - i xu} \frac{du}{u} = \frac{1}{\sqrt{2\pi}} \int_x^{\infty} e^{-\frac{1}{2}u^2} du$$

and we obtain the result. \square

Lemma 4.10. *We have*

$$\lim_{\tau \rightarrow \infty} \int_{\Gamma_2} \omega_\tau = 0.$$

Proof. Since $\Gamma_2 = \gamma_2 \cup \overline{\gamma_2}$, by symmetry, it is enough to consider γ_2 which is the line segment in \mathcal{R}_2 from the point $ie^{3\pi/8}$ to $i\tau^{-5/12}$. From the definition of ω_τ and Lemmas 3.1 and 3.3,

$$\int_{\gamma_2} \omega_\tau = \frac{i}{8\pi} \int_{\tau^{-5/12}}^{e^{3\pi/8}} \frac{E(iy)}{yu_0(iy)^4} e^{-\frac{\tau}{\sqrt{2\pi}}(\text{Li}_{5/2}(iy) - \text{Li}_{3/2}(iy)) - \frac{\tau^{1/2}}{\sqrt{2\pi}} \text{Li}_{3/2}(iy)} dy.$$

By the integral representation (3.2),

$$\text{Re}(\text{Li}_{5/2}(iy) - \text{Li}_{3/2}(iy)) = \frac{y^2}{\sqrt{\pi}} \int_0^\infty \frac{1}{e^{2t} + y^2} \left(2t^{1/2} - \frac{4}{3}t^{3/2} \right) dt.$$

The integrand changes its sign at $t = 3/2$. Splitting the integral into two, numerical evaluations show that, for $0 \leq y \leq e^{3\pi/8}$,

$$\begin{aligned} \text{Re}(\text{Li}_{5/2}(iy) - \text{Li}_{3/2}(iy)) &\geq \frac{y^2}{\sqrt{\pi}} \int_0^{\frac{3}{2}} \frac{1}{e^{2t} + e^{3\pi/4}} \left(2t^{1/2} - \frac{4}{3}t^{3/2} \right) dt - \frac{y^2}{\sqrt{\pi}} \int_{\frac{3}{2}}^\infty \frac{1}{e^{2t}} \left(\frac{4}{3}t^{3/2} - 2t^{1/2} \right) dt \\ &= \frac{y^2}{\sqrt{\pi}} ((0.06729 \dots) - (0.02600 \dots)) > (0.02)y^2. \end{aligned}$$

On the other hand, the function $y \mapsto \text{Li}_{3/2}(iy)$ is continuous in the interval $[0, e^{3\pi/8}]$ and has the behavior $\text{Re} \text{Li}_{3/2}(iy) = \text{Re}(iy - \frac{y^2}{2\sqrt{2}} + O(y^3)) = -\frac{y^2}{2\sqrt{2}} + O(y^3)$ as $y \rightarrow 0$. Hence, there is a constant $c_1 > 0$ such that

$$|\text{Re} \text{Li}_{3/2}(iy)| \leq c_1 y^2 \quad \text{for every } y \in [0, e^{3\pi/8}].$$

In addition, by Lemma 3.5 and continuity, there is $c_2 > 0$ such that $|E(iy)| \leq c_2 |u_0(iy)|^4$ on the contour. Combining together, we find that there is a constant $c_3 > 0$ such that

$$\left| \int_{\Gamma_2} \omega_\tau \right| \leq c_2 \int_{\tau^{-5/12}}^{e^{3\pi/8}} \frac{e^{-c_3 \tau y^2}}{y} dy \leq c_2 \int_{\tau^{1/12}}^\infty \frac{e^{-c_3 u^2}}{u} du$$

and we obtain the result. \square

Lemma 4.11. *We have*

$$\lim_{\tau \rightarrow \infty} \int_{\Gamma_1} \omega_\tau = 0.$$

Proof. By symmetry, it is enough to consider only the part γ_1 of Γ_1 that starts on the lower half plane on

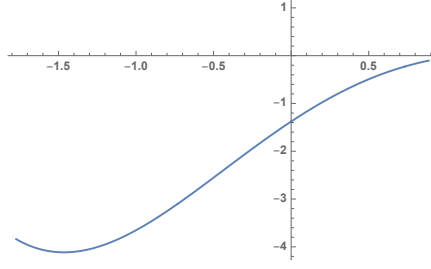


Figure 7: The plot of $\operatorname{Re} f_1(\gamma_1(t))$ for $t \in [-\sqrt{\pi}, \sqrt{\pi}/2]$: the maximum is $-0.104065 \dots$ at $t = \sqrt{\pi}/2$.

\mathcal{R}_1 and ends on the upper half plane on \mathcal{R}_2 . We specified γ_1 explicitly by its parametrization

$$\gamma_1(t) = e^{-\frac{\eta(t)^2}{2}} = e^{-\frac{1}{2}(t^2 - \pi) + i\sqrt{\pi}t} \quad \text{where } \eta(t) = t - i\sqrt{\pi} \text{ for } -\sqrt{\pi} \leq t \leq \sqrt{\pi}/2,$$

and we take $\gamma_1(t)$ to be on the first sheet \mathcal{R}_1 for $-\sqrt{\pi} \leq t < 0$, and on the second sheet \mathcal{R}_2 for $0 < t \leq \sqrt{\pi}/2$. We note that $\gamma_1(-\sqrt{\pi}) = -1 - i0$, $\gamma_1(0) = e^{\pi/2}$, and $\gamma_1(\sqrt{\pi}/2) = ie^{3\pi/8}$. It is straightforward to check that $u_0(\gamma_1(t)) = \eta(t)$ for $-\sqrt{\pi} \leq t < 0$ and $u_0(\gamma_1(t)) = -\eta(t)$ for $0 < t \leq \sqrt{\pi}/2$. From the definition (4.11) of ω_τ ,

$$\int_{\gamma_1} \omega_\tau = \frac{1}{8\pi i} \int_{-\sqrt{\pi}}^{\sqrt{\pi}/2} \frac{E(\gamma_1(t))}{\eta(t)^4} e^{\tau f_1(\gamma_1(t)) + \tau^{1/2} \hat{x} f_2(\gamma_1(t))} \gamma_1'(t) dt. \quad (4.13)$$

We have $|\eta(t)^4| = |t - i\sqrt{\pi}|^4 \geq \pi^2$. Each of the functions $|\gamma_1'(t)|$, $|E(\gamma_1(t))|$ and $\operatorname{Re} f_2(\gamma_1(t))$ is bounded along the contour: for γ_1' this is clear from its definition whereas for $\operatorname{Re} f_2$ and E this follows from Lemmas 3.3 and 3.4. From the definition and Lemma 3.3,

$$f_1(\gamma_1(t)) = \begin{cases} \frac{1}{\sqrt{2\pi}} \operatorname{Li}_{3/2}(\gamma_1(t)) - \frac{1}{\sqrt{2\pi}} \operatorname{Li}_{5/2}(\gamma_1(t)) - 2\eta(t) - \frac{2}{3}\eta(t)^3, & t < 0, \\ \frac{1}{\sqrt{2\pi}} \operatorname{Li}_{3/2}(\gamma_1(t)) - \frac{1}{\sqrt{2\pi}} \operatorname{Li}_{5/2}(\gamma_1(t)), & t \geq 0. \end{cases}$$

Using this explicit expression one can check numerically that the function $\operatorname{Re} f_1(\gamma_1(t))$ for $-\sqrt{\pi} \leq t \leq \sqrt{\pi}/2$ has its maximum at $t = \sqrt{\pi}/2$, and the maximum value is negative, see Figure 7. One could also rigorously prove that $\operatorname{Re} f_1(\gamma_1(t)) \leq -0.03$ in this interval by expanding the difference $\operatorname{Li}_{3/2}(\gamma_1(t)) - \operatorname{Li}_{5/2}(\gamma_1(t))$ in series and viewing the expression for f_1 above as a polynomial in $\eta(t)$ of degree 6 plus a small and controllable error. Since this proof is straightforward but cumbersome, and the claim is clear from Figure 7, we do not provide the explicit calculations. Hence, the integrand of (4.13) is $O(e^{-c\tau})$ for some $c > 0$, and we obtain the result. \square

4.4 Completion of the proof of Theorem 1.5

The only thing left to check is that it is possible to deform the contour Γ in (4.12) to Γ' . We thus need to check that ω_τ is analytic on \mathcal{R} . Since f_1, f_2, E, U_0 are all analytic on \mathcal{R} , the only possible singularities of ω_τ come from the zeros of U_0 . The only zero of U_0 is the branch point $z = 1$, which is a simple zero (see Lemma 3.1). Since E has a zero of order 3 by Lemma 3.4, and $dz = 2wdw$ has a simple zero using the local coordinate $z - 1 = w^2$, we find that ω_τ has a removable singularity at $z = 1$. (Putting aside the terminology of Riemann surfaces, this simply means that the function $\frac{E(z)e^{\tau f_1(z) + \tau^{1/2} \hat{x} f_2(z)}}{8\pi i z u_0(z)^4}$ has an integrable singularity at the branch point $z = 1$). Therefore, ω_τ is analytic on \mathcal{R} , and we can deform Γ to Γ' in the integral in

(4.12). The proof is then completed from Lemmas 4.9, 4.10 and 4.11.

5 Small time limit

We prove Theorem 1.6.

5.1 Small τ limit

We set $\gamma = 0$ as in Theorem 1.6. Recall $\Phi(\xi) = -\frac{1}{3}\tau\xi^3 + x\xi - Q(\xi)$ from (2.5). Scaling s, t by $\tau^{1/3}$ in Lemma 1.1, the distribution function (2.7) can be written as

$$F(\tau^{1/3}x; \tau, 0) = \oint e^{\tau^{1/3}xA_1(z) + \tau A_2(z) + 2B(z)} \det(\mathbb{I} - \mathbb{A}_{x,\tau}^2) \frac{dz}{2\pi iz},$$

where $\mathbb{A}_{x,\tau} : L^2(0, \infty) \rightarrow L^2(0, \infty)$ is the operator with the kernel

$$\mathbf{A}_{x,\tau}(s, t) = \tau^{1/3} \mathbf{T}_0(\tau^{1/3}s, \tau^{1/3}t)|_{x \mapsto \tau^{1/3}x} = \tau^{1/3} \sum_{\xi \in \mathcal{S}_-} \frac{1}{-\xi} e^{-\frac{1}{3}\tau\xi^3 + \tau^{1/3}\xi(s+t+x) - Q(\xi)} \quad (5.1)$$

for $s, t > 0$. Observe that $\mathbb{A}_{x,\tau}$ depends on z since the set \mathcal{S}_- depends on z .

We compare $F(\tau^{1/3}x; \tau, 0)$ with the GUE Tracy-Widom distribution, $F_{\text{GUE}}(x) = \det(\mathbb{I} - \mathbb{A}_x^2)$, where $\mathbb{A}_x : L^2(0, \infty) \rightarrow L^2(0, \infty)$ has kernel

$$\mathbf{A}_x(s, t) = \text{Ai}(s + x + t), \quad s, t > 0.$$

Recall the integral representation of the Airy function

$$\text{Ai}(z) = \frac{1}{2\pi i} \int_{\Lambda} e^{-\frac{u^3}{3} + zu} du, \quad z \in \mathbb{C}, \quad (5.2)$$

where Λ is an unbounded contour from $\infty e^{-\theta i}$ to $\infty e^{\theta i}$ for any $\theta \in (\pi/2, 5\pi/6)$.

We will show that if we scale z appropriately with τ then in the limit $\tau \rightarrow 0$ the term $Q(\xi)$ vanishes and the kernel $\mathbf{A}_{x,\tau}(s, t)$ converges to the Airy kernel along with its Fredholm determinant.

Lemma 5.1. *For every $\epsilon \in (0, 1)$, there is a constant $c > 0$ such that*

$$Q(\tau^{-1/3}\zeta) = \mathcal{O}(e^{-c\tau^{-2/3}}) \quad (5.3)$$

as $\tau \rightarrow 0$ uniformly for ζ satisfying $\text{Re}(\zeta^2) \geq 1 - \epsilon$ and $\text{Re} \zeta < 0$.

Proof. From (2.4), after a change of variables,

$$Q(\tau^{-1/3}\zeta) = - \int_{-i\infty}^{i\infty} \frac{\log(1 - e^{-\zeta^2/(2\tau^{2/3})} e^{u^2/2})}{u - \tau^{-1/3}\zeta} \frac{du}{\pi i} = - \frac{1}{\pi i} \int_{-i\infty}^{i\infty} \log \left(1 - e^{-\frac{\zeta^2 - u^2}{2\tau^{2/3}}} \right) \frac{du}{u - \zeta}.$$

Uniformly for $u \in i\mathbb{R}$ and $\text{Re}(\zeta^2) \geq 1 - \epsilon$, $|e^{-\frac{\zeta^2 - u^2}{2\tau^{2/3}}}| \leq |e^{-\frac{\zeta^2}{2\tau^{2/3}}}| = e^{-\frac{\text{Re}(\zeta^2)}{2\tau^{2/3}}} \leq e^{-\frac{1-\epsilon}{2\tau^{2/3}}} \rightarrow 0$ as $\tau \rightarrow 0$, and hence,

$$\left| \log \left(1 - e^{-\frac{\zeta^2 - u^2}{2\tau^{2/3}}} \right) \right| \leq 2 |e^{-\frac{\zeta^2 - u^2}{2\tau^{2/3}}}| = 2e^{-\frac{\text{Re}(\zeta^2 - u^2)}{2\tau^{2/3}}} \leq 2e^{-\frac{1-\epsilon + |u|^2}{2\tau^{2/3}}}.$$

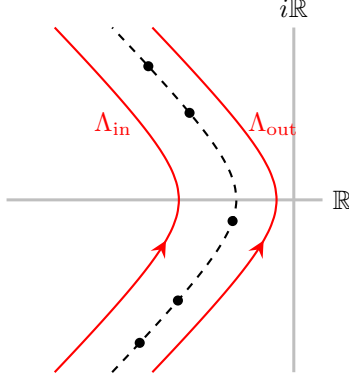


Figure 8: The dots are the points in \mathcal{S}_- and sit in the dashed parabola determined by $|e^{-w^2/2}| = |z|$. The contours Λ_{in} and Λ_{out} are represented in solid lines.

Also note that $|u - \zeta| \geq |\operatorname{Re} u - \operatorname{Re} \zeta| = \sqrt{(\operatorname{Re} \zeta)^2} \geq \sqrt{\operatorname{Re} \zeta^2} \geq \sqrt{1 - \epsilon}$ uniformly for $u \in i\mathbb{R}$ and ζ as assumed in the lemma. These two estimates complete the proof. \square

Lemma 5.2. *For every $x_0 \in \mathbb{R}$, there exist constants $C, c, \tau_0 > 0$ such that*

$$|\mathbf{A}_{x,\tau}(s, t) - \mathbf{A}_x(s, t)| \leq C e^{-c\tau^{-2/3}} e^{-c(s+t)-c(x-x_0)}$$

for every $x \geq x_0$, $s, t > 0$, $\tau \in (0, \tau_0)$, and every z satisfying

$$|z| = e^{-\frac{1}{2\tau^{2/3}}}. \quad (5.4)$$

Proof. Define the function

$$f(w) = \frac{z}{z - e^{-w^2/2}} e^{-\frac{1}{3}\tau w^3 + \tau^{1/3}w(x+s+t) - Q(w)}$$

for $\operatorname{Re} w < 0$ in the sector $\frac{3\pi}{4} < \arg w < \frac{5\pi}{4}$. Recall that this sector contains the set \mathcal{S}_- (see (1.5)) and that the function Q is analytic in this sector. The fraction in the formula for f has simple poles precisely at the set \mathcal{S}_- and

$$\operatorname{Res}_{\xi} f = \frac{1}{\xi} e^{-\frac{1}{3}\tau \xi^3 + \tau^{1/3}\xi(x+s+t) - Q(\xi)} \quad \text{for } \xi \in \mathcal{S}_-.$$

Therefore, (see (5.1)) we can write

$$\mathbf{A}_{x,\tau}(s, t) = -\tau^{1/3} \sum_{\xi \in \mathcal{S}_-} \operatorname{Res}_{\xi} f = \frac{\tau^{1/3}}{2\pi i} \int_{\Lambda_{\text{in}}} f(w) dw - \frac{\tau^{1/3}}{2\pi i} \int_{\Lambda_{\text{out}}} f(w) dw, \quad (5.5)$$

where Λ_{in} and Λ_{out} are two unbounded curves in \mathbb{C} , both from $\infty e^{-3\pi i/4}$ to $\infty e^{3\pi i/4}$, lying in the sector $\frac{3\pi}{4} < \arg w < \frac{5\pi}{4}$ such that \mathcal{S}_- is contained in the strip between Λ_{in} and Λ_{out} . We also choose Λ_{in} to be to the left of Λ_{out} ; see Figure 8.

Let z satisfy (5.4). Changing the variables $w = \tau^{-1/3}\zeta$ we get the identity

$$\tau^{1/3} \int_{\Lambda_{\text{in, out}}} f(w) dw = \int_{\hat{\Lambda}_{\text{in, out}}} \frac{z}{z - e^{-\zeta^2/(2\tau^{2/3})}} e^{-\frac{1}{3}\zeta^3 + \zeta(x+s+t) - Q(\tau^{-1/3}\zeta)} d\zeta, \quad (5.6)$$

where the new contours $\widehat{\Lambda}_{\text{in}}$ and $\widehat{\Lambda}_{\text{out}}$ are as follows. Since $|z| = e^{-\frac{1}{2\tau^{2/3}}}$,

$$\tau^{1/3}\mathcal{S}_- \subset \{u \in \mathbb{C} \mid \operatorname{Re} u^2 = 1, \operatorname{Re} u < 0\}.$$

Thus, for every $\varepsilon \in (0, 1)$, the scaled set $\tau^{1/3}\mathcal{S}_-$ lies between the contours

$$\widehat{\Lambda}_{\text{in}} := \{\zeta \in \mathbb{C} \mid \operatorname{Re} \zeta^2 = 1 + \varepsilon, \operatorname{Re} \zeta < 0\} \quad \text{and} \quad \widehat{\Lambda}_{\text{out}} := \{\zeta \in \mathbb{C} \mid \operatorname{Re} \zeta^2 = 1 - \varepsilon, \operatorname{Re} \zeta < 0\}.$$

These contours lie in the sector $\frac{3\pi}{4} < \arg \zeta < \frac{5\pi}{4}$. We choose the contours with any fixed $\varepsilon \in (0, 1)$.

Note that since $|z| = e^{-\frac{1}{2\tau^{2/3}}}$, we have $|ze^{\frac{\zeta^2}{2\tau^{2/3}}}| = e^{\frac{\operatorname{Re} \zeta^2 - 1}{2\tau^{2/3}}} = e^{\frac{\varepsilon}{2\tau^{2/3}}}$ for $\zeta \in \widehat{\Lambda}_{\text{in}}$ and $|ze^{\frac{\zeta^2}{2\tau^{2/3}}}| = e^{-\frac{\varepsilon}{2\tau^{2/3}}}$ for $\zeta \in \widehat{\Lambda}_{\text{out}}$. Thus,

$$\frac{z}{z - e^{-\zeta^2/(2\tau^{2/3})}} = \left(1 - \frac{1}{ze^{\zeta^2/(2\tau^{2/3})}}\right)^{-1} = 1 + \mathcal{O}(e^{-\frac{\varepsilon}{2\tau^{2/3}}}), \quad \zeta \in \widehat{\Lambda}_{\text{in}}, \quad (5.7)$$

and

$$\frac{z}{z - e^{-\zeta^2/(2\tau^{2/3})}} = -ze^{\zeta^2/(2\tau^{2/3})} \left(1 - ze^{\zeta^2/(2\tau^{2/3})}\right)^{-1} = \mathcal{O}(e^{-\frac{\varepsilon}{2\tau^{2/3}}}), \quad \zeta \in \widehat{\Lambda}_{\text{out}} \quad (5.8)$$

as $\tau \rightarrow 0$, uniformly for ζ on the respective contour and z satisfying (5.4).

Using $\Lambda = \widehat{\Lambda}_{\text{in}}$ in the integral formula of the Airy function in (5.2) and (5.6), we obtain

$$\left| \frac{\tau^{1/3}}{2\pi i} \int_{\Lambda_{\text{in}}} f(w) dw - \operatorname{Ai}(s+x+t) \right| = \left| \frac{1}{2\pi i} \int_{\widehat{\Lambda}_{\text{in}}} \left(\frac{z}{z - e^{-\zeta^2/(2\tau^{2/3})}} e^{-Q(\tau^{-1/3}\zeta)} - 1 \right) e^{-\frac{1}{3}\zeta^3 + \zeta(x+s+t)} d\zeta \right|.$$

Since $s, t > 0$ and $x > x_0$, and $-\operatorname{Re} \zeta = \sqrt{(\operatorname{Re} \zeta)^2} \geq \sqrt{\operatorname{Re} \zeta^2} = \sqrt{1 + \varepsilon}$, we have

$$\operatorname{Re} \zeta (x+s+t) \leq -\sqrt{1+\varepsilon}(x-x_0+s+t) + x_0 \operatorname{Re} \zeta, \quad \zeta \in \widehat{\Lambda}_{\text{in}} \cup \widehat{\Lambda}_{\text{out}}.$$

The integral $\int_{\widehat{\Lambda}_{\text{in}}} e^{\frac{1}{3}\operatorname{Re}(\zeta^3) - x_0 \operatorname{Re} \zeta} |d\zeta|$ is convergent, and thus we find using (5.7) and (5.3) that there is a constant $c > 0$ which is independent of the parameters, and another constant $C > 0$ which depends only on x_0 , such that

$$\left| \frac{\tau^{1/3}}{2\pi i} \int_{\Lambda_{\text{in}}} f(w) dw - \operatorname{Ai}(s+x+t) \right| \leq C e^{-c\tau^{-2/3}} e^{-\sqrt{1+\varepsilon}(x-x_0+s+t)}$$

as $\tau \rightarrow 0$. Similarly, we obtain using (5.8)

$$\left| \frac{\tau^{1/3}}{2\pi i} \int_{\Lambda_{\text{out}}} f(w) dw \right| \leq C e^{-c\tau^{-2/3}} e^{-\sqrt{1-\varepsilon}(x-x_0+s+t)}.$$

The proof is now complete once we combine these estimates with (5.5)–(5.6). □

Corollary 5.3. *For every $x_0 \in \mathbb{R}$, there exist constants $C, c, \tau_0 > 0$ such that*

$$|\det(\mathbb{I} - \mathbb{A}_{x,\tau}^2) - \det(\mathbb{I} - \mathbb{A}_x^2)| \leq C e^{-c\tau^{-2/3}} e^{-c(x-x_0)}$$

for all $x \geq x_0$, $\tau \in (0, \tau_0)$, and z satisfying $|z| = e^{-\frac{1}{2\tau^{2/3}}}$.

Proof. Denote by $\|\cdot\|_1$ the trace norm and by $\|\cdot\|_2$ the Hilbert-Schmidt norm. Using

$$|\det(\mathbb{I} - \mathbb{K}_1) - \det(\mathbb{I} - \mathbb{K}_2)| \leq \|\mathbb{K}_1 - \mathbb{K}_2\|_1 \exp(\|\mathbb{K}_1\|_1 + \|\mathbb{K}_2\|_1 + 1)$$

and $\|\mathbb{K}_1\mathbb{K}_2\|_1 \leq \|\mathbb{K}_1\|_2\|\mathbb{K}_2\|_2$, we have

$$|\det(\mathbb{I} - \mathbb{A}_{x,\tau}^2) - \det(\mathbb{I} - \mathbb{A}_x^2)| \leq \|\mathbb{A}_{x,\tau} - \mathbb{A}_x\|_2 (\|\mathbb{A}_{x,\tau}\|_2 + \|\mathbb{A}_x\|_2) \exp(\|\mathbb{A}_{x,\tau}\|_2^2 + \|\mathbb{A}_x\|_2^2 + 1)$$

Lemma 5.2 implies that

$$\|\mathbb{A}_{x,\tau} - \mathbb{A}_x\|_2^2 \leq C^2 e^{-2c\tau^{-2/3}} e^{-2c(x-x_0)} \int_0^\infty \int_0^\infty e^{-2c(s+t)} ds dt = \mathcal{O}(e^{-2c\tau^{-2/3}}).$$

On the other hand, $\|\mathbb{A}_x\|_2$ is uniformly bounded for $x \geq x_0$. Therefore, we obtain the result. \square

5.2 Completion of the proof of Theorem 1.6

The functions A_1, A_2 and B in (2.2) are analytic on the unit disk and $A_1(0) = A_2(0) = B(0) = 0$. Thus, by Cauchy's Theorem,

$$F(\tau^{1/3}x; \tau, \gamma = 0) - F_{\text{GUE}}(x) = \oint e^{\tau^{1/3}xA_1(z) + \tau A_2(z) + 2B(z)} (\det(\mathbb{I} - \mathbb{A}_{x,\tau}^2) - \det(\mathbb{I} - \mathbb{A}_x^2)) \frac{dz}{2\pi iz}.$$

Taking the contour as the circle (5.4), the proof now follows from Corollary 5.3

6 Right tail estimate

In this section we prove Theorem 1.7. It is convenient to reformulate the right tail of $F_{\text{GUE}}(x)$ and $(F_{\text{GUE}}(x))^2$ in terms of an integral involving the Airy function. The Airy function $\text{Ai}(x)$ has the integral representation (5.2) and

$$\text{Ai}(x) = \frac{1}{2\sqrt{\pi}x^{1/4}} e^{-\frac{2}{3}x^{3/2}} \left(1 + \mathcal{O}(x^{-3/2})\right), \quad x \rightarrow \infty. \quad (6.1)$$

We define

$$\mathcal{B}(x; \alpha) := \int_x^\infty (y-x) e^{\alpha y} \text{Ai}(y)^2 dy, \quad \alpha \in \mathbb{R}, \quad (6.2)$$

and denote in particular

$$\mathcal{B}(x) = \mathcal{B}(x; 0).$$

Lemma 6.1. *We have*

$$\mathcal{B}(x; \alpha) = \frac{1}{16\pi x^{3/2}} e^{\alpha x - \frac{4}{3}x^{3/2}} \left(1 + \frac{\alpha}{x^{1/2}} + \frac{3\alpha^2}{4x} + \mathcal{O}(x^{-3/2})\right) \quad (6.3)$$

as $x \rightarrow \infty$. Moreover, for any positive constants a and β ,

$$\int_x^{x+ax^\beta} (y-x) e^{\alpha y} \text{Ai}(y)^2 dy = \mathcal{B}(x; \alpha) (1 + \mathcal{O}(e^{-ax^{\beta+\frac{1}{2}}})) , \quad x \rightarrow \infty. \quad (6.4)$$

Proof. Inserting (6.1) in (6.2), and writing $y = x + s$, we have

$$\begin{aligned} \mathcal{B}(x; \alpha) &= \frac{e^{\alpha x}}{4\pi} \int_0^\infty \frac{s}{(s+x)^{1/2}} e^{\alpha s} e^{-\frac{4}{3}(x+s)^{3/2}} ds \left(1 + \mathcal{O}(x^{-3/2})\right) \\ &= \frac{e^{\alpha x - \frac{4}{3}x^{3/2}}}{4\pi\sqrt{x}} \int_0^1 s e^{\alpha s} \frac{e^{-\frac{s^2}{2\sqrt{x}}}}{(1+s/x)^{1/2}} e^{-2\sqrt{x}s} ds \left(1 + \mathcal{O}(x^{-3/2})\right) \end{aligned}$$

where for the second equality we changed the integral domain from $(0, \infty)$ to $(0, 1)$ since the integral over $(1, \infty)$ only gives exponentially smaller error, and expanded $(x + s)^{3/2}$. Expanding the fraction in the integrand in power series and applying Watson's lemma we obtain (6.3) after routine calculations. Using a similar calculation,

$$\int_{x+ax^\beta}^{\infty} (y-x)e^{\alpha y} \text{Ai}(y)^2 dy = \frac{e^{\alpha x - \frac{4}{3}x^{3/2}}}{4\pi\sqrt{x}} \mathcal{O}(e^{-cx^{\beta+\frac{1}{2}}})$$

for any positive constant c with $c < 2a$. Combining with (6.3), we obtain (6.4). \square

Noting that $\text{Tr}(\mathbb{A}_x^2) = \mathcal{B}(x)$, the right tail of the GUE Tracy-Widom distribution satisfies

$$1 - F_{\text{GUE}}(x) = \mathcal{B}(x) \left(1 + \mathcal{O}(e^{-\frac{4}{3}(1-\epsilon)x^{3/2}}) \right) \quad (6.5)$$

as $x \rightarrow \infty$, for any $\epsilon > 0$ fixed. This implies that

$$1 - (F_{\text{GUE}}(x))^2 = 2\mathcal{B}(x) \left(1 + \mathcal{O}(e^{-\frac{4}{3}(1-\epsilon)x^{3/2}}) \right). \quad (6.6)$$

Now we turn to the function $F(x; \tau, \gamma)$. Recall Lemma 1.1,

$$F(x; \tau, \gamma) = \oint e^{xA_1(z) + \tau A_2(z) + 2B(z)} \det(\mathbb{I} - \mathbb{T}_{-\gamma} \mathbb{T}_\gamma) \frac{dz}{2\pi iz} \quad (6.7)$$

where the contour is any circle $|z| = R$ with $0 < R < 1$. We take $x \rightarrow +\infty$ with the choice of contour

$$|z| = e^{-\frac{x}{2\tau}}.$$

We prove the following result.

Proposition 6.2. *For every $\gamma \in [-1/2, 1/2]$, there exists a constant $0 < \epsilon < 1$ such that the Hilbert-Schmidt norm of \mathbb{T}_γ satisfies*

$$\|\mathbb{T}_\gamma\|_2 \leq e^{-\frac{2}{3}(1-\epsilon)x^{3/2}\tau^{-1/2}} \quad \text{as } x \rightarrow \infty,$$

uniformly for $|z| = e^{-\frac{x}{2\tau}}$.

We also need to evaluate the leading term asymptotics for $\text{Tr}(\mathbb{T}_{-\gamma} \mathbb{T}_\gamma)$. This will be done with a careful control of the Laurent expansion of the kernel for the product $\mathbb{T}_{-\gamma} \mathbb{T}_\gamma$ at $z = 0$. As a result we will see that for $|\gamma| < 1$ the Laurent coefficient for z^0 is the leading one, whereas for $|\gamma| = 1/2$ the coefficients for $z^{\pm 1}$ and z^0 all contribute to the same order as $x \rightarrow \infty$. For the precise statement, set

$$b(\tau, \gamma, x) := \mathcal{B}\left(\frac{x}{\tau^{1/3}} + \frac{\gamma^2}{4\tau^{4/3}}\right), \quad b_{\pm}(\tau, \gamma, x) := \mathcal{B}\left(\frac{x}{\tau^{1/3}} + \frac{\gamma^2}{4\tau^{4/3}}; \pm \frac{1}{2\tau^{2/3}}\right).$$

Proposition 6.3. *For each $\gamma \in [-1/2, 1/2]$, there is $c > 0$ such that the following result holds as $x \rightarrow \infty$ uniformly for $|z| = e^{-\frac{x}{2\tau}}$: if $|\gamma| < 1/2$,*

$$\text{Tr}(\mathbb{T}_{-\gamma} \mathbb{T}_\gamma) = b(\tau, \gamma, x) \left(1 + \mathcal{O}(e^{-cx^{1/2}}) \right),$$

and if $\gamma = \pm 1/2$,

$$\text{Tr}(\mathbb{T}_{1/2} \mathbb{T}_{-1/2}) = \left(2b(\tau, 1/2, x) + ze^{-\frac{1}{96\tau^2}} b_+(\tau, 1/2, x) + z^{-1} e^{\frac{1}{96\tau^2}} b_-(\tau, 1/2, x) \right) \left(1 + \mathcal{O}(e^{-cx^{1/2}}) \right).$$

Lemma 6.1 implies that $b_{\pm}(\tau, 1/2, x) = e^{\pm(\frac{x}{2\tau} + \frac{1}{32\tau^2})} b(\tau, 1/2, x)(1 + \mathcal{O}(x^{-1/2}))$. Hence, for $|z| = e^{-\frac{x}{2\tau}}$,

$$zb_+(\tau, 1/2, x) = \mathcal{O}(b(\tau, 1/2, x)), \quad z^{-1}b_-(\tau, 1/2, x) = \mathcal{O}(b(\tau, 1/2, x)), \quad (6.8)$$

so the three terms in $\text{Tr}(\mathbb{T}_{1/2}\mathbb{T}_{-1/2})$ have the same order.

We prove the two propositions in the following subsections. Assuming them, we now obtain Theorem 1.7.

Proof of Theorem 1.7. The functions A_1, A_2 and B are analytic (see (2.2)), and using (3.1) we see that

$$E(z) := e^{xA_1(z) + \tau A_2(z) + 2B(z)} = 1 - \frac{(x + \tau)z}{\sqrt{2\pi}} + \mathcal{O}(z^2) \quad \text{as } z \rightarrow 0.$$

Hence,

$$\oint E(z) \frac{dz}{2\pi iz} = 1, \quad \oint zE(z) \frac{dz}{2\pi iz} = 0, \quad \oint z^{-1}E(z) \frac{dz}{2\pi iz} = -\frac{x + \tau}{\sqrt{2\pi}}. \quad (6.9)$$

We also have $E(z) = \mathcal{O}(1)$ for $|z| = e^{-\frac{x}{2\tau}}$ as $x \rightarrow \infty$. On the other hand, using $\|\mathbb{T}_{-\gamma}\mathbb{T}_{\gamma}\|_1 \leq \|\mathbb{T}_{-\gamma}\|_2 \|\mathbb{T}_{\gamma}\|_2$ and Proposition 6.2,

$$\det(\mathbb{I} - \mathbb{T}_{-\gamma}\mathbb{T}_{\gamma}) - 1 + \text{Tr}(\mathbb{T}_{-\gamma}\mathbb{T}_{\gamma}) = \mathcal{O}(\|\mathbb{T}_{-\gamma}\mathbb{T}_{\gamma}\|_1^2) = \mathcal{O}(e^{-\frac{8(1-\epsilon)x^{3/2}}{3\tau^{1/2}}})$$

as $x \rightarrow \infty$ uniformly for $|z| = e^{-\frac{x}{2\tau}}$. Hence,

$$1 - F(x; \tau, \gamma) = \oint_{|z|=e^{-\frac{x}{2\tau}}} E(z) \text{Tr}(\mathbb{T}_{-\gamma}\mathbb{T}_{\gamma}) \frac{dz}{2\pi iz} + \mathcal{O}(e^{-\frac{8(1-\epsilon)x^{3/2}}{3\tau^{1/2}}}). \quad (6.10)$$

Thus, for $|\gamma| < 1/2$, Proposition 6.3 and (6.5) imply the theorem. For $\gamma = \pm 1/2$, Proposition 6.3, the equation (6.9), and (6.8) imply that the integral in (6.10) is

$$\left(2b(\tau, x, 1/2) - \frac{(x + \tau)e^{\frac{1}{96\tau^2}}}{\sqrt{2\pi}} b_-(\tau, x, 1/2) \right) \left(1 + \mathcal{O}(e^{-cx^{1/2}}) \right).$$

Since $b_-(\tau, 1/2, x) = \mathcal{O}(e^{-\frac{x}{2\tau}} b(\tau, 1/2, x))$, we obtain the result from (6.6). \square

In Section 6.1, we first analyze the kernel of \mathbb{T}_{γ} . We then prove Propositions 6.2 and 6.3 in Sections 6.2 and 6.3, respectively.

6.1 Analysis of the kernel \mathbb{T}_{γ}

The kernel of \mathbb{T}_{γ} is given by Lemma 1.1 and we recall it here,

$$\mathbf{T}_{\gamma}(s, t) = \mathcal{T}_{\gamma}(x + s + t), \quad \mathcal{T}_{\gamma}(y) = \mathcal{T}_{\gamma}(y; z, \tau) = \sum_{\xi \in S_-} \frac{e^{-\frac{\tau}{3}\xi^3 + \frac{\tau}{2}\xi^2 + y\xi - Q(\xi)}}{-\xi} \quad (6.11)$$

for $s, t > 0$. The function Q is defined in (2.3). In this subsection we find the asymptotic behavior of $\mathcal{T}_{\gamma}(y)$ as $y \rightarrow \infty$.

Fix $\tau > 0$ and define the Airy-like function

$$A(y; \mu) = \int_{\Lambda} e^{-\frac{\tau}{3}\xi^3 + \frac{\mu}{2}\xi^2 + y\xi - Q(\xi)} \frac{d\xi}{2\pi i} \quad (6.12)$$

where Λ is any simple unbounded contour from $\infty e^{5\pi i/4}$ to $\infty e^{3\pi i/4}$ contained in the sector $3\pi/4 < \arg \xi < 5\pi/4$, the latter condition being imposed so that Q remains analytic along Λ . Without the term Q , the above function is a scaled Airy function,

$$\int_{\Lambda} e^{-\frac{\tau}{3}\xi^3 + \frac{\mu}{2}\xi^2 + y\xi} \frac{d\xi}{2\pi i} = \frac{e^{\frac{\mu^3}{12\tau^2} + \frac{\mu y}{2\tau}}}{\tau^{1/3}} \text{Ai}\left(\frac{y}{\tau^{1/3}} + \frac{\mu^2}{4\tau^{4/3}}\right). \quad (6.13)$$

The function $\mathcal{T}_{\gamma}(y)$ in (6.11) looks like a discretization of $A(y; \gamma)$. The factor $\frac{1}{-\xi}$ is close to the spacing between the points in the discrete set \mathcal{S}_- , which is not uniformly spaced. A precise comparison between $\mathcal{T}_{\gamma}(y)$ and $A(y; \gamma)$ is in Proposition 6.9 below.

6.1.1 Asymptotics of $A(y; \mu)$

Lemma 6.4. *There are constants $c > 0$ and $y_0 > 0$ such that*

$$A(y; \mu) = \frac{e^{\frac{\mu^3}{12\tau^2} + \frac{\mu y}{2\tau}}}{\tau^{1/3}} \text{Ai}\left(\frac{y}{\tau^{1/3}} + \frac{\mu^2}{4\tau^{4/3}}\right) (1 + \mathcal{O}(e^{-cy}))$$

for all $y \geq y_0$ and $\mu \leq 2\sqrt{\tau y}$.

Proof. The proof follows from the standard steepest descent analysis, accounting for the factor Q in the exponent. Introduce the change of variables $\xi \mapsto w$ for (6.12) and (6.13),

$$\xi = sw + \frac{\mu}{2\tau}, \quad \text{with} \quad s := \frac{1}{\sqrt{\tau}} \left(y + \frac{\mu^2}{4\tau}\right)^{1/2} > 0.$$

In terms of the new variable,

$$\tau^{1/3} e^{-\frac{\mu^3}{12\tau^2} - \frac{\mu y}{2\tau}} A(y; \mu) - \text{Ai}(\tau^{2/3} s^2) = \frac{\tau^{1/3} s}{2\pi i} \int_{\hat{\Lambda}} e^{\tau s^3 (-\frac{1}{3}w^3 + w)} (e^{-Q(\xi(w))} - 1) dw.$$

To evaluate the integral as $s \rightarrow \infty$, we need to take a contour of steepest descent. The relevant critical point of the function $-w^3/3 + w$ is $w = -1$ and its path of steepest descent is a contour from $\infty e^{4\pi i/3}$ to $\infty e^{2\pi i/3}$, it is on the hyperbola $3x^2 - y^2 = 3$. However, $Q(\xi(w))$ is analytic in the sector $3\pi/4 < \arg \xi(w) < 5\pi/3$, which is approximately $3\pi/4 < \arg w < 5\pi/3$ when w becomes large, and consequently we cannot deform the contour to the path of steepest descent. Nonetheless, since the functions involved are explicit, we find that there is a contour in the sector that is “steep enough” and passes the critical point $z = -1$. We use the following concrete choice:

$$\hat{\Lambda} = \hat{\Lambda}_1 \cup \hat{\Lambda}_2 := \{-1 + bi \mid -0.2 \leq b \leq 0.2\} \cup \{a + bi \mid a^2 - b^2 = -1.45a - 0.49, a \leq -1\}.$$

This contour is locally the same as the path of steepest descent near the critical point $z = -1$. To verify that the method of steepest descent applies, it is enough to show that (1) $\text{Re}(-\frac{1}{3}w^3 + w)$ decreases as $a = \text{Re } w$ decreases along $\hat{\Lambda}_2$ and (2) the factor $e^{-Q(\xi(w))} - 1$ is exponentially small uniformly on the contour.

For (1), it is direct to check that for $w = a + bi \in \hat{\Lambda}_2$,

$$\text{Re}\left(-\frac{w^3}{3} + w\right) = \frac{2}{3}a^3 + 1.45a^2 + 1.49a$$

and its derivative is $2a^2 + 2.9a + 1.49 > 0$ for all a .

For (2), we use the integral representation (2.4) of Q . For $w = a + bi \in \widehat{\Lambda}_2$,

$$\operatorname{Re}(\xi(w)^2) = \frac{1}{\tau} \left(y + \frac{\mu^2}{4\tau} \right) (\lambda^2 + a(2\lambda - 1.45) - 0.49), \quad \lambda := \frac{\mu}{2\tau s} = \frac{\mu}{\sqrt{\mu^2 + 4\tau y}}.$$

Note that the above function depends only on $a = \operatorname{Re}(w)$, not on $b = \operatorname{Im}(w)$. The assumption $\mu \leq 2\sqrt{\tau y}$ implies that $\lambda \leq 1/\sqrt{2}$ which in turn gives $2\lambda - 1.45 < 0$. Hence, the above function takes its minimum when $a = -1$, and for this value of a we have $b = \pm 0.2$ since $a + ib$ is on $\widehat{\Lambda}_2$.

On the other hand, for $w = a + ib \in \widehat{\Lambda}_1$, $\operatorname{Re}(\xi(-1 + bi)^2)$ is equal to $-s^2 b^2$ plus a term which is independent of b . Hence, the minimum of $\operatorname{Re}(\xi(w)^2)$ over $w \in \widehat{\Lambda}_1$ is achieved at the end points $w = -1 \pm 0.2i$.

Thus, we found that $\operatorname{Re}(\xi(w)^2) \geq \operatorname{Re}(\xi(-1 \pm 0.2i)^2)$ for any $w \in \widehat{\Lambda}$. Now, noting that the function $f(v) := v^2 - 2v + 0.96$ is a decreasing function for $v \leq 1$, we have $f(\lambda) \geq f(\frac{1}{\sqrt{2}}) = 1.46 - \sqrt{2} > 0$, and therefore,

$$\operatorname{Re}(\xi(w)^2) \geq \operatorname{Re}(\xi(-1 \pm 0.2i)^2) = s^2 f(\lambda) \geq (1.46 - \sqrt{2}) s^2 \quad \text{for } w \in \widehat{\Lambda}.$$

Combined with $\operatorname{Re}(\xi(w)) < 0$ from the definition of $\xi(w)$, we find that $\xi(w)$ is in the sector $3\pi/4 < \arg(\xi(w)) < 5\pi/4$ for all $w \in \widehat{\Lambda}$, and also,

$$|e^{-\xi(w)^2/2}| = e^{-\operatorname{Re}(\xi(w)^2)/2} \leq e^{-c(y + \frac{\mu^2}{4\tau})}$$

with $c = (1.46 - \sqrt{2})/\tau$. With arguments similar to the ones in Lemma 5.1 we obtain

$$|Q(\xi(w))| = \mathcal{O}(e^{-c(y + \frac{\mu^2}{4\tau})}) \quad (6.14)$$

as $y \rightarrow \infty$, uniformly for $w \in \widehat{\Lambda}$. Hence $e^{-Q(\xi(w))} - 1 = \mathcal{O}(e^{-c(y + \frac{\mu^2}{4\tau})})$ uniformly for $w \in \widehat{\Lambda}$.

Thus, the method of steepest-descent applies. Since the integral without the term $(e^{-Q(\xi(w))} - 1)$ is the same as $\operatorname{Ai}(\tau^{2/3}s^2)$, the asymptotic formula is the same as that of the airy function multiplied by an error from $(e^{-Q(\xi(w))} - 1)$. From (6.14) we find that

$$\frac{\tau^{1/3}s}{2\pi i} \int_{\widehat{\Lambda}} e^{\tau s^3(-\frac{1}{3}w^3 + w)} (e^{-Q(\xi(w))} - 1) dw = \mathcal{O}(\operatorname{Ai}(\tau^{1/3}s^2) e^{-c(y + \frac{\mu^2}{4\tau})}).$$

This completes the proof. \square

By (6.1), the above lemma implies that

$$\operatorname{A}(y; \mu) = \frac{1}{2\sqrt{\pi}\tau^{1/4}} \left(y + \frac{\mu^2}{4\tau} \right)^{-1/4} e^{\frac{\mu^3}{12\tau^2} + \frac{\mu y}{2\tau} - \frac{2}{3\sqrt{\tau}} \left(y + \frac{\mu^2}{4\tau} \right)^{3/2}} \left(1 + \mathcal{O}(y^{-3/2}) \right) \quad (6.15)$$

for all $y \geq y_0$ and $\mu \leq 2\sqrt{\tau y}$.

6.1.2 Truncated series expansion of $\mathcal{T}_\gamma(y)$

Note that $\mathcal{T}_\gamma(y)$ depends on \mathcal{S}_- which, in turn, depends on the complex variable z that appears in the integral in (6.7). To compare $\mathcal{T}_\gamma(y)$ with $\operatorname{A}(y; \gamma)$, we start with the following formula.

Lemma 6.5. *There are positive constants x_0 and C such that*

$$\left| \mathcal{T}_\gamma(y) - \sum_{k=-K}^{\infty} z^{-k} \mathbf{A}(y; \gamma - k) \right| \leq C \left(\frac{|z|}{0.9} \right)^K$$

for all $y \geq x_0$, $0 < |z| \leq 0.8$, and $K \geq 1$.

The values 0.8 and 0.9 are chosen solely for convenience. The proof will show that the condition $|z| \leq 0.8$ can be changed to $|z| \leq r$ for any fixed $r \in (0, 1)$ with the bound changed to $\left(\frac{|z|}{R} \right)^K$ for any $R \in (r, 1)$.

Proof. Using the fact that \mathcal{S}_- is a set of zeros of the equation $e^{-\xi^2/2} - z = 0$, we can write (cf. the proof of Lemma 5.2)

$$\mathcal{T}_\gamma(y) = \left(\int_{\Lambda_{\text{out}}} - \int_{\Lambda_{\text{in}}} \right) \frac{z}{z - e^{-\xi^2/2}} e^{-\frac{\tau}{3}\xi^3 + \frac{\gamma}{2}\xi^2 + y\xi - Q(\xi)} \frac{d\xi}{2\pi i}$$

where we take $\Lambda_{\text{out}} := \{\xi : |e^{-\xi^2/2}| = 0.9|z|, \text{Re}(\xi) < 0\}$ and $\Lambda_{\text{in}} := \{\xi : |e^{-\xi^2/2}| = 0.9, \text{Re}(\xi) < 0\}$. Both contours lie in the sector $3\pi/4 < \arg \xi < 5\pi/4$ and they extend from $\infty e^{5\pi i/4}$ to $\infty e^{3\pi i/4}$. The points of \mathcal{S}_- lie between these two contours since $|e^{-\xi^2/2}| = |z|$ for all $\xi \in \mathcal{S}_-$ and $0.9|z| < |z| < 0.9$.

Since $|z^{-1}e^{-\xi^2/2}| = 0.9 < 1$ for $\xi \in \Lambda_{\text{out}}$, the geometric series implies that

$$\frac{1}{2\pi i} \int_{\Lambda_{\text{out}}} \frac{z}{z - e^{-\xi^2/2}} e^{-\frac{\tau}{3}\xi^3 + \frac{\gamma}{2}\xi^2 + y\xi - Q(\xi)} d\xi = \sum_{k=0}^{\infty} z^{-k} \int_{\Lambda_{\text{out}}} e^{-\frac{\tau}{3}\xi^3 + \frac{\gamma}{2}\xi^2 + y\xi - Q(\xi)} \frac{d\xi}{2\pi i}.$$

The integral is $\mathbf{A}(y; \gamma - k)$. On the other hand, for $\xi \in \Lambda_{\text{in}}$, we write

$$\frac{z}{z - e^{-\xi^2/2}} = - \sum_{k=1}^K z^k e^{k\xi^2/2} + \left(\frac{z}{e^{-\xi^2/2}} \right)^K \frac{z}{z - e^{-\xi^2/2}}.$$

Since $|e^{-\xi^2/2}| = 0.9$ for $\xi \in \Lambda_{\text{in}}$ and $|z| \leq 0.8$,

$$\left| \frac{1}{2\pi i} \int_{\Lambda_{\text{in}}} \left(\frac{z}{e^{-\xi^2/2}} \right)^K \frac{z}{z - e^{-\xi^2/2}} e^{-\frac{\tau}{3}\xi^3 + \frac{\gamma}{2}\xi^2 + y\xi - Q(\xi)} d\xi \right| \leq \frac{4}{\pi} \left(\frac{|z|}{0.9} \right)^K (0.9)^{-\gamma} \int_{\Lambda_{\text{in}}} e^{-\text{Re}(\frac{\tau}{3}\xi^3 + Q(\xi))} |d\xi|.$$

where we use the fact that $\text{Re}(\xi) < 0$ on Λ_{in} . The last integral does not depend on z , y , or K . Hence, we obtain the result. \square

We use the above result when $|z| = e^{-\frac{x}{2\tau}}$ with $x \rightarrow \infty$. We will also choose $K = K(y)$ depending on y in a specific way; see (6.21).

Corollary 6.6. *There are positive constants x_0 and C such that*

$$\left| \mathcal{T}_\gamma(y) - \sum_{k=-K}^{\infty} z^{-k} \mathbf{A}(y; \gamma - k) \right| \leq C e^{-\frac{9K(y)x}{19\tau}} \quad (6.16)$$

for all $0 < |z| \leq e^{-\frac{x}{2\tau}}$, $y \geq x \geq x_0$, and any choice of $K = K(y) \geq 1$.

6.1.3 $\mathcal{T}_\gamma(y)$ when y is close to x

We show that the main contribution to the sum in Corollary 6.6 comes from only one or two terms. From (6.15), for $|z| = e^{-\frac{x}{2\tau}}$,

$$|z^{-k} A(y; \mu - k)| = \frac{e^{\frac{\mu x}{2\tau} + \frac{2y^{3/2}}{3\sqrt{\tau}} f\left(\frac{\mu-k}{2\sqrt{\tau}y}; 1 - \frac{x}{y}\right)}}{\sqrt{2\pi}(4\tau y + (\mu - k)^2)^{1/4}} \left(1 + \mathcal{O}(y^{-3/2})\right) \quad (6.17)$$

as $y \rightarrow \infty$, uniformly for μ and k satisfying $\mu - k \leq 2\sqrt{\tau y}$, where

$$f(u; \lambda) := u^3 + \frac{3}{2}\lambda u - (1 + u^2)^{3/2}. \quad (6.18)$$

This function $f(u; \lambda)$ is strictly concave for every λ . It is strictly increasing when $\lambda \geq 1$, and when $\lambda < 1$ it has the unique maximum

$$\max_{u \in \mathbb{R}} f(u; \lambda) = f(u_c; \lambda) = -\frac{3}{2}(1 - \lambda)^{1/2} + \frac{1}{2}(1 - \lambda)^{3/2}, \quad u_c = \frac{\lambda}{2\sqrt{1 - \lambda}}. \quad (6.19)$$

We are interested in the case when $x \leq y \leq x + \mathcal{O}(x^{1/2})$ and $x \rightarrow \infty$. In this case, $\lambda = 1 - \frac{x}{y} \rightarrow 0$ as $x \rightarrow \infty$, and hence the maximizer u_c of $f(u; 1 - \frac{x}{y})$ is close to 0. We may expect that the main contribution to the sum in Corollary 6.6 comes from the term corresponding to k at which the function $f(\frac{\mu-k}{2\sqrt{\tau}y}; 1 - \frac{x}{y})$ becomes the largest. Since f is concave and k is a discrete index, the maximum may occur either at one value of k or two values of k . We will show that the main contribution to the sum comes from the term $k = 0$ when $|\gamma| < 1/2$, from the terms $k = 1, 0$ when $\gamma = 1/2$, and from the terms $k = 0, -1$ when $\gamma = -1/2$. For this purpose, we first analyze the function f . We use the next result when $s = \mathcal{O}(x) \rightarrow \infty$.

Lemma 6.7. *The function f defined in (6.18) satisfies the following inequalities.*

(a) *For all $\alpha < 1/2$, $s > 0$, and $\lambda \geq 0$,*

$$f\left(\frac{\alpha}{s}; \lambda\right) - f\left(\frac{\alpha-1}{s}; \lambda\right) \geq \frac{3(1-2\alpha)}{2s^2}.$$

(b) *For all $\alpha > -1/2$, $s \geq \frac{3(1+2\alpha)^2+1}{5(1+2\alpha)}$, and $0 \leq \lambda \leq \frac{1+2\alpha}{12s}$,*

$$f\left(\frac{\alpha}{s}; \lambda\right) - f\left(\frac{\alpha+1}{s}; \lambda\right) \geq \frac{1+2\alpha}{8s^2}.$$

Proof. (a) Since u^3 and $\frac{3}{2}\lambda u$ are increasing functions of u , we have

$$f\left(\frac{\alpha}{s}; \lambda\right) - f\left(\frac{\alpha-1}{s}; \lambda\right) \geq \left(1 + \frac{(\alpha-1)^2}{s^2}\right)^{3/2} - \left(1 + \frac{\alpha^2}{s^2}\right)^{3/2}.$$

Using the inequality $(1+a)^{3/2} \geq 1 + \frac{3a}{2}$, which holds for all $a \geq 0$, the above is equal to

$$\left(1 + \frac{\alpha^2}{s^2}\right)^{3/2} \left(\left(1 + \frac{1-2\alpha}{\alpha^2 + s^2}\right)^{3/2} - 1 \right) \geq \left(1 + \frac{\alpha^2}{s^2}\right) \frac{3(1-2\alpha)}{2(\alpha^2 + s^2)} = \frac{3(1-2\alpha)}{2s^2}.$$

(b) From the formula of f ,

$$f\left(\frac{\alpha}{s}; \lambda\right) - f\left(\frac{\alpha+1}{s}; \lambda\right) = \frac{\alpha^3 - (\alpha+1)^3}{s^3} - \frac{3\lambda}{2s} + \left(1 + \frac{\alpha^2}{s^2}\right)^{3/2} \left(\left(1 + \frac{1+2\alpha}{\alpha^2 + s^2}\right)^{3/2} - 1 \right).$$

From the assumption on s ,

$$\frac{\alpha^3 - (\alpha+1)^3}{s^3} = -\frac{3(1+2\alpha)^2 + 1}{4s^3} \geq -\frac{5(1+2\alpha)}{4s^2}.$$

Using the inequality $(1+a)^{3/2} \geq 1 + \frac{3a}{2}$ for $a \geq 0$ again,

$$f\left(\frac{\alpha}{s}; \lambda\right) - f\left(\frac{\alpha+1}{s}; \lambda\right) \geq -\frac{5(1+2\alpha)}{4s^2} - \frac{3\lambda}{2s} + \frac{3(1+2\alpha)}{2s^2}.$$

From the condition $\lambda \leq \frac{1+2\alpha}{12s}$ we conclude the proof. \square

Lemma 6.8. Fix $\tau > 0$.

(a) For each fixed $\mu < 1/2$, there exists $x_0 > 0$ such that

$$|z^{-k-1}A(y; \mu - k - 1)| \leq 2e^{-\frac{1+2\mu+2k}{4\tau^{3/2}}y^{1/2}} |z^{-k}A(y; \mu - k)|$$

for all $|z| = e^{-\frac{x}{2\tau}}$, $y \geq x \geq x_0$, and $k \geq 0$.

(b) For each fixed $\mu > -1/2$, there exists $x_0 > 0$ such that

$$|z^{k+1}A(y; \mu + k + 1)| \leq 2e^{-\frac{1+2\mu+2k}{48\tau^{3/2}}y^{1/2}} |z^kA(y; \mu + k)|$$

for all $|z| = e^{-\frac{x}{2\tau}}$ and $x \geq x_0$, and for all y and k satisfying $x \leq y \leq x + \frac{1+2\mu+2k}{24\sqrt{\tau}}\sqrt{x}$ and $0 \leq k \leq K(y) := \lfloor \frac{19}{12}\sqrt{\tau y} \rfloor$.

Proof. (a) The formula (6.17) applies since $\mu - k \leq \mu \leq 2\sqrt{\tau x} \leq 2\sqrt{\tau y}$ holds if x is large enough. Note that $(\mu - k)^2 \leq (\mu - k - 1)^2$ for all $k \geq 0$ since $\mu < 1/2$. Also noting that the error term in (6.17) is uniform in y and k , we find that for all large enough $y \geq x$,

$$\frac{|z^{-k-1}A(y; \mu - k - 1)|}{|z^{-k}A(y; \mu - k)|} \leq 2 \exp \left\{ -\frac{2y^{3/2}}{3\tau^{1/2}} \left(f\left(\frac{\mu - k}{2\sqrt{\tau y}}; 1 - \frac{x}{y}\right) - f\left(\frac{\mu - k - 1}{2\sqrt{\tau y}}; 1 - \frac{x}{y}\right) \right) \right\}.$$

Applying Lemma 6.7 (a) with $\alpha = \mu - k$, $s = 2\sqrt{\tau y}$, and $\lambda = 1 - \frac{x}{y}$, we obtain the result.

(b) Since $\mu + k + 1 \leq \mu + 1 + K(y) \leq 2\sqrt{\tau y}$ if $y \geq x$ and x is large enough, the formula (6.17) applies. By the same argument as the part (a), the result follows from Lemma 6.7 (b) with $\alpha = \mu + k$, $s = 2\sqrt{\tau y}$, and $\lambda = 1 - \frac{x}{y}$ if these values satisfy the conditions of the lemma. Clearly, $\alpha > -1/2$ since $\mu > -1/2$ and $k \geq 0$. The condition $0 \leq \lambda \leq \frac{1+2\alpha}{12s}$ is satisfied since

$$0 \leq 1 - \frac{x}{y} = \frac{y - x}{y} \leq \frac{(1 + 2\mu + 2k)x^{1/2}}{24\sqrt{\tau y}} \leq \frac{1 + 2\mu + 2k}{24\sqrt{\tau y}} = \frac{1 + 2\alpha}{12s}$$

Finally, to verify the condition on s we observe that for x large enough so that $\sqrt{\tau x} \geq 6(1 + 2\mu) + \frac{2}{1+2\mu}$,

$$\frac{3}{5}(1 + 2\alpha) + \frac{1}{5(1 + 2\alpha)} \leq \frac{3}{5}(1 + 2\mu + 2K) + \frac{1}{5(1 + 2\mu)} = \frac{1}{10} \left(6(1 + 2\mu) + \frac{2}{1 + 2\mu} \right) + \frac{6}{5}K \leq s$$

since $K \leq \frac{19}{12}\sqrt{\tau y}$ and $x \leq y$. Hence, Lemma 6.7 (b) applies and we obtain the result. \square

The above estimates imply the following result.

Proposition 6.9 ($\mathcal{T}_\gamma(y)$ when y is close to x). *Fix $\tau > 0$. For any fixed $\gamma \in (-1/2, 1/2)$, there exists $c > 0$ such that*

$$\mathcal{T}_\gamma(y) = A(y; \gamma) \left(1 + \mathcal{O}(e^{-cy^{1/2}})\right) \quad (6.20)$$

as $x \rightarrow \infty$ uniformly for $y \in \left[x, x + \frac{(1+2\gamma)\sqrt{x}}{24\sqrt{\tau}}\right]$ and $|z| = e^{-\frac{x}{2\tau}}$. For $\gamma = \pm 1/2$, there is $c > 0$ such that

$$\mathcal{T}_{\pm 1/2}(y) = (A(y; \pm 1/2) + z^{\mp 1}A(y; \mp 1/2)) \left(1 + \mathcal{O}(e^{-cy^{1/2}})\right) + \mathcal{O}(e^{-\frac{9K(y)x}{19\tau}})$$

as $x \rightarrow \infty$ uniformly for $y \in \left[x, x + \frac{\sqrt{x}}{12\sqrt{\tau}}\right]$ and $|z| = e^{-\frac{x}{2\tau}}$.

Proof. We use the truncated series formula for $\mathcal{T}_\gamma(y)$ given in Corollary 6.6 with

$$K(y) = \left\lfloor \frac{19}{12}\sqrt{\tau y} \right\rfloor. \quad (6.21)$$

Consider first the case when $-1/2 < \gamma < 1/2$. For $k \geq 1$, using Lemma 6.8 (a) k times,

$$|z^{-k}A(y; \gamma - k)| \leq (2e^{-c_1 y^{1/2}})^k |A(y; \gamma)|, \quad c_1 := \frac{1 - 2\gamma}{4\tau^{3/2}}$$

for all $y \geq x$. For $-K \leq k \leq -1$, using Lemma 6.8 (b) $|k|$ times,

$$|z^{-k}A(y; \gamma - k)| \leq (2e^{-c_2 y^{1/2}})^{|k|} |A(y; \gamma)|, \quad c_2 := \frac{1 + 2\gamma}{48\tau^{3/2}}$$

for $x \leq y \leq x + \frac{(1+2\gamma)\sqrt{x}}{24\sqrt{\tau}}$. With (6.16) in mind, this implies that $k = 0$ term gives the main contribution to the sum and with $c = \min\{c_1, c_2\}$,

$$\mathcal{T}_\gamma(y) = A(y; \gamma) \left(1 + \mathcal{O}(e^{-cy^{1/2}})\right) + \mathcal{O}(e^{-\frac{9K(y)x}{19\tau}})$$

as $x \rightarrow \infty$ uniformly for $y \in \left[x, x + \frac{(1+2\gamma)\sqrt{x}}{24\sqrt{\tau}}\right]$ and $|z| = e^{-\frac{x}{2\tau}}$. We compare the two error terms. From (6.21) and $y \geq x$, we see that $\mathcal{O}(e^{-\frac{9K(y)x}{19\tau}})$ is (super-)exponentially smaller than $A(y; \gamma)$ (see (6.15)). Hence, the additive error can be replaced by a multiplicative error and we obtain (6.20).

Consider now the case $\gamma = 1/2$. For $k \geq 2$, we use Lemma 6.8 (a) $k - 1$ times to obtain

$$|z^{-k}A(y; 1/2 - k)| \leq (2e^{-c_1 y^{1/2}})^{k-1} |z^{-1}A(y; -1/2)|, \quad c_1 := \frac{1 - 2\gamma + 2}{4\tau^{3/2}} = \frac{1}{2\tau^{3/2}},$$

for all $y \geq x$. For $-K \leq k \leq -1$, we use Lemma 6.8 (b) $|k|$ times to obtain

$$|z^{-k}A(y; 1/2 - k)| \leq (2e^{-c_2 y^{1/2}})^{|k|} |A(y; 1/2)|, \quad c_2 := \frac{1 + 2\gamma}{48\tau^{3/2}} = \frac{1}{24\tau^{3/2}},$$

for $x \leq y \leq x + \frac{\sqrt{x}}{12\sqrt{\tau}}$. Proceeding as before and replacing the additive error by the multiplicative error we obtain the result in this case.

Finally, consider the case when $\gamma = -1/2$. For $k \geq 1$, we use 6.8 (a) k times and estimate of $|z^{-k}A(y; 1/2 + k)|$ in terms of $|A(y; 1/2)|$ for all $y \geq x$. For $-K \leq k \leq -2$, we use 6.8 (b) $|k| - 1$ times and find an estimate

of $|z^{-k}A(y; 1/2 + k)|$ in terms of $|zA(y; -1/2)|$, which are valid for $x \leq y \leq x + \frac{1+2\gamma+2}{24\sqrt{\tau}}\sqrt{x} = x + \frac{\sqrt{x}}{12\sqrt{\tau}}$. We now obtain the result in the same way as before. \square

6.1.4 Uniform estimate of $\mathcal{T}_\gamma(y)$ for all $y \geq x$

Although valid for all $y \geq x$, the next result will only be used for $y \geq x + \mathcal{O}(x^{1/2})$.

Proposition 6.10 (Uniform estimate of $\mathcal{T}_\gamma(y)$ for $y \geq x$). *Fix $-1/2 \leq \gamma \leq 1/2$ and $\tau > 0$. There exist positive constants C and x_0 such that*

$$|\mathcal{T}_\gamma(y)| \leq C \max \left\{ y^{1/4} e^{\frac{\gamma x}{2\tau} - \frac{\sqrt{x}(3y-x)}{3\sqrt{\tau}}}, e^{-\frac{9K(y)x}{19\tau}} \right\}, \quad K(y) := \left\lfloor \frac{19}{12} \sqrt{\tau y} \right\rfloor,$$

for all $y \geq x \geq x_0$ and $|z| = e^{-\frac{x}{2\tau}}$.

Proof. We use (6.16). Since Lemma 6.8 (a) holds for all $y \geq x$, using the same argument of the proof of Proposition 6.9 we find that for some $c_1 > 0$,

$$\sum_{k=2}^{\infty} |z^{-k}A(y; \gamma - k)| \leq |z^{-2}A(y; \gamma - 2)| \left(1 + \mathcal{O}(e^{-c_1 y^{1/2}}) \right) \leq 2|z^{-2}A(y; \gamma - 2)|.$$

for all $y \geq x$ as $x \rightarrow \infty$. Thus,

$$\sum_{k=-K(y)}^{\infty} |z^{-k}A(y; \gamma - k)| \leq 2(K(y) + 3) \max_{-K(y) \leq k \leq 2} |z^{-k}A(y; \gamma - k)|$$

for all $y \geq x$ as $x \rightarrow \infty$. Hence, from (6.17) we obtain that there are $C > 0$ and $x_0 > 0$ such that

$$\sum_{k=-K(y)}^{\infty} |z^{-k}A(y; \gamma - k)| \leq C y^{1/4} e^{\frac{\gamma x}{2\tau}} \exp \left\{ \frac{2y^{3/2}}{3\tau^{1/2}} \max_u f \left(u; 1 - \frac{x}{y} \right) \right\}$$

for all $y \geq x \geq x_0$. Inserting the formula (6.19) of the maximum, we obtain

$$\sum_{k=-K(y)}^{\infty} |z^{-k}A(y; \gamma + k)| \leq C y^{1/4} e^{\frac{\gamma x}{2\tau} - \frac{\sqrt{x}(3y-x)}{3\sqrt{\tau}}}.$$

Remembering the error term in (6.16) we obtain the result. \square

6.2 Proof of Proposition 6.2

From the formula (6.11),

$$\|\mathbb{T}_\gamma\|_2^2 = \int_0^\infty \int_0^\infty |\mathcal{T}_\gamma(x + s + t)|^2 ds dt = \int_x^\infty (y - x) |\mathcal{T}_\gamma(y)|^2 dy.$$

We split the integral into two parts: one for $x \leq y \leq x + c\sqrt{x}$ and the other for $y \geq x + c\sqrt{x}$, where $c = \frac{1-2\gamma}{24\tau^{1/2}}$ for $|\gamma| < \frac{1}{2}$ and $c = \frac{1}{12\tau^{1/2}}$ for $\gamma = \pm \frac{1}{2}$. Equation (6.15) implies that there is $0 < \epsilon < 1$ such that

$$|A(y; \gamma)|^2, |z^{\mp 1}A(y; \gamma \mp 1)|^2 \leq e^{-\frac{4}{3\sqrt{\tau}}(1-\frac{\epsilon}{2})y^{3/2}}$$

as $x \rightarrow \infty$, uniformly for $x \leq y \leq x + c\sqrt{x}$. Thus, for the first part of the integral, Proposition 6.9 and the equation (6.15) imply that for every $\epsilon \in (0, 1)$,

$$\int_x^{x+c\sqrt{x}} (y-x)|\mathcal{T}_\gamma(y)|^2 dy \leq \int_x^{x+cx^{1/2}} (y-x)e^{-\frac{4}{3\sqrt{\tau}}(1-\frac{\epsilon}{2})y^{3/2}} dy \leq e^{-\frac{4}{3\sqrt{\tau}}(1-\epsilon)x^{3/2}}$$

for all large enough x . For the second part of the integral, applying Proposition 6.10 we have

$$\int_{x+c\sqrt{x}}^\infty (y-x)|\mathcal{T}_\gamma(y)|^2 dy \leq C^2 \int_{x+c\sqrt{x}}^\infty (y-x) \left(y^{1/2} e^{\frac{\gamma x}{\tau} - \frac{2(3y-x)\sqrt{x}}{3\sqrt{\tau}}} + e^{-\frac{18K(y)x}{19\tau}} \right) dy \leq e^{-\frac{4}{3\sqrt{\tau}}(1-\epsilon)x^{3/2}}$$

for all large enough x . This completes the proof.

6.3 Proof of Proposition 6.3

From the formula (6.11),

$$\text{Tr}(\mathbb{T}_{-\gamma}\mathbb{T}_\gamma) = \int_0^\infty \int_0^\infty \mathcal{T}_{-\gamma}(x+s+t)\mathcal{T}_\gamma(x+s+t)dsdt = \int_x^\infty (y-x)\mathcal{T}_{-\gamma}(y)\mathcal{T}_\gamma(y)dy.$$

We split the integral into two parts; the part I_1 for $x \leq y \leq x+a\sqrt{x}$ and the second part I_2 for $y \geq x+a\sqrt{x}$ where $a = \frac{1-2|\gamma|}{24\sqrt{\tau}}$ when $|\gamma| < 1/2$, and $a = \frac{1}{12\sqrt{\tau}}$ when $\gamma = 1/2$.

Consider the first part I_1 . Proposition 6.9 implies that for $\gamma \in (-1/2, 1/2)$,

$$I_1 = \int_x^{x+ax^{1/2}} (y-x)A(y;\gamma)A(y;-\gamma)dy \left(1 + \mathcal{O}(e^{-cx^{1/2}}) \right),$$

and for $\gamma = \pm 1/2$,

$$I_1 = \int_x^{x+ax^{1/2}} (y-x) \left(2A(y;1/2)A(y;-1/2) + zA(y;1/2)^2 + z^{-1}A(y;-1/2)^2 \right) dy \left(1 + \mathcal{O}(e^{-cx^{1/2}}) \right).$$

From Lemma 6.4 and Equation (6.4),

$$\int_x^{x+ax^{1/2}} (y-x)A(y;\gamma)A(y;-\gamma)dy = \mathcal{B} \left(\frac{x}{\tau^{1/3}} + \frac{\gamma^2}{4\tau^{4/3}} \right) \left(1 + \mathcal{O}(e^{-cx^{1/2}}) \right),$$

$$\int_x^{x+ax^{1/2}} (y-x)A(y;1/2)^2 dy = e^{-\frac{1}{96\tau^2}} \mathcal{B} \left(\frac{x}{\tau^{1/3}} + \frac{1}{16\tau^{4/3}}; \frac{1}{2\tau^{2/3}} \right) \left(1 + \mathcal{O}(e^{-cx^{1/2}}) \right),$$

and

$$\int_x^{x+ax^{1/2}} (y-x)A(y;-1/2)^2 dy = e^{\frac{1}{96\tau^2}} \mathcal{B} \left(\frac{x}{\tau^{1/3}} + \frac{1}{16\tau^{4/3}}; -\frac{1}{2\tau^{2/3}} \right) \left(1 + \mathcal{O}(e^{-cx^{1/2}}) \right),$$

Consider the second part I_2 . Using Proposition 6.10 (which holds for $\gamma \in [-1/2, 1/2]$) for each of $\mathcal{T}_\gamma(y)$ and $\mathcal{T}_{-\gamma}(y)$, we need to consider four integrals. Noting the cancellation of the terms $-\frac{\gamma x}{2\tau}$ and $\frac{\gamma x}{2\tau}$, the first integral is bounded by a constant times

$$\int_{x+a\sqrt{x}}^\infty (y-x)y^{1/2}e^{-\frac{2(3y-x)\sqrt{x}}{3\sqrt{\tau}}} dy = \mathcal{O} \left(xe^{-\frac{4}{3\sqrt{\tau}}x^{3/2}-cx} \right).$$

for some $c > 0$. As we will see in a moment, this extra decay e^{-cx} is relevant. Two of the remaining three integrals are bounded by a constant times

$$\int_{x+a\sqrt{x}}^{\infty} (y-x)y^{1/4} e^{\pm \frac{\gamma x}{2\tau} - \frac{(3y-x)\sqrt{x}}{3\sqrt{\tau}} - \frac{9K(y)x}{19\tau}} dy = \mathcal{O}\left(e^{-\frac{4(1+\epsilon')}{3\sqrt{\tau}}x^{3/2}}\right)$$

for some $\epsilon' > 0$ due to the term involving $K(y)$. The final integral is bounded by a constant times

$$\int_{x+a\sqrt{x}}^{\infty} (y-x)e^{-\frac{18K(y)x}{19\tau}} dy = \mathcal{O}\left(e^{-\frac{4(1+\epsilon')}{3\sqrt{\tau}}x^{3/2}}\right).$$

Thus, $I_2 = \mathcal{O}(xe^{-\frac{4}{3\sqrt{\tau}}x^{3/2}-cx})$. We compare this with I_1 . Using Lemma 6.1 the leading terms in I_1 are of order $\mathcal{B}\left(\frac{x}{\tau^{1/3}} + \frac{1}{16\tau^{4/3}}\right) = \mathcal{O}\left(e^{-\frac{4}{3\sqrt{\tau}}x^{3/2}}\right)$. Hence, I_2 is exponentially smaller than I_1 , completing the proof.

7 Integrable differential equations

As mentioned before, from Lemmas 2.2 and 2.3 we learn that the operators \mathbb{H} and \mathbb{F} are IKS-integrable [27], and it is now the time to explore this structure.

It is known that the resolvent of an integrable operator can be evaluated in terms of a canonically associated Riemann-Hilbert problem (RHP) [27, 18]. The main difference of \mathbb{F} and \mathbb{H} is that \mathbb{F} acts on a space L^2 with absolutely continuous reference measure, whereas \mathbb{H} acts on a space ℓ^2 with discrete reference measure. Consequently the RHP for the former is continuous (involves only jump conditions) whereas the RHP for the latter is purely discrete (involves only residue conditions). The survey paper [18] reviews many aspects of the theory of continuous IKS operators. Properties of discrete IKS integrable operators were analyzed by Deift, in a work of Borodin [13, Section 4]. In this Section we explore this integrable structure to obtain Theorem 1.2.

Riemann-Hilbert problems, whether discrete, continuous or mixed, often arise in the inverse scattering transform in integrable differential equations. The common cubic polynomial factor V in (2.14) is the key to recognize the associated Riemann-Hilbert problems for \mathbb{H} and \mathbb{F} both as the ones that arise from coupled mKdV equations and coupled nonlinear heat equations, yielding Theorem 1.2. This approach of using integrable operators and Riemann-Hilbert problems for finding differential equations was also used in many other problems; see, for example, [19, 18, 13, 14, 11].

7.1 Riemann-Hilbert problem

As a first step, we describe the Riemann-Hilbert Problems (RHPs) associated to \mathbb{F} and \mathbb{H} . For that, recall that Λ and \mathcal{S} were defined in (2.13), V was defined in (2.14) and the functions $\vec{f}, \vec{g}, \vec{a}$ and \vec{b} appear in Lemmas 2.2 and 2.3.

The RHP asks for finding 2×2 matrices X (which is associated to \mathbb{H}) and Y (which is associated to \mathbb{F}) with the following properties.

RHP(a) The entries of X are analytic on $\mathbb{C} \setminus \mathcal{S}$ and the entries of Y are analytic on $\mathbb{C} \setminus \Lambda$.

RHP(b) X has a simple pole at every $\xi \in \mathcal{S}$, and its residue satisfies

$$\text{Res}_{s=\xi} X(s) = \lim_{s \rightarrow \xi} X(s) R_X(s),$$

with

$$R_X(s) := \vec{f}(s)\vec{g}(s)^T = \begin{pmatrix} 0 & \frac{e^{Q(s)-V(s)}}{s}\chi_+(s) \\ \frac{e^{-Q(s)+V(s)}}{s}\chi_-(s) & 0 \end{pmatrix}.$$

The matrix Y has continuous boundary values $Y_{\pm}(s)$ as s approaches Λ from its \pm -side, and they are related by

$$Y_+(s) = Y_-(s)J_Y(s),$$

with

$$J_Y(s) := I - \vec{a}(s)\vec{b}(s)^T = \begin{pmatrix} 1 & -e^{-V(s)}\chi_{\Lambda_+}(s) \\ e^{V(s)}\chi_{\Lambda_-}(s) & 1 \end{pmatrix},$$

where I is the 2×2 identity matrix.

RHP(c) As $s \rightarrow \infty$ the matrices X and Y admit asymptotic expansions of the form

$$X(s) \sim I + \sum_{k=1}^{\infty} \frac{X_k}{s^k} \quad \text{and} \quad Y(s) \sim I + \sum_{k=1}^{\infty} \frac{Y_k}{s^k} \quad (7.1)$$

for matrices X_k and Y_k that are constant in s .

The condition **RHP(c)** for X should be understood as $s \rightarrow \infty$ uniformly away from \mathcal{S} .

For $\gamma = 0$ and $\tau = 1$, the RHP for Y above coincides with a particular case of the ones studied in [11, 12].

Since $\vec{g}(s)^T \vec{f}(s) = 0$, we find that $R_X(s)^2 = 0$. This implies that the limit $\lim_{\xi \rightarrow s} X(\xi)R_X(s)$ in **RHP(b)** converges. The residue condition can also be stated in a different way. The following basic result is essentially in [13, Lemma 4.4].

Lemma 7.1. *Let $X(\xi)$ be an $r \times r$ matrix function with a simple pole at a point $s \in \mathbb{C}$. Let R be a constant $r \times r$ matrix such that $R^2 = 0$. The following statements are equivalent.*

- (i) $\text{Res}_s X = \lim_{\xi \rightarrow s} X(\xi)R$
- (ii) *The product $X(\xi)(-\frac{R}{\xi-s} + I)$ is analytic at $\xi = s$.*

Proof. Without loss of generality, assume $s = 0$ and write $X(\xi) = \frac{X_{-1}}{\xi} + X_0 + \mathcal{O}(\xi)$ as $\xi \rightarrow 0$. Then

$$X(\xi) \left(-\frac{R}{\xi} + I \right) = -\frac{X_{-1}R}{\xi^2} + \frac{X_{-1} - X_0R}{\xi} + \mathcal{O}(1), \quad \xi \rightarrow 0.$$

This means that (ii) holds true if and only if $X_{-1}R = 0$ and $X_{-1} - X_0R = 0$. Since $R^2 = 0$, these two equations are equivalent to the single equation $X_{-1} = X_0R$, which is equivalent to the statement (i). \square

We now state the solvability of the RHPs.

Lemma 7.2. *For any real values of x, γ and τ , the RHP for Y has a unique solution. The RHP for X has a solution for all (τ, γ, x) and $0 < |z| < 1$ satisfying $\det(\mathbb{I} - \mathbb{K}_z) \neq 0$ which is an open set of full Lebesgue measure in the space of parameters (τ, γ, x, z) . Also, if X exists, then it is unique and $\det X \equiv 1$.*

Proof. From Lemma 2.3 we know that $\det(\mathbb{I} - \mathbb{F}) = \det(\mathbb{I} - \mathbb{A}_{-\gamma}\mathbb{A}_{\gamma})$, and the latter is never zero because it coincides with the classical Airy determinant (see (1.3)). Consequently $\mathbb{I} - \mathbb{F}$ is invertible and by [18] the RHP for Y has a unique solution.

By [13], the RHP for X has a unique solution if $\mathbb{I} - \mathbb{H}$ is invertible. Hence, the first statement for X follows since $\det(\mathbb{I} - \mathbb{K}_z)$ is analytic in all four variables. On the other hand, from $R_X(s)^2 = 0$ we obtain that $\det(I - (\xi - s)^{-1}R) \equiv 1$ and Lemma 7.1 implies that $\det X(\xi)$ is an entire function. Because $\det X(\xi) \rightarrow 1$ as $\xi \rightarrow \infty$, Liouville's Theorem implies that $\det X \equiv 1$. \square

Since $\det X \equiv 1$ and $\det Y \equiv 1$, from **RHP(c)** we find that $\text{Tr } X_1 = 0$ and $\text{Tr } Y_1 = 0$. We denote the entries of X_1 and Y_1 as

$$X_1 := \begin{pmatrix} Q_{\text{per}} & P_{\text{per}} \\ R_{\text{per}} & -Q_{\text{per}} \end{pmatrix}, \quad \text{and} \quad Y_1 := \begin{pmatrix} Q_{\text{KPZ}} & P_{\text{KPZ}} \\ R_{\text{KPZ}} & -Q_{\text{KPZ}} \end{pmatrix} \quad (7.2)$$

where $Q_{\text{per}}, P_{\text{per}}, R_{\text{per}}$ are functions of x, γ, τ , and also z , whereas $Q_{\text{KPZ}}, P_{\text{KPZ}}, R_{\text{KPZ}}$ are functions of x, γ, τ but not of z .

If the integrable operator has some additional structure, then the logarithmic derivative of the Fredholm determinant can be expressed directly in terms of the solution to the associated RHP. In our case, we show that the logarithmic derivative of the Fredholm determinants in the x variable can be expressed in terms of (7.2) as in the next lemma.

Lemma 7.3 (Deformation formula). *We have*

$$\partial_x \log \det(\mathbb{I} - \mathbb{H}) = Q_{\text{per}} \quad \text{and} \quad \partial_x \log \det(\mathbb{I} - \mathbb{F}) = Q_{\text{KPZ}}. \quad (7.3)$$

Proof. The proof is standard, and various versions of this formula for continuous RHPs have appeared, for example, in [19, 13, 12]. For convenience of the reader in Appendix A we provide a proof in the discrete case. \square

7.2 Coupled integrable differential equations

From the explicit form of the vectors $\vec{a}, \vec{b}, \vec{f}$ and \vec{g} given in Lemmas 2.2 and 2.3, the matrices R_X and J_Y can be brought to the form

$$R_X(s) = e^{-\frac{1}{2}\mathcal{V}(s)\sigma_3} R_0(s) e^{\frac{1}{2}\mathcal{V}(s)\sigma_3} \quad \text{and} \quad J_Y(s) = e^{-\frac{1}{2}\mathcal{V}(s)\sigma_3} J_0(s) e^{\frac{1}{2}\mathcal{V}(s)\sigma_3}$$

for matrices $R_0(s)$ and $J_0(s)$ which do not depend on τ, γ, τ , and the choice $\mathcal{V}(s) = V(s; \tau, \gamma, x)$ with V as (2.14).

For general \mathcal{V} , the dressing method for RHPs consists of, starting from a residue or jump matrix as above, finding an integrable differential equation related to the solution $W = X, Y$ as follows. Setting $W_0 = W e^{-\mathcal{V}\sigma_3/2}$, the new matrix W_0 has the residue matrix R_0 (or jump matrix J_0) which does not depend on the parameters of \mathcal{V} . So the derivative of W_0 with respect to these parameters satisfies the same RHP as W itself, apart from different asymptotics as $s \rightarrow \infty$. This implies that $(\partial W_0)W_0^{-1}$ has only removable singularities, and using Liouville's theorem, we find linear differential equations for W_0 on the parameters of \mathcal{V} . When these differential equations for two different parameters are combined they form a Lax pair for W . The specific form of this Lax pair depends solely on \mathcal{V} but not on whether W solves a discrete or continuous RHP. After some work, the compatibility condition for this Lax pair reduces to nonlinear equations/systems on the entries of $W_1 = X_1, Y_1$.

Carrying out the general ideas just outlined, by picking different rational exponents \mathcal{V} one can produce different integrable systems, including (modified) Korteweg-de Vries equation, nonlinear Schrödinger equation, or even more generally the AKNS system [1] that contains the former and many other integrable differential equations.

In our specific context, we can suppress the γ term from V into R_0 and J_0 and write

$$R_X(s) = e^{-\frac{1}{2}(-\frac{\gamma}{3}s^3+xs)\sigma_3} R_1(s) e^{\frac{1}{2}(-\frac{\gamma}{3}s^3+xs)\sigma_3} \quad \text{and} \quad J_Y(s) = e^{-\frac{1}{2}(-\frac{\gamma}{3}s^3+xs)\sigma_3} J_1(s) e^{\frac{1}{2}(-\frac{\gamma}{3}s^3+xs)\sigma_3}$$

for matrices $R_1(s)$ and $J_1(s)$ which do not depend on τ and x . The formalism just mentioned then produces that the entries of X_1 and Y_1 solve the coupled mKdV system claimed in Theorem 1.2. If, on the other hand, we suppress the τ term and write

$$R_X(s) = e^{-\frac{1}{2}(\frac{\gamma}{2}s^2+xs)\sigma_3} R_2(s) e^{\frac{1}{2}(\frac{\gamma}{2}s^2+xs)\sigma_3} \quad \text{and} \quad J_Y(s) = e^{-\frac{1}{2}(\frac{\gamma}{2}s^2+xs)\sigma_3} J_2(s) e^{\frac{1}{2}(\frac{\gamma}{2}s^2+xs)\sigma_3}$$

for matrices $R_2(s)$ and $J_2(s)$ which do not depend on γ and x , then we obtain the nonlinear heat equations in Theorem 1.2. We stress that these arguments do not rely on the choice of R_1, R_2, J_1, J_2 but solely on the choice of the conjugating exponential factors in the above.

In either of the two situations above, for X we are dealing with a purely discrete RHP with infinitely many poles, which indicates that P_{per} and R_{per} are infinite soliton solutions. Also, we considered the parameter z that defines the set of poles \mathcal{S} to be fixed. In terms of the integrable systems for X , the dependence of P_{per} and R_{per} on z appears in the initial/boundary conditions, and since this set of poles is not, for general z , symmetric under the real axis, these solutions P_{per} and R_{per} are, also for general z , complex-valued.

The equations in Theorem 1.2 should be supplemented by appropriate initial/boundary conditions, which should be read off from the RHP. Finding these initial/boundary conditions is a challenge of its own, and we do not pursue it in this paper.

The calculations that lead to the exact form of the systems (1.10)–(1.11) is a folklore in integrable systems theory, for convenience of the reader we include them in the Appendix B.

In concrete terms, the outcome of this discussion is summarized as the next result.

Proposition 7.4. *The entries $q = Q_{\text{KPZ}}$, $r = R_{\text{KPZ}}$ and $p = P_{\text{KPZ}}$ of Y_1 in (7.2) satisfy*

$$q_x = pr. \tag{7.4}$$

The pair (p, r) satisfies a coupled system of nonlinear heat equations,

$$\begin{cases} 2p_\gamma = -p_{xx} - 2p^2r \\ 2r_\gamma = r_{xx} + 2pr^2 \end{cases} \tag{7.5}$$

and also a coupled system of mKdV equations

$$\begin{cases} 3p_\tau + p_{xxx} + 6prp_x = 0 \\ 3r_\tau + r_{xxx} + 6prr_x = 0. \end{cases} \tag{7.6}$$

The same is true for the entries $q = Q_{\text{per}}$, $r = R_{\text{per}}$ and $p = P_{\text{per}}$ of X_1 in (7.2), provided the solution X of the RHP exists.

7.3 From the coupled systems to the KP equation: proof of Theorem 1.2 and Corollary 1.3

For $u = U_{\text{per}}, U_{\text{KPZ}}$ as in Corollary 1.3, we take the derivative of the equation (7.3) and use Lemma 2.2 (for $u = U_{\text{per}}$) or Lemma 2.3 (for $u = U_{\text{KPZ}}$), combined with (7.4), and write

$$u = q_x = pr,$$

with $q = Q_{\text{KPZ}}, Q_{\text{per}}$ etc. Thus, Proposition 7.4 implies Theorem 1.2 except (1.12) which we prove in the next subsection.

We now show that the pair of coupled systems (7.5) and (7.6), when combined together, yield the KP equation, hence proving Theorem 1.3. Using (7.5), we have $2u_\gamma = pr_{xx} - p_{xx}r = \partial_x(pr_x - p_xr)$. Using (7.5) again and noting $pr(pr_x + p_xr) = uu_x$, we find that

$$4u_{\gamma\gamma} = \partial_x (pr_{xxx} + p_{xxx}r + 4uu_x - (p_xr_x)_x).$$

On the other hand, multiplying the first equation in (7.6) by r and the second by p , and adding the results, we get, using $pr(pr_x + p_xr) = uu_x$ again,

$$3u_\tau + pr_{xxx} + p_{xxx}r + 6uu_x = 0.$$

Finally, the third derivative evaluation of $u = pr$ is given by

$$u_{xxx} = pr_{xxx} + p_{xxx}r + 3(p_xr_x)_x.$$

We combine the above three equations to remove $pr_{xxx} + p_{xxx}r$ and $(p_xr_x)_x$ and obtain the KP equation

$$12u_{\gamma\gamma} + (u_{xxx} + 12uu_x + 12u_\tau)_x = 0.$$

This proves Theorem 1.3.

In summary, the calculations above show that any RHP with residue or jump matrix of the form

$$M(s) = e^{-\frac{1}{2}(-\frac{\tau}{3}s^3 + \frac{\gamma}{2}s + xs)\sigma_3} M_0(s) e^{\frac{1}{2}(-\frac{\tau}{3}s^3 + \frac{\gamma}{2}s + xs)\sigma_3}$$

with a matrix $M_0(s)$ which do not depend on τ, γ, x is associated to the KP equation. Rigorous analysis of the scattering transform for the KP equation has been carried out for classes of real solutions that decay sufficiently fast as $x, \gamma \rightarrow \infty$, except possibly along a line (see [4] and the references therein). In these situations, the inverse scattering transform always involves a so-called d-bar problem component, possibly also with poles, and a continuous RHP, all for scalar functions instead of matrix-valued functions. Our RHP for Y is nothing but a dressed-up version of the RHP for the Hastings-McLeod solution to PII, which is well understood. In contrast, our RHP for X is a purely discrete matrix RHP. Hence, the KP solution encoded in our discrete matrix RHP falls outside the class of the just mentioned works. Determining the exact growth/decay properties of our KP solution is a separate task of interest.

7.4 Symmetry

We start with the discrete RHP for X . Define

$$\widehat{X}(\xi; \gamma) := \sigma_1 X(-\xi; -\gamma) \sigma_1, \quad \text{with } \sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}.$$

This matrix tends to the identity matrix I as $\xi \rightarrow \infty$.

A direct calculation shows that the residue matrix for X satisfies the symmetry property

$$R_X(-s; -\gamma) = -\sigma_1 R_X(s; \gamma) \sigma_1.$$

Hence, $\widehat{X}(\xi; \gamma)$ satisfies, for every $s \in \mathcal{S}$,

$$\widehat{X}(\xi; \gamma) \left(-\frac{R_X(s; \gamma)}{\xi - s} + I \right) = \sigma_1 X(-\xi; -\gamma) \left(-\frac{R_X(-s; -\gamma)}{(-\xi) - (-s)} + I \right) \sigma_1.$$

By the RHP for X and Lemma 7.1, the above formula is analytic at $\xi = s$. Hence, Lemma 7.1 again shows that $\widehat{X}(\xi; \gamma)$ satisfies the same residue condition as $X(\xi; \gamma)$. By the uniqueness of the solution to the RHP, we find that $\widehat{X}(\xi) = X(\xi)$, thus obtaining the symmetry property

$$X(\xi; \gamma) = \sigma_1 X(-\xi; -\gamma) \sigma_1.$$

Inserting this into the asymptotic expansion (7.1) we find that $X_k = (-1)^k \sigma_1 X_k(-\gamma) \sigma_1$ for all $k \geq 1$. When $k = 1$, this means that the coefficients in (7.2) satisfy $p(\gamma) = -r(-\gamma)$, proving the symmetry (1.12). We also have $q(\gamma) = q(-\gamma)$.

The proof for Y is similar: the jump symmetry is now

$$\sigma_1 J_Y(-s; -\gamma) \sigma_1 = J_Y(s; \gamma)^{-1},$$

and this implies that $\sigma_1 Y(-s; -\gamma) \sigma_1 = Y(s; \gamma)$, which then from (7.1) yields the symmetry (1.12).

We discussed in Section 1.2 that using the symmetry, the function p itself satisfies the non-local differential equations (1.13) and (1.14). The equation (1.14) is a non-local nonlinear Schrödinger (NLS) equation with complex time variable. The appearance of the non-local NLS from the AKNS system was obtained relatively recently in [3], and the inverse scattering transform of this non-local NLS equation has also recently been analyzed (see [2] and the references therein) for a class of initial conditions with finite amplitude as $x \rightarrow \infty$. Among other distinguishing features, in these works the poles of the discrete RHP were symmetric under reflection onto the imaginary axis, which is not the case for our discrete RHP.

8 Flat initial condition

All of the results for the step initial condition extend to the flat initial condition, and we now discuss them.

The limit of the one point distribution with the flat initial condition does not depend on the location parameter γ . It is given by the formula [8]

$$F_1(x; \tau) = \oint e^{xA_1(z) + \tau A_2(z) + A_3(z) + B(z)} \det(\mathbb{I} - \mathbb{K}_z^{(1)}) \frac{dz}{2\pi i z}, \quad (8.1)$$

where the integral is a small circle around the origin in the counterclockwise direction. The functions A_1, A_2, B are the same as in the step initial condition case, and $A_3(z) = -\frac{1}{4} \log(1 - z)$. The operator $\mathbb{K}_z^{(1)} : \ell^2(\mathcal{S}_-) \rightarrow \ell^2(\mathcal{S}_-)$ is defined via the kernel

$$\mathbf{K}_z^{(1)}(\xi_1, \xi_2) = \mathbf{K}_z^{(1)}(\xi_1, \xi_2; x, \tau) = \frac{e^{\Psi(\xi_1) + \Psi(\xi_2)}}{\xi_1(\xi_1 + \xi_2)}, \quad \xi_1, \xi_2 \in \mathcal{S}_-, \quad (8.2)$$

where the function Ψ is given by

$$\Psi(\xi) = \Psi(\xi; x, \tau) := -\frac{1}{3} \tau \xi^3 + x\xi - \frac{1}{2} Q(\xi) = \frac{1}{2} \Phi(\xi; 2x, 2\tau) \quad (8.3)$$

compared with the function Φ in (2.5). We have the following results.

Theorem 8.1 (Large τ limit; flat case). *For each fixed $x \in \mathbb{R}$,*

$$\lim_{\tau \rightarrow \infty} F_1 \left(-\tau + \frac{\pi^{1/4}}{\sqrt{2}} x \tau^{1/2}; \tau \right) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^x e^{-\frac{y^2}{2}} dy.$$

Theorem 8.2 (Small τ limit; flat case). *For every $x_0 \in \mathbb{R}$, there exist constants $C, c, \epsilon > 0$ and $\tau_0 > 0$ such that*

$$\left| F_1 \left(\tau^{1/3} x; \tau \right) - F_{\text{GOE}}(2^{2/3} x) \right| \leq C e^{-\epsilon \tau^{-2/3}} e^{-c(x-x_0)}, \quad 0 < \tau < \tau_0, \quad x \geq x_0,$$

where F_{GOE} is the GOE Tracy-Widom distribution. In particular,

$$\lim_{\tau \rightarrow 0} F_1(\tau^{1/3} x; \tau) = F_{\text{GOE}}(2^{2/3} x).$$

Theorem 8.3 (Right tail estimate; flat case). *For every fixed $\tau > 0$, there is a constant $c > 0$ such that*

$$1 - F_1(x; \tau) = (1 - F_{\text{GOE}}(2^{2/3} \tau^{-1/3} x)) \left(1 + \mathcal{O}(e^{-cx^{1/2}}) \right), \quad x \rightarrow \infty.$$

The above result shows that the leading term of the right tail of $F_1(\tau^{1/3} x; \tau)$ does not depend on τ , and it is the same as the right tail of $F_{\text{GOE}}(2^{2/3} x)$, which can be found, for example, in [6].

Theorem 8.4 (Integrable differential equations; flat case). *The kernel $\mathbb{K}^{(1)}$ with x, τ replaced by $\frac{x}{2}, \frac{\tau}{2}$ satisfies*

$$\partial_x \ln \det(\mathbb{I} - \mathbb{K}_z^{(1)}|_{\frac{x}{2}, \frac{\tau}{2}}) = \frac{1}{2} R(\tau, x) + \frac{1}{2} Q(\tau, x)$$

where $R(\tau, x) = R_{\text{per}}(\tau, 0, x)$ and $Q(\tau, x) = Q_{\text{per}}(\tau, 0, x)$ in terms of the functions in Theorem 1.2 and Proposition 7.4. The function R satisfies the (defocusing) mKdV equation

$$3R_\tau + R_{xxx} - 6R^2 R_x = 0 \quad \text{and} \quad Q_x = -R^2.$$

As a consequence, we rediscover a connection with the KdV equation that was first pointed out by Prolhac [39, Section 2.6.3], albeit in different form.

Corollary 8.5. *The function*

$$U(\tau, x) := 2\partial_{xx} \ln \det(\mathbb{I} - \mathbb{K}_z^{(1)}|_{\frac{x}{2}, \frac{\tau}{2}})$$

satisfies the Korteweg–de Vries equation (KdV) equation¹²

$$3U_\tau + U_{xxx} + 6UU_x = 0.$$

Proof. We have $U = R_x + Q_x = R_x - R^2$. It is straightforward to check that if R satisfies the mKdV equation, then U satisfies the KdV equation. Indeed, this is a well-known Miura transformation. \square

We prove the above theorems in the following subsections.

¹²The scale $\tau \mapsto 3\tau$ changes to a standard form of the KdV equation $U_\tau + U_{xxx} + 6UU_x = 0$.

8.1 Large τ limit

For x_τ as in (4.1), we use (8.1)–(8.3) and write

$$F_1(x_\tau/2; \tau/2) = \oint e^{\frac{x_\tau}{2} A_1(z) + \frac{\tau}{2} A_2(z) + A_3(z) + B(z)} \det(\mathbb{I} - \mathbb{K}_z^{(1)}|_{\frac{x_\tau}{2}, \frac{\tau}{2}}) \frac{dz}{2\pi iz},$$

emphasizing the explicit expression

$$\mathbf{K}_z^{(1)}|_{\frac{x_\tau}{2}, \frac{\tau}{2}}(\xi_1, \xi_2) = \frac{e^{\frac{1}{2}\Phi_\tau(\xi_1) + \frac{1}{2}\Phi_\tau(\xi_2)}}{\xi_1(\xi_1 + \xi_2)}, \quad \xi_1, \xi_2 \in \mathcal{S}_-,$$

with $\Phi_\tau(\xi) := \Phi(\xi; x_\tau, \tau)$ as in (4.5).

As in Lemma 4.4, let $\mathcal{S}_- = \{u_k\}_{k \in \mathbb{Z}}$ and let ℓ_1, \dots, ℓ_N be distinct integers. Corollary 4.2 and Lemma 4.3 imply that

$$\sum_{k=1}^N \left| \mathbf{K}_z^{(1)}|_{\frac{x_\tau}{2}, \frac{\tau}{2}}(\xi, u_{\ell_k}) \right|^2 \leq \frac{1}{c^2} e^{\operatorname{Re} \Phi_\tau(\xi)} \sum_{k=-\infty}^{\infty} \frac{e^{\operatorname{Re} \Phi_\tau(u_k)}}{|k| + 2}, \quad \xi \in \mathcal{S}_-,$$

and we further estimate

$$\sum_{k=-\infty}^{\infty} \frac{e^{\operatorname{Re} \Phi_\tau(u_k)}}{|k| + 2} \leq \frac{e^{0.4734\tau}}{2} + 2 \sum_{k=1}^{\infty} e^{-1.9366|k|^{3/2}\tau} \leq e^{0.4734\tau}$$

for all large enough τ and every z as in Corollary 4.2. Thus, there are τ_0 and $C > 0$ such that

$$\sum_{k=1}^N \left| \mathbf{K}_z^{(1)}|_{\frac{x_\tau}{2}, \frac{\tau}{2}}(\xi, u_{\ell_k}) \right|^2 \leq C e^{\operatorname{Re} \Phi_\tau(\xi) + 0.4734\tau}$$

uniformly for $\xi \in \mathcal{S}_-$ and $\tau \geq \tau_0$; this estimate is similar to Lemma 4.4. Similar arguments as used in the proof of Proposition 4.5 now show that

$$\det(\mathbb{I} - \mathbb{K}_z^{(1)}|_{\frac{x_\tau}{2}, \frac{\tau}{2}}) = 1 - \operatorname{Tr}(\mathbb{K}_z^{(1)}|_{\frac{x_\tau}{2}, \frac{\tau}{2}}) + \mathcal{O}(e^{-0.255\tau})$$

as $\tau \rightarrow \infty$, uniformly for $1 - \delta \leq |z| \leq 1 - \delta_1$ for some $\delta \in (0, 1)$ and any fixed $\delta_1 \in (0, \delta)$. Here, the exponent in the error is half the one from Proposition 4.5 due to the change from Φ_τ to $\frac{1}{2}\Phi_\tau$ in the kernel.

We look now at the proof of Proposition 4.6. The estimate (4.8) implies that for every $R \in (0, 1 - \delta_1)$,

$$\max_{|z|=R} \operatorname{Re} \left(\frac{x_\tau}{2} A_1(z) + \frac{\tau}{2} A_2(z) + A_3(z) + B(z) \right) < 0.254\tau$$

for sufficiently large τ , and Proposition 4.6 changes to

$$F_1(x_\tau/2, \tau/2) = 1 - \oint e^{\frac{x_\tau}{2} A_1(z) + \frac{\tau}{2} A_2(z) + A_3(z) + B(z)} \operatorname{Tr}(\mathbb{K}_z^{(1)}|_{\frac{x_\tau}{2}, \frac{\tau}{2}}) \frac{dz}{2\pi iz} + \mathcal{O}(e^{-0.001\tau})$$

as $\tau \rightarrow \infty$. From the formula of $\mathbb{K}_z^{(1)}$, the version of Lemma 4.7 now follows from the simpler estimate

$$\operatorname{Tr} \mathbb{K}_z^{(1)}|_{\frac{x_\tau}{2}, \frac{\tau}{2}} = \frac{e^{\Phi_\tau(u_0(z))}}{2u_0(z)^2} + \sum_{k \in \mathbb{Z} \setminus \{0\}} \frac{e^{\Phi_\tau(u_k)}}{2u_k^2} = \frac{e^{\Phi_\tau(u_0(z))}}{2u_0(z)^2} + \mathcal{O}(e^{-1.9\tau}),$$

where the error term was obtained using Corollary 4.2 and Lemma 4.3.

Plugging in the formulas and using the notations (4.9),

$$\int e^{\frac{x}{2}\tau} A_1(z) + \frac{\tau}{2} A_2(z) + A_3(z) + B(z) \frac{e^{\Phi_\tau(u_0(z))}}{2u_0(z)^2} \frac{dz}{2\pi i z} = \frac{1}{4\pi i} \int \frac{E^{(1)}(z) e^{\frac{1}{2}\tau f_1(z) + \frac{1}{2}\tau^{1/2}\hat{x}f_2(z)}}{zu_0(z)^2} dz$$

where $\hat{x} = \frac{\pi^{1/4}x}{2}$ as before, $x \in \mathbb{R}$ fixed, and

$$E^{(1)}(z) := e^{A_3(z) + B(z) - Q(u_0(z))} = \frac{E(z)^{1/2}}{(1-z)^{1/4}}, \quad E(z) = e^{2B(z) - 2Q(u_0(z))} \text{ as before.}$$

The functions f_1 and f_2 have analytic extensions, f_1 and f_2 , on the Riemann surface \mathcal{R} (see Section 3.3). On the other hand, the function $E(z)$ also extends analytically on \mathcal{R} and has a zero of order 3 at $z = 1$ (see Section 3.4). Combined with $(1-z)^{-1/4}$, we see that $E^{(1)}(z)$ extends analytically on \mathcal{R} and it has a zero of order 1 at $z = 1$. We denote the extension by $\mathbf{E}^{(1)}(z)$. Recalling Lemma 3.5, $\mathbf{E}(z) \approx -4u_0(z)^4$ as $z \rightarrow 0^{(2)}$. It is also direct to verify that $(1-z)^{-1/4} = -i$ as $z \rightarrow 0^{(2)}$. Combining everything, $\mathbf{E}^{(1)}(z) = -2u_0(z)^2(1 + \mathcal{O}(z^2))$ as $z \rightarrow 0^{(2)}$. Define the one form (cf. (4.11))

$$\omega_\tau^{(1)} := \frac{\mathbf{E}^{(1)}(z) e^{\frac{\tau}{2}f_1(z) + \frac{\tau^{1/2}\hat{x}}{2}f_2(z)}}{4\pi i z U_0(z)^2} dz$$

on the Riemann surface \mathcal{R} . Using this notation, we just verified that (cf. (4.12))

$$F_1(x_\tau/2, \tau/2) = 1 - \int_\Gamma \omega_\tau^{(1)} + \mathcal{O}(e^{-0.001\tau})$$

where Γ is the same contour that was used in (4.12). We evaluate the integral following Section 4.3. The contour is divided into three parts. The proofs of Lemma 4.10 and 4.11 for the parts Γ_1 and Γ_2 apply with minimal changes, and contributions from these parts tend to zero as $\tau \rightarrow \infty$. On the other hand, for the contour Γ_3 , which is a small semicircle about the origin in the second sheet of \mathcal{R} , most of the proof of Lemma 4.9 does not change, but in the last steps we find

$$\lim_{\tau \rightarrow \infty} \int_{\Gamma_3} \omega_\tau^{(1)} = \frac{1}{2\pi i} \int_{-i\infty}^{i\infty} e^{\frac{1}{2}\left(\frac{1}{s\sqrt{\pi}}s^2 - \frac{\hat{x}}{\sqrt{2}\pi}s\right)} \frac{ds}{s} = \frac{1}{2\pi i} \int_{-\infty}^{\infty} e^{-\frac{u^2}{2} - i\frac{x}{\sqrt{2}}u} \frac{du}{u} = \frac{1}{\sqrt{2\pi}} \int_{\frac{x}{\sqrt{2}}}^{\infty} e^{-\frac{1}{2}u^2} du,$$

where for the second inequality we changed variables $s = i2^{3/2}\pi^{1/4}u$ and used that $\hat{x} = \pi^{1/4}x/\sqrt{2}$. Having in mind the explicit expression for x_τ in (4.1), we just obtained that

$$\lim_{\tau \rightarrow 0} F_1\left(-\frac{\tau}{2} + \frac{\pi^{1/4}}{\sqrt{2}} \frac{x}{\sqrt{2}} \left(\frac{\tau}{2}\right)^{1/2}, \frac{\tau}{2}\right) = \lim_{\tau \rightarrow 0} F_1\left(-\tau + \frac{\pi^{1/4}}{\sqrt{2}} \frac{x}{\sqrt{2}} \tau^{1/2}, \tau\right) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\frac{x}{\sqrt{2}}} e^{-\frac{u^2}{2}} du,$$

valid for any $x \in \mathbb{R}$ fixed. This finishes the proof of Theorem 8.1.

8.2 Small τ limit

After a simple conjugation, we may replace the kernel $\mathbf{K}_z^{(1)}(\xi_1, \xi_2)$ in (8.2) by (using the same notation)

$$\mathbf{K}_z^{(1)}(\xi_1, \xi_2) = -\frac{e^{\Psi(\xi_1) + \Psi(\xi_2)}}{\sqrt{-\xi_1}\sqrt{-\xi_2}(\xi_1 + \xi_2)}, \quad \xi_1, \xi_2 \in \mathcal{S}_-,$$

without changing the Fredholm determinant. Using (8.3) and the notation from (2.10), we see that

$$\mathbf{K}_z^{(1)}\left(\xi, \eta; \frac{x}{2}, \frac{\tau}{2}\right) = -\frac{e^{\frac{1}{2}\Phi(\xi; x, \tau) + \frac{1}{2}\Phi(\eta; x, \tau)}}{\sqrt{-\xi}\sqrt{-\eta}(\xi + \eta)} = -\mathbf{J}(\xi, \eta; x, \gamma = 0, \tau), \quad \text{that is, } \mathbb{K}_z^{(1)}|_{\frac{x}{2}, \frac{\tau}{2}} = -\mathbb{J}|_{\gamma=0}. \quad (8.4)$$

Now from (2.12) we have $\mathbb{J}|_{\gamma=0} = -\mathbb{G}_0\mathbb{G}_0^T$, and recalling that $\mathbb{T}_\gamma = \mathbb{G}_{-\gamma}^T\mathbb{G}_{-\gamma}$ we find that

$$\det(\mathbb{I} - \mathbb{K}_z^{(1)}|_{\frac{x}{2}, \frac{\tau}{2}}) = \det(\mathbb{I} - \mathbb{T}_0) \quad (8.5)$$

where \mathbb{T}_0 has kernel as in Lemma 1.1 with $\gamma = 0$. Thus, changing x to $\tau^{1/3}x$, we find that

$$F_1\left(\frac{\tau^{1/3}x}{2}; \frac{\tau}{2}\right) = \oint e^{\frac{\tau^{1/3}x}{2}A_1(z) + \frac{\tau}{2}A_2(z) + A_3(z) + B(z)} \det(\mathbb{I} - \mathbb{A}_{x,\tau}) \frac{dz}{2\pi iz}$$

where the operator $\mathbb{A}_{x,\tau}$ is defined by (5.1). Recall that $F_{\text{GOE}}(x) = \det(\mathbb{I} - \mathbb{A}_x)$. Lemma 5.2 established the convergence of $\mathbb{A}_{x,\tau}$ to the operator \mathbb{A}_x with an explicit error bound for the kernel. Hence, we find that the Fredholm determinant converges as well with the same error bound as in Corollary 5.3. Taking the integral (see Section 5.2), we find that

$$\left|F_1\left(\frac{\tau^{1/3}x}{2}; \frac{\tau}{2}\right) - F_{\text{GOE}}(x)\right| \leq C e^{-\epsilon\tau^{-2/3}} e^{-c(x-x_0)}.$$

Changing $\tau \mapsto 2\tau$, and $x \mapsto 2^{2/3}x$, and renaming the constants, we conclude the proof of Theorem 8.2.

8.3 Right tail

From (8.5),

$$F_1(x/2; \tau/2) = \oint e^{\frac{x}{2}A_1(z) + \frac{\tau}{2}A_2(z) + A_3(z) + B(z)} \det(\mathbb{I} - \mathbb{T}_0) \frac{dz}{2\pi iz}.$$

As in Section 6, we take the contour $|z| = e^{-\frac{x}{2\tau}}$. Proposition 6.2 implies that we may change the Fredholm determinant to $1 - \text{Tr}(\mathbb{T}_0)$ plus an error term. The kernel is given by $\mathbf{T}_0(s, t) = \mathcal{T}_0(x + s + t)$ (see (6.11)). Proposition 6.9 and 6.10 allow us to replace $\mathcal{T}_0(x + s + t)$ by $\mathbf{A}(x + s + t; 0)$ whose asymptotic formula is given in Lemma 6.4. Thus, after performing the trivial z -integral, we find that

$$1 - F_1(x/2; \tau/2) = \int_x^\infty \frac{1}{\tau^{1/3}} \text{Ai}\left(2\tau^{-1/3}y\right) dy \left(1 + \mathcal{O}(e^{-cx^{1/2}})\right).$$

We have

$$\int_x^\infty \frac{1}{\tau^{1/3}} \text{Ai}\left(2\tau^{-1/3}y\right) dy = \int_x^\infty \text{Ai}(2y) dy = \text{Tr}(\mathbb{A}_x) = (1 - F_{\text{GOE}}(x)) \left(1 + \mathcal{O}(e^{-cx})\right).$$

Scaling x and τ completes the proof of Theorem 8.3.

8.4 Integrable differential equations

From (8.4),

$$\det(\mathbb{I} - \mathbb{K}_z^{(1)}|_{\frac{x}{2}, \frac{\tau}{2}}) = \det(\mathbb{I} + \mathbb{J}|_{\gamma=0}).$$

The operator for the step initial condition case satisfies $\mathbb{K}_z = \mathbb{J}\mathbb{J}^T$ (see (2.9)). Because of the symmetry $\mathbb{J}^T|_\gamma = \mathbb{J}|_{-\gamma}$ (see (2.11)), we find that

$$\mathbb{K}_z|_{\gamma=0} = (\mathbb{J}|_{\gamma=0})^2.$$

For all the computations in the rest of this section we set $\gamma = 0$, and in particular for simplicity we write $\mathbb{K}_z|_{\gamma=0}$ and $\mathbb{J}|_{\gamma=0}$ simply \mathbb{K}_z and \mathbb{J} . Also, we use the notation $\partial = \partial_x$.

We have

$$\partial \ln \det(\mathbb{I} - \mathbb{K}_z^{(1)}|_{\frac{x}{2}, \frac{\tau}{2}}) = \partial \ln \det(\mathbb{I} + \mathbb{J}) = \text{Tr}((\mathbb{I} + \mathbb{J})^{-1} \partial \mathbb{J}) = \text{Tr}((\mathbb{I} - \mathbb{J}^2)^{-1} (\mathbb{I} - \mathbb{J}) \partial \mathbb{J}).$$

Using that $(\mathbb{I} - \mathbb{J}^2)^{-1}$ and \mathbb{J} commute, we write

$$\begin{aligned} \partial \ln \det(\mathbb{I} - \mathbb{K}_z^{(1)}|_{\frac{x}{2}, \frac{\tau}{2}}) &= \text{Tr}((\mathbb{I} - \mathbb{J}^2)^{-1} \partial \mathbb{J}) - \frac{1}{2} \text{Tr}((\mathbb{I} - \mathbb{J}^2)^{-1} (\mathbb{J}(\partial \mathbb{J}) + (\partial \mathbb{J})\mathbb{J})) \\ &= \text{Tr}((\mathbb{I} - \mathbb{J}^2)^{-1} \partial \mathbb{J}) + \frac{1}{2} \partial \ln \det(\mathbb{I} - \mathbb{J}^2). \end{aligned} \quad (8.6)$$

From Lemmas 2.2 and 7.3 we know that

$$\partial \ln \det(\mathbb{I} - \mathbb{J}^2) = \partial \ln \det(\mathbb{I} - \mathbb{K}_z) = \partial \ln \det(\mathbb{I} - \mathbb{H}) = Q_{\text{per}}(\tau, 0, x)$$

Hence, it is enough to consider

$$\text{Tr}((\mathbb{I} - \mathbb{J}^2)^{-1} \partial \mathbb{J}).$$

We use the following lemma.

Lemma 8.6. *Let \mathcal{H}_1 and \mathcal{H}_2 be two Hilbert spaces. Suppose that $\mathbb{K}_1 : \mathcal{H}_2 \rightarrow \mathcal{H}_1$, $\mathbb{K}_2 : \mathcal{H}_2 \rightarrow \mathcal{H}_1$, and $\mathbb{K}_3 : \mathcal{H}_1 \rightarrow \mathcal{H}_1$ are trace class operators. Set $\mathcal{H} = \mathcal{H}_1 \oplus \mathcal{H}_2$. We extend $\mathbb{K}_1, \mathbb{K}_2, \mathbb{K}_3$ to operators on \mathcal{H} in a natural way, and we use the same notations. Let $\mathbb{P}_1, \mathbb{P}_2 : \mathcal{H} \rightarrow \mathcal{H}$ be the projection operators to \mathcal{H}_1 and \mathcal{H}_2 , respectively. Then,*

$$\text{Tr}((\mathbb{I} - \mathbb{K}_1 \mathbb{K}_2)^{-1} \mathbb{K}_3)_{\mathcal{H}_1} = \text{Tr}((\mathbb{I} - \mathbb{P}_1 \mathbb{K}_1 \mathbb{P}_2 - \mathbb{P}_2 \mathbb{K}_2 \mathbb{P}_1)^{-1} \mathbb{P}_1 \mathbb{K}_3 \mathbb{P}_1)_{\mathcal{H}}$$

Proof. It is enough to show that the non-zero eigenvalues of both operators are the same. This is straightforward to check, we skip the details. \square

In the proof of Lemma 2.2, we set $\mathbb{W} : \ell^2(\mathcal{S}_+) \rightarrow \ell^2(\mathcal{S}_-)$ to be the reflection operator $(\mathbb{W}h)(u) = h(-u)$ and used the decomposition $\mathbb{J}^2 = \mathbb{K}_z = \mathbb{J}_1 \mathbb{J}_2$ where $\mathbb{J}_1 = \mathbb{J} \mathbb{W}$ and $\mathbb{J}_2 = \mathbb{W}^T \mathbb{J}^T = \mathbb{W}^T \mathbb{J}$, with the last equality being valid because $\gamma = 0$. Recall the definition $\mathcal{S} = \mathcal{S}_1 \cup \mathcal{S}_2$ and observe that $\ell^2(\mathcal{S}_-) \oplus \ell^2(\mathcal{S}_+) = \ell^2(\mathcal{S})$. Denoting by \mathbb{P}_\pm the projections onto \mathcal{S}_\pm , the above lemma implies that

$$\text{Tr}((\mathbb{I} - \mathbb{J}^2)^{-1} \partial \mathbb{J})_{\ell^2(\mathcal{S}_-)} = \text{Tr}((\mathbb{I} - \mathbb{P}_- \mathbb{J}_1 \mathbb{P}_+ - \mathbb{P}_+ \mathbb{J}_2 \mathbb{P}_-)^{-1} \mathbb{P}_- \partial \mathbb{J} \mathbb{P}_-)_{\ell^2(\mathcal{S})} = \text{Tr}((\mathbb{I} - \mathbb{H})^{-1} \mathbb{P}_- \partial \mathbb{J} \mathbb{P}_-)_{\ell^2(\mathcal{S})}$$

where $\mathbb{H} = \mathbb{P}_- \mathbb{J}_1 \mathbb{P}_+ + \mathbb{P}_+ \mathbb{J}_2 \mathbb{P}_-$ is the same operator as in Lemma 2.2 (with $\gamma = 0$).

Since $\Phi(s) = -\frac{1}{3}\tau s^3 + xs - Q(s)$ and recalling that $\partial = \partial_x$, we find from direct differentiation that

$$\chi_-(u) \partial \mathbf{J}(u, v) \chi_-(v) = \frac{1}{2} \chi_-(u) \frac{e^{\frac{1}{2}\Phi(u) + \frac{1}{2}\Phi(v)}}{\sqrt{-u}\sqrt{-v}} \chi_-(v) = \frac{1}{2} f_2(u) g_1(v),$$

where f_i and g_i are the components of the vectors \vec{f} and \vec{g} in Lemma 2.2. Hence,

$$\mathrm{Tr}((\mathbb{I} - \mathbb{J}^2)^{-1} \partial \mathbb{J})_{\ell^2(\mathcal{S}_-)} = \frac{1}{2} \mathrm{Tr}((\mathbb{I} - \mathbb{H})^{-1} f_2 \otimes g_1).$$

Using the notation $\vec{F} := (\mathbb{I} - \mathbb{J})^{-1} \vec{f}$, the above equation becomes

$$\mathrm{Tr}((\mathbb{I} - \mathbb{J}^2)^{-1} \partial \mathbb{J})_{\ell^2(\mathcal{S}_-)} = \frac{1}{2} \mathrm{Tr}(F_2 \otimes g_1) = \frac{1}{2} \sum_{s \in \mathcal{S}} F_2(s) g_1(s).$$

In formulas (A.1) and (A.4), we will show that $\sum_{s \in \mathcal{S}} \vec{F}(s) \vec{g}(s)^T = X_1$ is the residue matrix in (7.2). Therefore,

$$\mathrm{Tr}((\mathbb{I} - \mathbb{J}^2)^{-1} \partial \mathbb{J})_{\ell^2(\mathcal{S}_-)} = \frac{1}{2} (X_1)_{21}.$$

Recalling the notation $(X_1)_{21} = R_{\mathrm{per}}$ in (7.2) and combining with (8.6), we obtain

$$\partial_x \ln \det(\mathbb{I} - \mathbb{K}_z^{(1)}|_{\frac{x}{2}, \frac{\tau}{2}}) = \frac{1}{2} R_{\mathrm{per}}(\tau, 0, x) + \frac{1}{2} Q_{\mathrm{per}}(\tau, 0, x).$$

The coupled system of mKdV equations (1.10) and the symmetry $P_{\mathrm{per}}(\gamma) = -R_{\mathrm{per}}(-\gamma)$ in (1.12) implies that $R(\tau, x) := R_{\mathrm{per}}(\tau, 0, x)$ satisfies the mKdV equation

$$3R_\tau + R_{xxx} - 6R^2 R_x = 0.$$

On the other hand, the equation (7.4) implies that $Q(\tau, x) := Q_{\mathrm{per}}(\tau, 0, x)$ satisfies

$$Q_x = -R^2.$$

The proof of Theorem 8.4 is completed.

A Proof of Lemma 7.3

We prove the lemma. It is a fundamental property of integrable operators [18, 13] that the vector

$$\vec{F} := (\mathbb{I} - \mathbb{H})^{-1} \vec{f} \tag{A.1}$$

can be obtained from the RHP by the formula

$$\vec{F}(s) = \lim_{\xi \rightarrow s} X(\xi) \vec{f}(s) \tag{A.2}$$

where the limit converges. Now, the solution of the RHP satisfies the identity

$$X(\xi) = I - \sum_{s \in \mathcal{S}} \frac{\vec{F}(s) \vec{g}(s)^T}{s - \xi} \quad \text{for } \xi \in \mathbb{C} \setminus \mathcal{S}, \tag{A.3}$$

with $\vec{F}(s)$ given by (A.2). This equation can be seen by checking directly that the right-hand side satisfies the conditions RHP-X (a), (b), and (c) of the RHP for X , and using the uniqueness of the solution. For the

condition RHP-X (b), note that

$$\operatorname{Res}_{\xi=w} \left(I - \sum_{s \in \mathcal{S}} \frac{\vec{F}(s) \vec{g}(s)^T}{s - \xi} \right) = \vec{F}(w) \vec{g}(w)^T = \lim_{\xi \rightarrow w} X(\xi) \vec{f}(w) \vec{g}(w)^T = \lim_{\xi \rightarrow w} X(\xi) R_X(w).$$

Considering the asymptotic behavior as $\xi \rightarrow \infty$, (A.3) implies that

$$X_1 = \sum_{s \in \mathcal{S}} \vec{F}(s) \vec{g}(s)^T. \quad (\text{A.4})$$

From the formulas of \vec{f} and \vec{g} , we see that

$$\partial_x \vec{f}(u) = -\frac{u}{2} \sigma_3 \vec{f}(u) \quad \text{and} \quad \partial_x \vec{g}(u) = \frac{u}{2} \sigma_3 \vec{g}(u).$$

Thus,

$$\partial_x \mathbf{H}(u, v) = \frac{\partial_x \vec{f}(u)^T \vec{g}(v) + \vec{f}(u)^T \partial_x \vec{g}(v)}{u - v} = -\frac{1}{2} \vec{f}(u)^T \sigma_3 \vec{g}(v),$$

and using (A.1),

$$\begin{aligned} \partial_x \log \det(\mathbb{I} - \mathbb{H}) &= -\operatorname{Tr}((\mathbb{I} - \mathbb{H})^{-1} \partial_x \mathbb{H}) = \frac{1}{2} \operatorname{Tr}((\mathbb{I} - \mathbb{H})^{-1} \vec{f} \otimes (\sigma_3 \vec{g})) \\ &= \frac{1}{2} \operatorname{Tr}(\vec{F} \otimes (\sigma_3 \vec{g})) = \frac{1}{2} \sum_{s \in \mathcal{S}} \vec{F}(s)^T \sigma_3 \vec{g}(s). \end{aligned}$$

On the other hand, from (A.4),

$$\operatorname{Tr}(X_1 \sigma_3) = \sum_{s \in \mathcal{S}} \operatorname{Tr}(\vec{F}(s) \vec{g}(s)^T \sigma_3) = \sum_{s \in \mathcal{S}} \vec{g}(s)^T \sigma_3 \vec{F}(s) = \sum_{s \in \mathcal{S}} \vec{F}(s)^T \sigma_3 \vec{g}(s).$$

Equating the last two formulas, we obtain the lemma.

B Proof of Proposition 7.4

We prove Proposition 7.4 focusing only on X . The proof for Y is similar: we define $W = Y e^{-V \sigma_3/2}$ similarly as in (B.1) below and obtain the Lax equations in Lemma B.1 in the standard way for continuous Riemann-Hilbert problems. Having the Lax equations at hand, all the remaining arguments are algebraic and can be repeated for Y , line-by-line, as below, simply replacing X and X_k by Y and Y_k .

B.1 The Lax systems

Define the new matrix function

$$W(\xi) = X(\xi) e^{-\frac{V(\xi)}{2} \sigma_3}, \quad \xi \in \mathbb{C} \setminus \mathcal{S}. \quad (\text{B.1})$$

Then, W satisfies the following RHP:

RHP-W 1: $W : \mathbb{C} \setminus \mathcal{S} \rightarrow \mathbb{C}^{2 \times 2}$ is analytic.

RHP-W 2: The points in \mathcal{S} are simple poles of W with residue matrix

$$R_W(s) = e^{\frac{V(s)}{2} \sigma_3} R_X(s) e^{-\frac{V(s)}{2} \sigma_3} = \begin{pmatrix} 0 & \frac{1}{s} e^{Q(s)} \chi_+(s) \\ \frac{1}{s} e^{-Q(s)} \chi_-(s) & 0 \end{pmatrix} \quad \text{for } s \in \mathcal{S}.$$

RHP-W 3: As $\xi \rightarrow \infty$,

$$W(\xi) = (I + \mathcal{O}(\xi^{-1}))e^{-\frac{V(\xi)}{2}\sigma_3}.$$

The jump matrix does not depend on the parameters τ, γ, x . This has the following consequence.

Lemma B.1 (Lax equations). *The matrix W satisfies linear differential equations*

$$\partial_\gamma W(\xi) = A(\xi)W(\xi), \quad \partial_\tau W(\xi) = B(\xi)W(\xi), \quad \partial_x W(\xi) = D(\xi)W(\xi), \quad (\text{B.2})$$

for some polynomial matrices

$$A(\xi) = \xi^2 A_2 + \xi A_1 + A_0, \quad B(\xi) = \xi^3 B_3 + \xi^2 B_2 + \xi B_1 + B_0, \quad D(\xi) = \xi D_1 + D_0$$

where $A_2 = -\frac{1}{4}\sigma_3$, $B_3 = \frac{1}{6}\sigma_3$, and $D_1 = -\frac{1}{2}\sigma_3$, and other matrices A_i, B_i, D_i do not depend on ξ .

Proof. Since $\det X \equiv 1$, $\det W \equiv 1$. Hence, W is invertible. Let ∂ be the partial derivative with respect either τ, γ or x . For $s \in \mathcal{S}$, Lemma 7.1 implies that

$$Z(\xi) := W(\xi) \left(-\frac{R_W(s)}{\xi - s} + I \right)$$

is analytic at $\xi = s$. Since $R_W(s)^2 = 0$, we have $\det Z(\xi) = 1$, and hence $Z(\xi)^{-1}$ is also analytic at $\xi = s$. Since R_W does not depend on the parameters, the derivative becomes

$$\partial Z(\xi) = \partial W(\xi) \left(-\frac{R_W}{\xi - s} + I \right).$$

Hence,

$$(\partial W(\xi))W(\xi)^{-1} = \partial W(\xi) \left(-\frac{R_W}{\xi - s} + I \right) \left(\frac{R_W}{\xi - s} + I \right) W(\xi)^{-1} = (\partial Z(\xi))Z(\xi)^{-1}$$

is analytic at $\xi = s$. Thus, $(\partial W(\xi))W(\xi)^{-1}$ is an entire function.

The asymptotic condition, RHP-W 3, implies that

$$(\partial W(\xi))W(\xi)^{-1} = \mathcal{O}(\xi^{-1}) - \frac{\partial V(\xi)}{2}(I + \mathcal{O}(\xi^{-1}))\sigma_3(I + \mathcal{O}(\xi^{-1}))$$

as $\xi \rightarrow \infty$. Since

$$\partial_\gamma V(\xi) = \frac{\xi^2}{2}, \quad \partial_\tau V(\xi) = -\frac{\xi^3}{3}, \quad \partial_x V(\xi) = \xi,$$

the Liouville's theorem implies that $(\partial W(\xi))W(\xi)^{-1}$ is a polynomial with the leading term $-\frac{\partial V(\xi)}{2}\sigma_3$. We thus obtain the result. \square

We now insert (B.1) and the asymptotic series condition (7.1) into the equations (B.2) to obtain sequences of relationships between A_i, B_i, D_i and X_k . We find that

$$\begin{aligned} 4A_1 &= -6B_2 = 2D_0 = [\sigma_3, X_1] =: C_1, \\ 4A_0 &= -6B_1 = -[\sigma_3, X_1]X_1 + [\sigma_3, X_2] =: C_2, \\ -6B_0 &= [\sigma_3, X_1]X_1^2 - [\sigma_3, X_2]X_1 - [\sigma_3, X_1]X_2 + [\sigma_3, X_3] =: C_3 \end{aligned}$$

and for $k \geq 1$,

$$4\partial_\gamma X_k = -[\sigma_3, X_{k+2}] + C_1 X_{k+1} + C_2 X_k, \quad (\text{B.3})$$

$$-6\partial_\tau X_k = -[\sigma_3, X_{k+3}] + C_1 X_{k+2} + C_2 X_{k+1} + C_3 X_k, \quad (\text{B.4})$$

$$2\partial_x X_k = -[\sigma_3, X_{k+1}] + C_1 X_k \quad (\text{B.5})$$

where the bracket denotes the commutator $[P, Q] = PQ - QP$.

Using (B.5) when $k = 1, 2$, we may remove the commutator terms in C_2 and C_3 and express them as

$$-\frac{1}{2}C_2 = \partial_x X_1 \quad \text{and} \quad -\frac{1}{2}C_3 = (\partial_x X_1)X_1 + \partial_x X_2. \quad (\text{B.6})$$

Recall the notation (7.2). The diagonal entries of the equation (B.5) with $k = 1$ gives us the identity

$$q_x = pr. \quad (\text{B.7})$$

This proves (7.4) of Proposition 7.4.

B.2 Coupled nonlinear heat equations

We find a partial differential equation for X_1 in the variables x and γ and prove (7.5) of Proposition 7.4.

The $k = 1$ case of equation (B.3) becomes, using (B.6) for C_2 ,

$$4\partial_\gamma X_1 = -2(\partial_x X_1)X_1 + [\sigma_3, X_1]X_2 - [\sigma_3, X_3].$$

We remove $[\sigma_3, X_3]$ using the $k = 2$ case of the equation (B.5). The equation becomes

$$2\partial_\gamma X_1 = -(\partial_x X_1)X_1 + \partial_x X_2. \quad (\text{B.8})$$

This equation contains X_2 which we remove as follows. The x -derivative of the $k = 1$ case of (B.5) is

$$[\sigma_3, \partial_x X_2] = -2\partial_{xx} X_1 + \partial_x([\sigma_3, X_1]X_1).$$

We solve for $\partial_x X_2$ in (B.8) and insert it to the above equation and arrive at an equation involving only X_1 . Using the general commutator identity $[A, BC] = [A, B]C + B[A, C]$, the equation can be written as

$$2[\sigma_3, \partial_\gamma X_1] = -2\partial_{xx} X_1 + [\sigma_3, X_1](\partial_x X_1) - (\partial_x X_1)[\sigma_3, X_1]. \quad (\text{B.9})$$

We insert the entries q, p, r of X_1 in (7.2) into (B.9). The diagonal entries simply give the x -derivative of (B.7). The off-diagonal entries give two non-trivial equations, which after inserting $q_x = pr$ become (7.5) of Proposition 7.4.

B.3 Coupled mKdV equations

We find a partial differential equation for X_1 in the variables x and τ and prove (7.6) of Proposition 7.4. In this section, we set

$$Q := [\sigma_3, X_1] \quad \text{and} \quad R := [\sigma_3, X_2] = -2\partial_x X_1 + QX_1.$$

where the second equality in R follows from the $k = 1$ case of (B.5). Consider the $k = 1$ case of (B.4). The equation contains $[\sigma_3, X_4]$. We remove it using the $k = 3$ case of (B.5). Further inserting the formula (B.6),

the $k = 1$ case of (B.4) becomes

$$\partial_x X_3 = (\partial_x X_1)X_2 + (\partial_x X_2)X_1 - (\partial_x X_1)X_1^2 - 3\partial_\tau X_1.$$

The $k = 2$ case of (B.5) is

$$[\sigma_3, X_3] = -2\partial_x X_2 + QX_2. \quad (\text{B.10})$$

Taking the x -derivative of this equation, and then inserting the formula of $\partial_x X_3$ above, we find

$$[\sigma_3, (\partial_x X_1)X_2 + (\partial_x X_2)X_1] - [\sigma_3, (\partial_x X_1)X_1^2] - 3\partial_\tau Q = -2\partial_{xx} X_2 + \partial_x(QX_2).$$

We use the general commutator identity $[A, BC] = [A, B]C + B[A, C]$ for the first term on the left-hand side and move the term $\partial_x(QX_2)$ to the left-hand side of the equation. Since $\text{Tr } X_1 = 0$, the matrix X_1^2 is diagonal, and hence $[\sigma_3, X_1^2] = 0$, implying that $[\sigma_3, (\partial_x X_1)X_1^2] = [\sigma_3, \partial_x X_1]X_1^2 = (\partial_x Q)X_1^2$. Hence, recalling the notations Q and R , the above equation can be written as

$$(\partial_x X_1)R + (\partial_x R)X_1 + (\partial_x X_2)Q - Q(\partial_x X_2) - (\partial_x Q)X_1^2 - 3\partial_\tau Q = -2\partial_{xx} X_2.$$

Taking the commutator with σ_3 ,

$$[\sigma_3, (\partial_x X_1)R + (\partial_x R)X_1] + [\sigma_3, (\partial_x X_2)Q - Q(\partial_x X_2)] - [\sigma_3, (\partial_x Q)X_1^2] - 3[\sigma_3, \partial_\tau Q] = -2\partial_{xx} R. \quad (\text{B.11})$$

We express $[\sigma_3, (\partial_x X_2)Q - Q(\partial_x X_2)]$ in terms of Q and R using the next lemma.

Lemma B.2. *We have*

$$2[\sigma_3, (\partial_x X_2)Q] = -QRQ \quad \text{and} \quad 2[\sigma_3, Q(\partial_x X_2)] = Q^2 R.$$

Proof. The equation (B.10) gives $2\partial_x X_2 = QX_2 - [\sigma_3, X_3]$. Observe that since $[\sigma_3, X_3]$ and $Q = [\sigma_3, X_1]$ have zero diagonal entries, $[\sigma_3, X_3]Q$ is a diagonal matrix, and hence $[\sigma_3, [\sigma_3, X_3]Q] = 0$. Similarly we have $[\sigma_3, Q[\sigma_3, X_3]] = 0$. Therefore,

$$2[\sigma_3, (\partial_x X_2)Q] = [\sigma_3, QX_2Q - [\sigma_3, X_3]Q] = [\sigma_3, QX_2Q]$$

and

$$2[\sigma_3, Q(\partial_x X_2)] = [\sigma_3, Q^2 X_2 - Q[\sigma_3, X_3]] = [\sigma_3, Q^2 X_2].$$

Now, since $Q = [\sigma_3, X_1]$, we have $\sigma_3 Q + Q\sigma_3 = 0$. Using this identity, we can write

$$[\sigma_3, QX_2Q] = -Q[\sigma_3, X_2]Q = -QRQ \quad \text{and} \quad [\sigma_3, Q^2 X_2] = Q^2[\sigma_3, X_2] = Q^2 R.$$

□

The equation (B.11) thus becomes an equation only of X_1 :

$$2[\sigma_3, (\partial_x X_1)R + (\partial_x R)X_1] - Q(RQ + QR) - 2[\sigma_3, (\partial_x Q)X_1^2] - 6[\sigma_3, \partial_\tau Q] = -4\partial_{xx} R. \quad (\text{B.12})$$

We now insert the entries (7.2) of X_1 . The entries are

$$X_1 = \begin{bmatrix} q & p \\ r & -q \end{bmatrix} \quad \text{and} \quad Q = \begin{bmatrix} 0 & 2p \\ -2r & 0 \end{bmatrix} \quad \text{and} \quad R = \begin{bmatrix} 0 & -2p_x - 2pq \\ -2r_x - 2rq & 0 \end{bmatrix}$$

where we used (B.7) for the diagonal entries of R . It is useful to observe that

$$RQ + QR = -4(r_x p - p_x r)I \quad \text{and} \quad X_1^2 = (q^2 + pr)I.$$

Inserting these into (B.12), the diagonal entries of the equation give trivial identities. The off-diagonal entries, on the other hand, imply, using $q_x = pr$, (7.6) of Proposition 7.4.

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